

AKD4627-A

Evaluation board Rev.0 for AK4627

GENERAL DESCRIPTION

The AKD4627-A is an evaluation board for the AK4627, a single chip CODEC that includes four channels of ADC and six channels of DAC. The AKD4627-A also has the digital audio interface and can achieve the interface with digital audio systems via opt-contractor or BNC connector.

■ Ordering guide

AKD4627-A --- AK4627 Evaluation Board
 (Cable for connecting with printer port of IBM-AT compatible PC and control software are packed with this.) This control software can't operate on Windows NT.

FUNCTION

- On-board analog output buffer circuit
- Compatible with 2 types of interface
 - AK4118 (DIT&DIR) with optical output/input and BNC output/input
 - Direct interface with AC3 decoder by 10pin header
- 10pin header for serial control interface

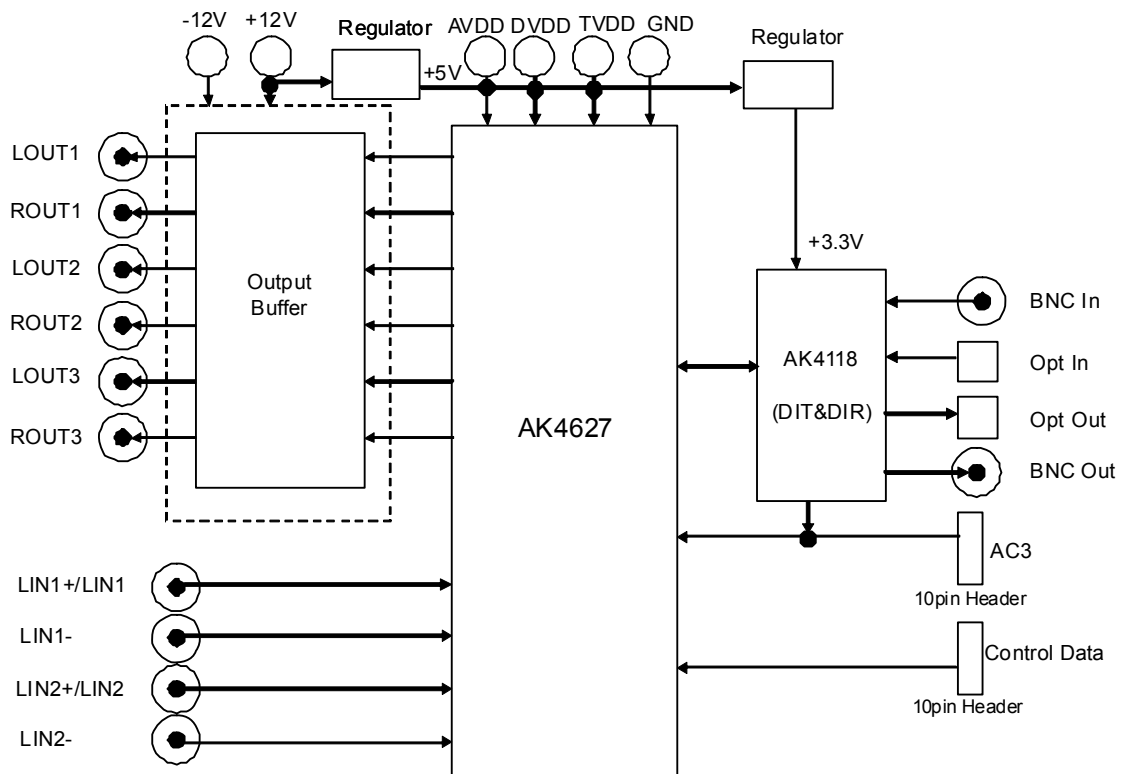


Figure 1 AKD4627-A Block Diagram

*Circuit diagram and PCB layout are attached at the end of this manual.

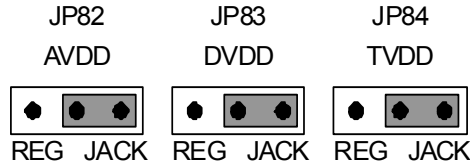
Evaluation Board Manual

■ Operation sequence

1) Set up the power supply lines.

(1-1) In case of using separate power supply lines <Default>

Set up the jumper pins.



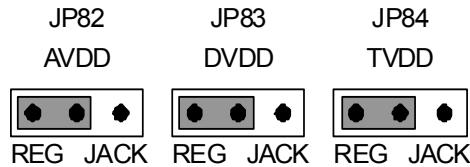
Set up the power supply lines.

Name	Color	Voltage	Comments	Attention
+12V	Red	+12V	Regulator, Power Supply for Op-amp	Should be connected.
-12V	Red	-12V	Power Supply for Op-amp	Should be connected.
AVDD	Orange	+5V	Power supply for AVDD of the AK4627	Should be connected.
DVDD	Orange	+5V	Power supply for DVDD of the AK4627	Should be connected.
TVDD	Orange	+5V	Power supply for TVDD of the AK4627	Should be connected.
AGND	Black	0V	Analog ground	Should be connected.
DGND	Black	0V	Digital ground	Should be connected.

Table 1 Set up of power supply lines

(1-2) In case of using the regulator

Set up the jumper pins.



Set up the power supply lines.

Name	Color	Voltage	Comments	Attention
+12V	Red	+12V	Regulator, Power Supply for Op-amp	Should be connected.
-12V	Red	-12V	Power Supply for Op-amp	Should be connected.
AVDD	Orange	+5V	Power supply for AVDD of the AK4627	Should be open.
DVDD	Orange	+5V	Power supply for DVDD of the AK4627	Should be open.
TVDD	Orange	+5V	Power supply for TVDD of the AK4627	Should be open.
AGND	Black	0V	Analog ground	Should be connected.
DGND	Black	0V	Digital ground	Should be connected.

Table 2 Set up of power supply lines

2) Set up the evaluation mode, jumper pins. (See the followings)

3) Power on.

The AK4627 and AK4118 should be reset once bringing SW1 "L" upon power-up.

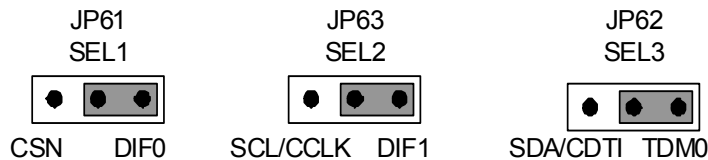
■ Control mode

(1) Parallel control mode <Default>

(1-1) Set up Parallel/Serial select pin

Set up SW2-7 (PS) to “H”. (See Table 3)

(1-2) Set up the jumper pins

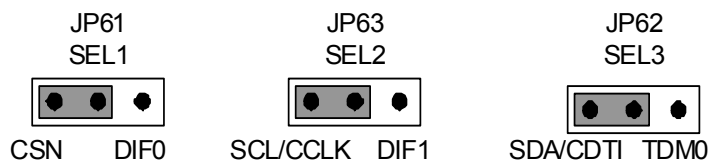


(2) Serial control mode

(1-1) Set up Parallel/Serial select pin

Set up SW2-7 (PS) to “L”. (See Table 3)

(1-2) Set up the jumper pins



■ Audio I/F evaluation mode

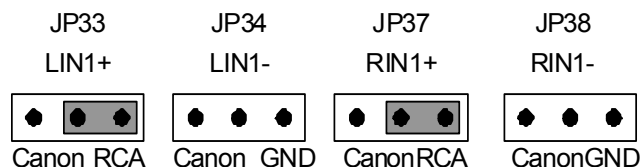
(1) Evaluation of ADC using DIT of AK4118

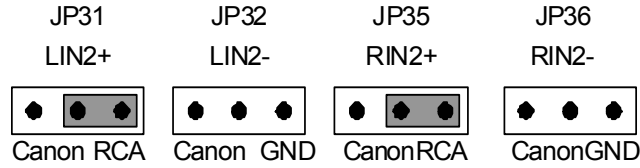
(1-1) Set up analog inputs

(1-1-1) Evaluation of ADC using DIT of AK4118 when single-ended inputs

PORT2 (DIT) or J2 (BNC_TX) is used. Nothing should be connected to PORT4 (AC3).
Set up SW2-2 (SGL) to H (See Table 3).

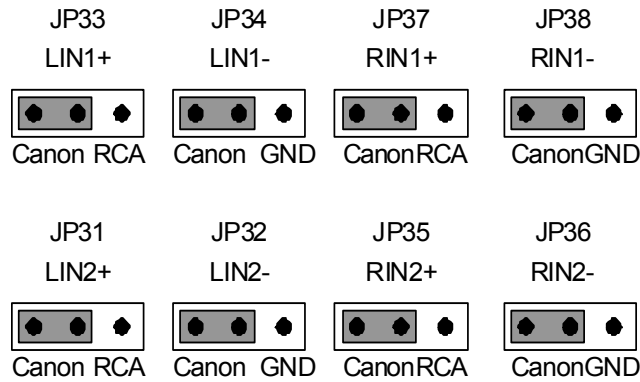
Set up the jumper pins.





(1-1-2) Evaluation of ADC using DIT of AK4118 when differential inputs <Default>
 PORT2 (DIT) or J2 (BNC_TX) is used. Nothing should be connected to PORT4 (AC3).
 Set up SW2-2 (SGL) to L (See Table 3).

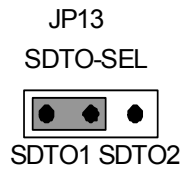
Set up the jumper pins.



(1-2) Set up the digital output

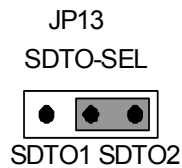
(1-2-1) In case of selecting SDTO1 <Default>

Set up the jumper pin.



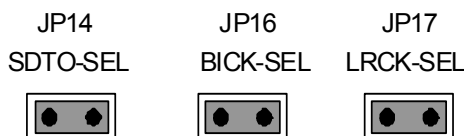
(1-2-2) In case of selecting SDTO2

Set up the jumper pin.



(1-3) Set up the audio interface.

Set up the jumper pins.

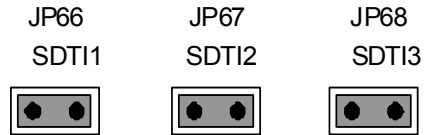


(2) Evaluation of DAC using DIR of AK4118 <Default>

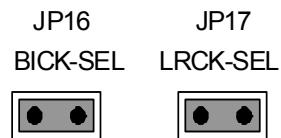
J1 (BNC_RX) or PORT1 (DIR) is used. Nothing should be connected to PORT4 (AC3).

(2-1) Set up the digital inputs

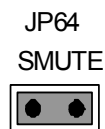
Set up the jumper pins.

**(2-2) Set up the audio interface**

Set up the jumper pins.

**(2-3) Set up the SMUTE pin**

Set up the jumper pin.



When JP64 (SMUTE) is open, soft mute cycle is initialized.
When JP64 (SMUTE) is short, the output mute releases.

■ DIP Switch set up

[SW2] (MODE1): Mode settings for AK4627.

About the TDM mode of AK4627, please refer to Page 18 of AK4627's datasheet.

No.	Name	“H”	“L”	Default
1	TDM0	TDM Mode	Normal Mode	L
2	SGL	ADC Single-ended Input Mode	ADC Differential Input Mode	L
3	I2C	I2C Bus	3-wire Serial	L
4	DFS0	Double Speed	Normal Speed	L
5	DZFE	Zero Input Detect. Refer to the datasheet P23 of the AK4627.		L
6	PS	Parallel Control mode	Serial Control mode	H
7	CAD1	Chip Address Select. Refer to Table 9		L
8	CAD0			L

Table 3 Mode Setting for AK4627

[SW3] (AK4118 Mode_setting): Mode setting for AK4118.

No.	Name	“H”	“L”	Default
1	DIF2	AK4118's Audio Data Format Settings, and AK4627's Audio Data Format Settings when Parallel Control Mode. See Table 5 and Table 6		H
2	DIF1			L
3	DIF0			L
4	OCKS1	AK4118's Master Clock Settings. See Table 7		H
5	OCKS0			L
6	CM1	AK4118's Clock Operation Mode Select. See Table 8		L
7	CM0			L

Table 4 Mode Setting for AK4118

AK4118's audio data format and AK4627's audio data format are set up at the same time by settings of SW3-1 (DIF2), SW3-2 (DIF1) and SW3-3 (DIF0) when AK4627 is on Parallel Control Mode.

SW3-1 DIF2	SW3-2 DIF1	SW3-3 DIF0	AK4627 DIF1	AK4627 DIF0	AK4118 DAUX	AK4118 SDTO	LRCK		BICK	
0	1	0	0	0	24bit, Left justified	20bit, Right justified	H/L	O	64fs	O
0	1	1	0	1	24bit, Left justified	24bit, Right justified	H/L	O	64fs	O
1	0	0	1	0	24bit, Left justified	24bit, Left justified	H/L	O	64fs	O
1	0	1	1	1	24bit, I ² S	24bit, I ² S	L/H	O	64fs	O

Table 5 AK4118's Audio Data Format (Parallel control mode)

It is necessary to set DIF1-0 bits of AK4627's registers and SW3-1 (DIF2), SW3-2 (DIF1), SW3-3 (DIF0) to the same audio data format when AK4627 is on Serial Control Mode.

Mode	DIF1	DIF0	SDTO1-2	SDTI1-3
0	0	0	24bit, Left justified	20bit, Right justified
1	0	1	24bit, Left justified	24bit, Right justified
2	1	0	24bit, Left justified	24bit, Left justified
3	1	1	24bit, I ² S	24bit, I ² S

Table 6 AK4627's Audio data formats (Serial control mode)

AK4118 supplies AK4627's Master Clock with MCKO1.

No.	OCKS1	OCKS0	MCKO1	MCKO2	X'tal	fs (max)
0	0	0	256fs	256fs	256fs	96 kHz
1	0	1	256fs	128fs	256fs	96 kHz
2	1	0	512fs	256fs	512fs	48 kHz
3	1	1	128fs	64fs	128fs	192 kHz

(default)

Table 7 AK4118's Master Clock Frequency Select (Stereo mode)

Mode	CM1	CM0	PLL	X'tal	Clock source	SDTO
0	0	0	ON	ON	PLL	RX
1	0	1	OFF	ON	X'tal	DAUX
2	1	0	ON	ON	PLL	RX
			ON	ON	X'tal	DAUX
3	1	1	ON	ON	X'tal	DAUX

(default)

ON: Oscillation (Power-up), OFF: STOP (Power-Down)

Table 8 AK4118's Clock Operation Mode select

■ Other jumper pins set up

- JP81 (GND) : Connection between AGND and DGND.
 OPEN : AGND and DGND are separated on the board.
 SHORT : AGND and DGND are connected on the board. <Default>
- JP11 (RX3) : Digital input connector selection for AK4118.
 OPT : Optical connector (PORT1) is used, except when Quad Speed Mode for DAC evaluation.
 BNC : BNC Jack (J1) is used. <Default>
- JP12 (TX) : Digital output connector selection for AK4118.
 OPT : Optical connector (PORT2) is used.
 BNC : BNC Jack (J2) is used. <Default>
- JP15 (MCLK_SEL): This jumper pin is fixed to SHORT. <Default>
- JP65 (SDTI4) : This jumper pin is not used. <Default>

■ The function of the toggle SW

[SW1] (PDN): Power down of AK4627. Keep "H" during normal operation.

■ The indication content for LED

- [LE1] Monitor DZF1 pin of the AK4627.
 [LE2] Monitor DZF2 pin of the AK4627.

About zero detection of AK4627, please refer to Page 23 of AK4627's datasheet.

■ Serial Control

The AK4627 can be controlled via the printer port (parallel port) of IBM-AT compatible PC. Connect PORT3 (CTRL) with PC by 10 wire flat cable packed with the AKD4627-A.

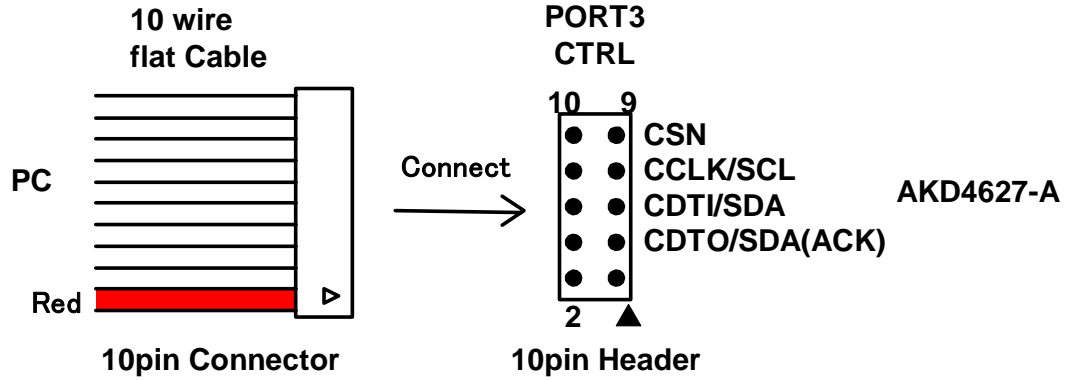


Figure 2 Connect of 10 wire flat cable

The AK4627 supports 3-wire serial control mode and I2C-bus control mode (fast-mode, max : 400kHz). Please set the jump pins: JP61 (SEL1), JP63 (SEL2) and JP62 (SEL3), referred to (2) Serial Control Mode.

Mode	Chip Address	SW2-7 (CAD1)	SW2-8 (CAD0)	R/W
3-wire	00	0	0	Write only (default)
	01	0	1	Write only
	10	1	0	Write only
	11	1	1	Write only
I2C	00	0	0	R/W
	01	0	1	R/W
	10	1	0	R/W
	11	1	1	R/W

Table 9 Select Interface and Chip Address

■ Analog Input/Output Circuits

1. Analog Input Circuits

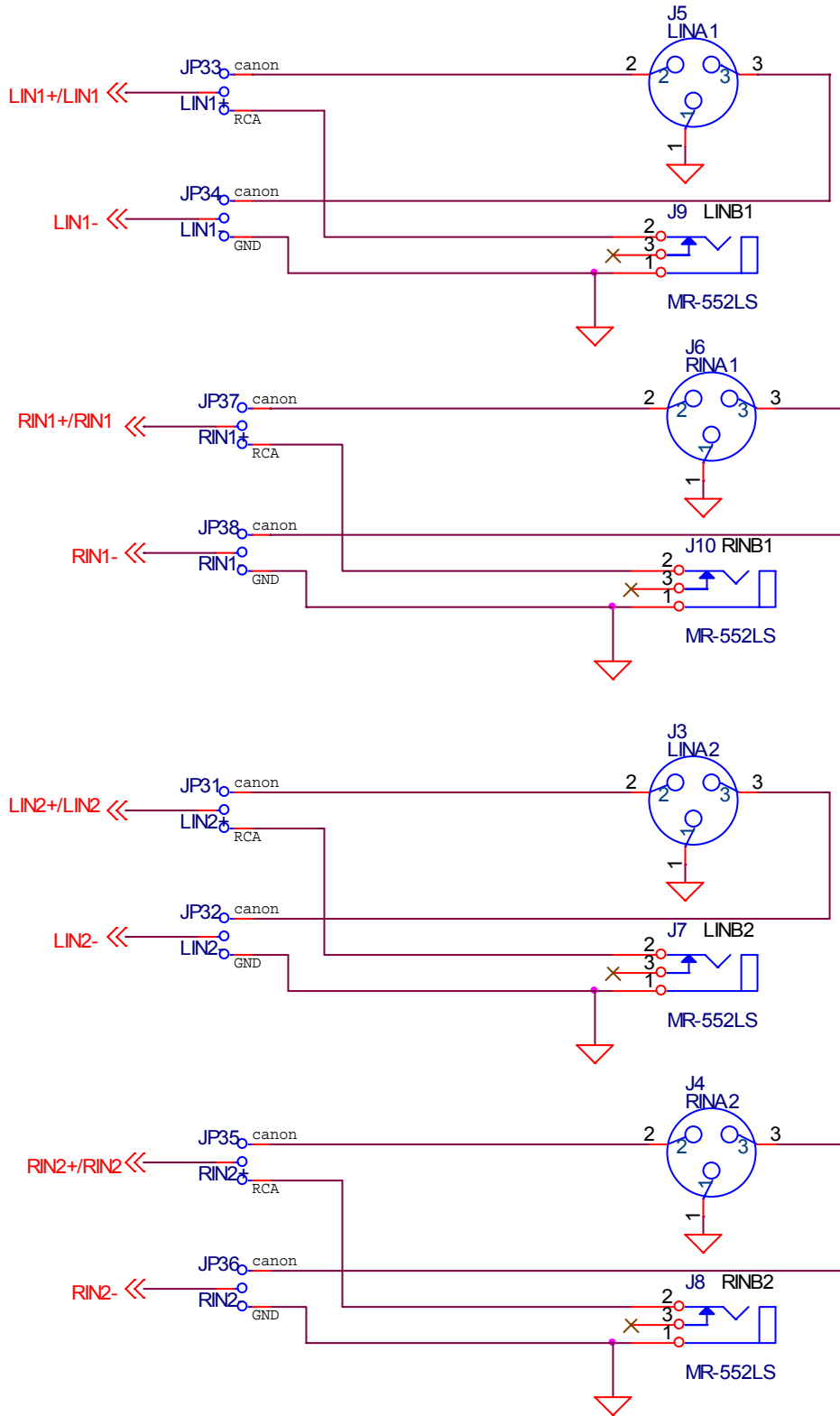


Figure 3 AKD4627-A Analog Input Circuits

2. Analog Output Circuits

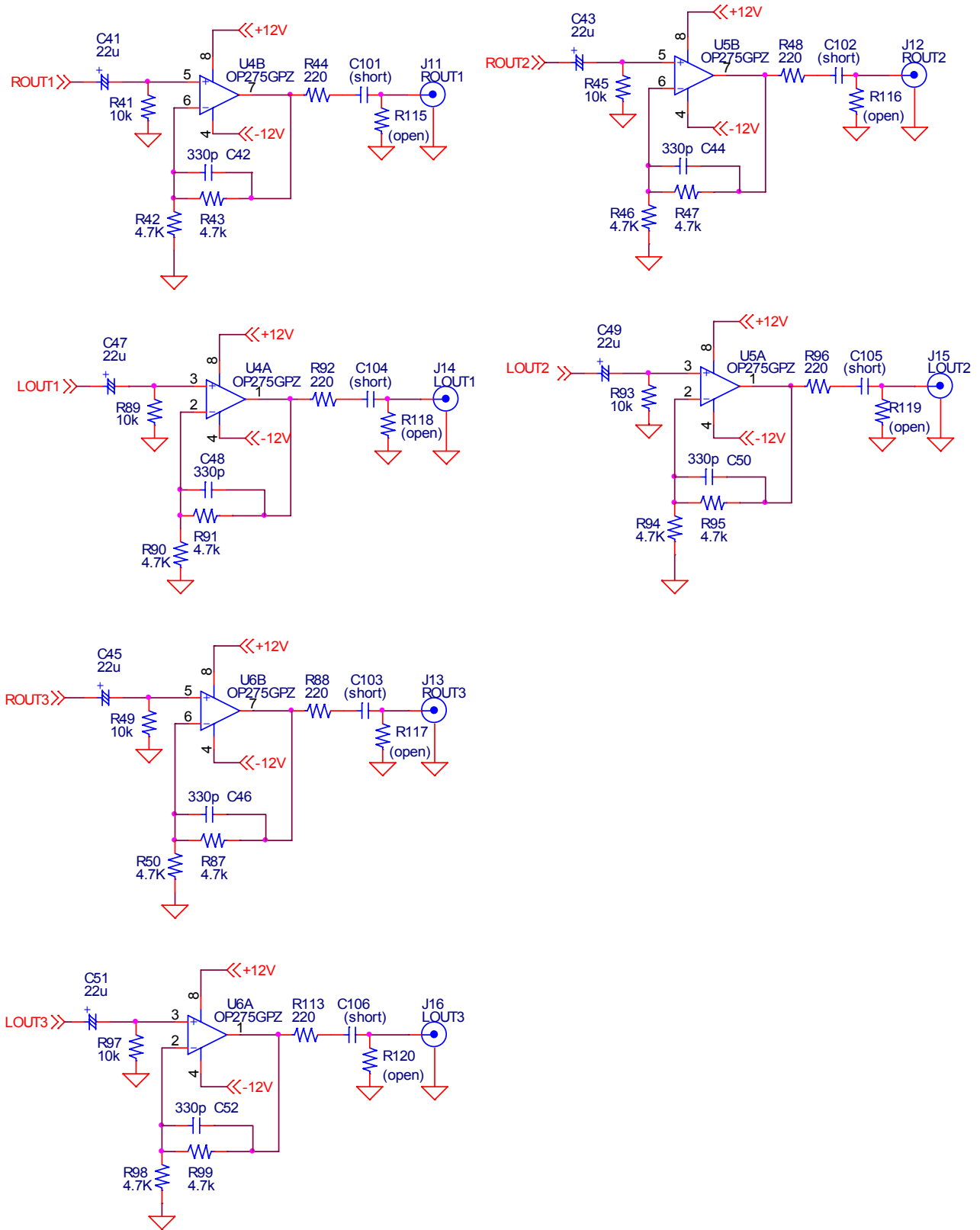


Figure 4 AKD4627-A Analog Output Circuits

Control Soft Manual

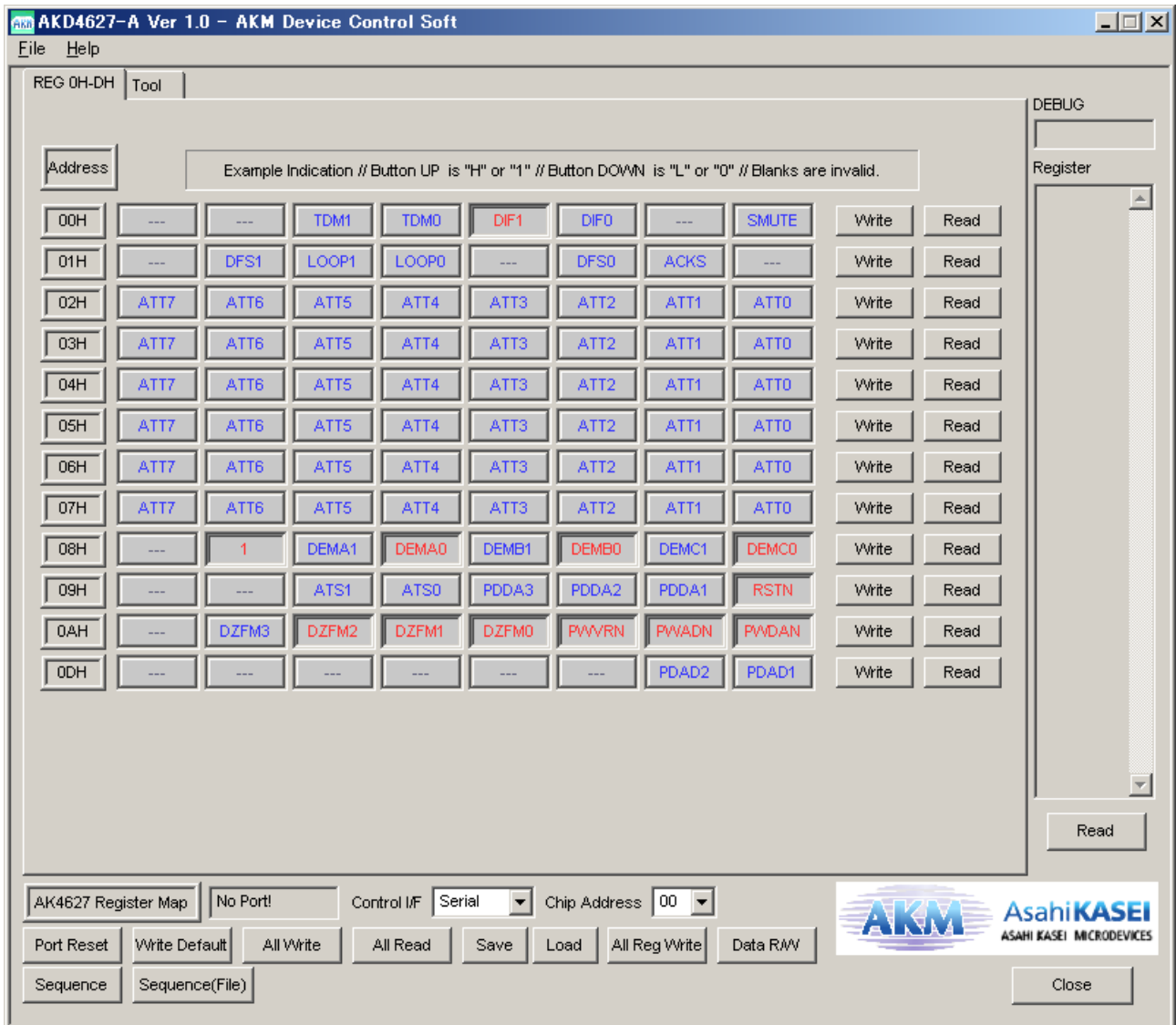
■ Evaluation Board and Control Soft Settings

1. Set an evaluation board properly.
2. Connect the evaluation board to an IBM PC/AT compatible PC by a 10 wire flat cable. Be aware of the direction of the 10pin header. When running this control soft on the Windows 2000/XP, the driver which is included in the CD must be installed. Refer to the “Driver Control Install Manual for AKM Device Control Software” for installing the driver. When running this control soft on the windows 95/98/ME, driver installing is not necessary. This control soft does not support the Windows NT.
3. Continue the evaluation by following the process below.

■ Operation Screen

1. Start up the control program following the process above.

The operation screen is shown below.



■ Operation Overview

Register map and testing tool can be controlled by this control soft. These controls are selected by upper tabs.

Buttons which are frequently used such as register initializing button “Write Default”, are located outside of the switching tab window. Refer to the “Dialog Boxes” for details of each dialog box setting.

1. [Port Reset]: For when connecting to USB I/F board (AKDUSBIF-A)
Click this button after the control soft starts up when connecting USB I/F board (AKDUSBIF-A).
2. [Write Default]: Register Initializing
When the device is reset by a hardware reset, use this button to initialize the registers.
3. [All Write]: Executing write commands for all registers displayed.
4. [All Read]: Executing read commands for all registers displayed.
5. [Save]: Saving current register settings to a file.
6. [Load]: Executing data write from a saved file.
7. [All Reg Write]: “All Reg Write” dialog box is popped up.
8. [Data R/W]: “Data R/W” dialog box is popped up.
9. [Sequence]: “Sequence” dialog box is popped up.
10. [Sequence(File)]: “Sequence(File)” dialog box is popped up.
11. [Read]: Reading current register settings and display on to the Register area (on the right of the main window).
This is different from [All Read] button, it does not reflect to a register map, only displaying hexadecimal.

1. [REG]: Register Map

This tab is for a register writing and reading.

Each bit on the register map is a push-button switch.

Button Down indicates “H” or “1” and the bit name is in red (when read only it is in deep red).

Button Up indicates “L” or “0” and the bit name is in blue (when read only it is in gray)

The registers which is not defined in the datasheet are indicated as “---”.

REG 0H-DH Tool

Address

Example Indication // Button UP is "H" or "1" // Button DOWN is "L" or "0" // Blanks are invalid.

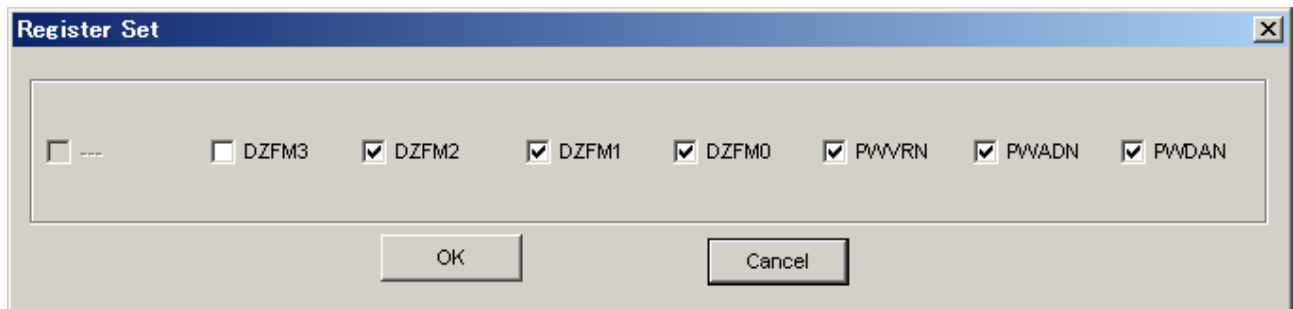
00H	---	---	TDM1	TDM0	DIF1	DIF0	---	SMUTE	Write	Read
01H	---	DFS1	LOOP1	LOOP0	---	DFS0	ACKS	---	Write	Read
02H	ATT7	ATT6	ATT5	ATT4	ATT3	ATT2	ATT1	ATT0	Write	Read
03H	ATT7	ATT6	ATT5	ATT4	ATT3	ATT2	ATT1	ATT0	Write	Read
04H	ATT7	ATT6	ATT5	ATT4	ATT3	ATT2	ATT1	ATT0	Write	Read
05H	ATT7	ATT6	ATT5	ATT4	ATT3	ATT2	ATT1	ATT0	Write	Read
06H	ATT7	ATT6	ATT5	ATT4	ATT3	ATT2	ATT1	ATT0	Write	Read
07H	ATT7	ATT6	ATT5	ATT4	ATT3	ATT2	ATT1	ATT0	Write	Read
08H	---	1	DEMA1	DEMA0	DEMB1	DEMB0	DEMC1	DEMC0	Write	Read
09H	---	---	ATS1	ATS0	PDDA3	PDDA2	PDDA1	RSTN	Write	Read
0AH	---	DZFM3	DZFM2	DZFM1	DZFM0	PWVRN	PWADN	PVDAN	Write	Read
0DH	---	---	---	---	---	---	PDAD2	PDAD1	Write	Read

[Write]: Data Writing Dialog

It is for when changing two or more bits on the same address at the same time.

Click [Write] button located on the right of the each corresponded address for a pop-up dialog box.

When checking the checkbox, the register will be “H” or “1”, when not checking the register will be “L” or “0”.
Click [OK] to write setting value to the registers, or click [Cancel] to cancel this setting.

**[Read]: Data Read**

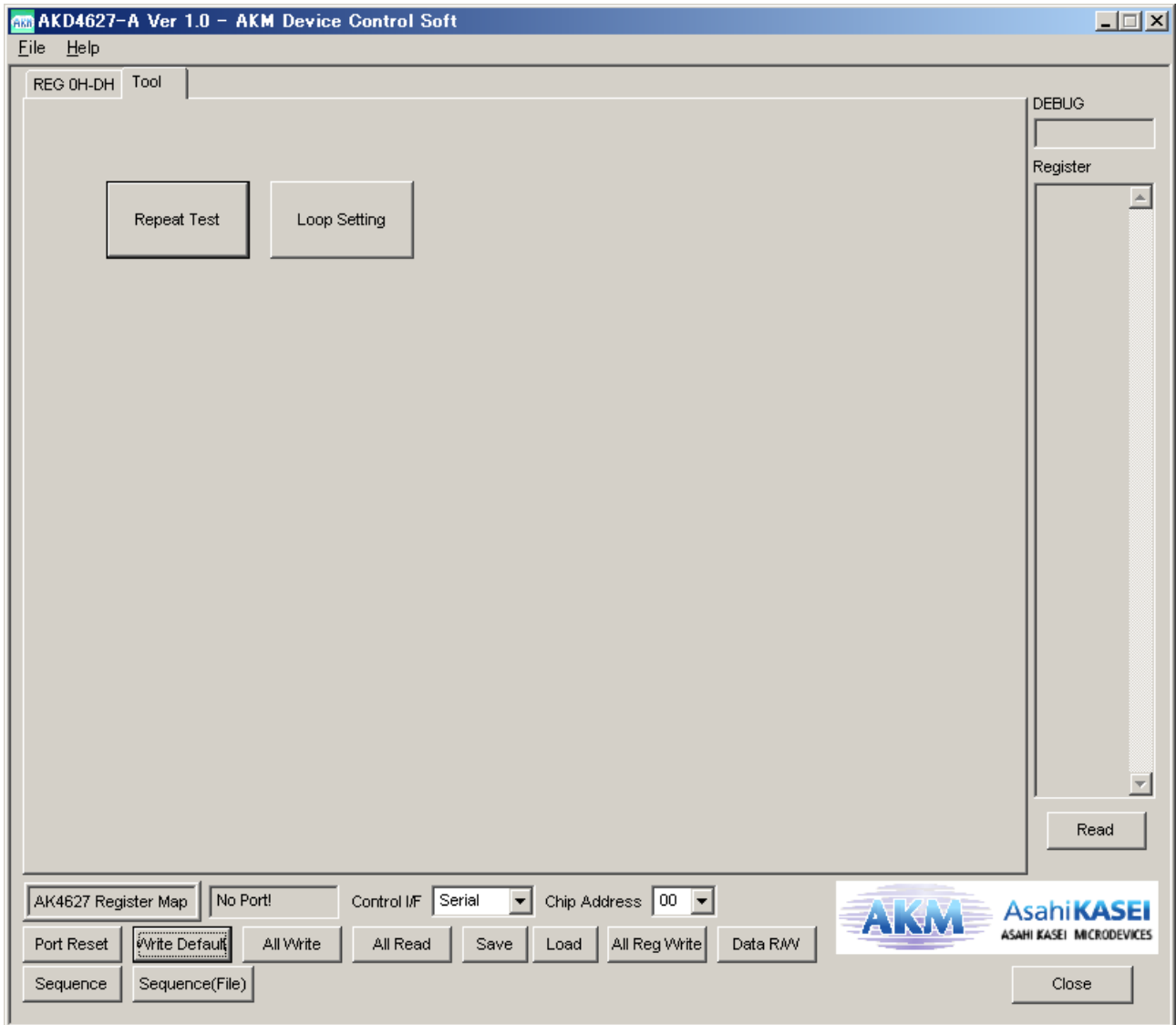
Click [Read] button located on the right of the each corresponded address to execute register reading.

After register reading, the display will be updated regarding to the register status.
Button Down indicates “H” or “1” and the bit name is in red (when read only it is in deep red).
Button Up indicates “L” or “0” and the bit name is in blue (when read only it is in gray)

Please be aware that button statuses will be changed by Read command.

2. [Tool]: Testing Tools

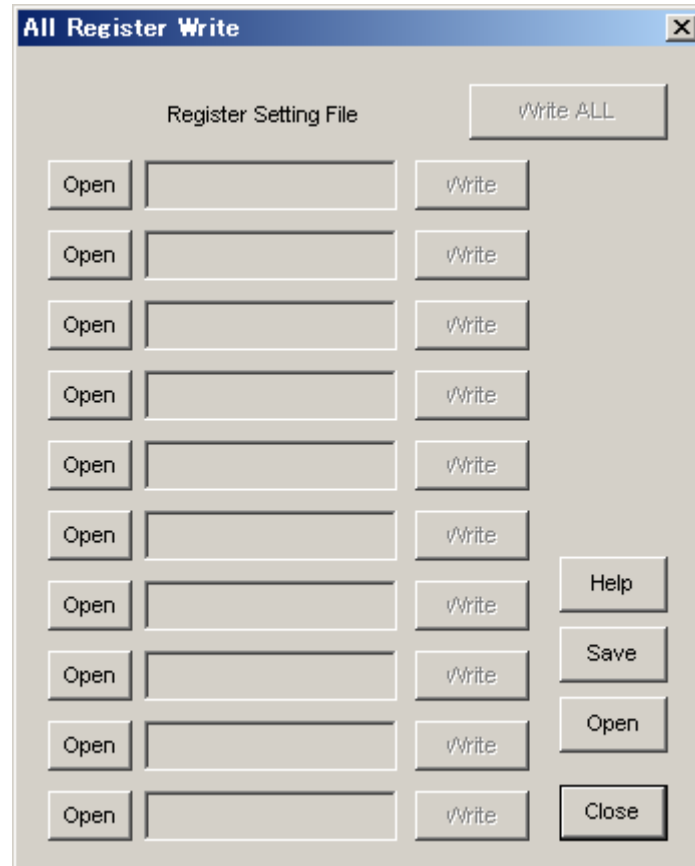
This tab screen is for evaluation testing tool.
Click buttons for each testing tool.



■ Dialog Boxes

1. [All Reg Write]: All Register Write dialog box

Click [All Reg Write] button in the main window to open register setting files.
Register setting files saved by [SAVE] button can be applied.



[Open (left)]: Selecting a register setting file (*.akr).

[Write]: Executing register writing.

[Write All]: Executing all register writings.

Writings are executed in descending order.

[Help]: Help window is popped up.

[Save]: Saving the register setting file assignment. The file name is “*.mar”.

[Open (right)]: Opening a saved register setting file assignment “*. mar”.

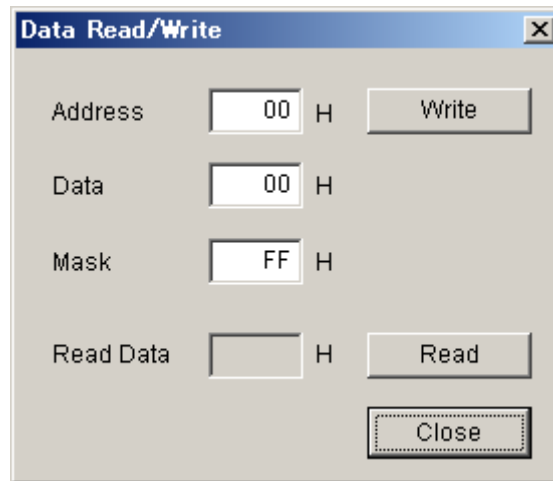
[Close]: Closing the dialog box and finish the process.

*Operating Suggestions

- (1) Those files saved by [Save] button and opened by [Open] button on the right of the dialog “*.mar” should be stored in the same folder.
- (2) When register settings are changed by [Save] button in the main window, re-read the file to reflect new register settings.

2. [Data R/W]: Data R/W Dialog Box

Click the [Data R/W] button in the main window for data read/write dialog box.
Data write is available to specified address.



Address Box: Input data address in hexadecimal numbers for data writing.

Data Box: Input data in hexadecimal numbers.

Mask Box: Input mask data in hexadecimal numbers.

This is “AND” processed input data.

[Write]: Writing to the address specified by “Address” box.

[Read]: Reading from the address specified by “Address” box.

The result will be shown in the Read Data Box in hexadecimal numbers.

[Close]: Closing the dialog box and finish the process.

Data writing can be cancelled by this button instead of [Write] button.

*The register map will be updated after executing [Write] or [Read] commands.

3. [Sequence]: Sequence Dialog Box

Click [Sequence] button to open register sequence setting dialog box.
Register sequence can be set in this dialog box.

	Address		Data		Mask		Interval		Select		Address		Data		Mask		Interval		Select
1	00	H	00	H	FF	H	0	ms	No_use	16	00	H	00	H	FF	H	0	ms	No_use
2	00		00		FF		0		No_use	17	00		00		FF		0		No_use
3	00		00		FF		0		No_use	18	00		00		FF		0		No_use
4	00		00		FF		0		No_use	19	00		00		FF		0		No_use
5	00		00		FF		0		No_use	20	00		00		FF		0		No_use
6	00		00		FF		0		No_use	21	00		00		FF		0		No_use
7	00		00		FF		0		No_use	22	00		00		FF		0		No_use
8	00		00		FF		0		No_use	23	00		00		FF		0		No_use
9	00		00		FF		0		No_use	24	00		00		FF		0		No_use
10	00		00		FF		0		No_use	25	00		00		FF		0		No_use
11	00		00		FF		0		No_use										
12	00		00		FF		0		No_use										
13	00		00		FF		0		No_use										
14	00		00		FF		0		No_use										
15	00		00		FF		0		No_use										

Start Step: 1

Buttons: Start, Help, Save, Open, Close

Sequence Setting

Set register sequence by following process below.

(1) Select a command

Use [Select] pull-down box to choose commands.

Corresponding boxes will be valid.

< Select Pull-down menu >

- No_use: Not using this address
- Register: Register writing
- Reg(Mask): Register writing (Masked)
- Interval: Taking an interval
- Stop: Pausing the sequence
- End: Finishing the sequence

(1) Input sequence

[Address]: Data address

[Data]: Writing data

[Mask]: Mask

[Data] box data is ANDed with [Mask] box data. This is the actual writing data.
When Mask = 0x00, current setting is hold.

When Mask = 0xFF, the 8bit data which is set in the [Data] box is written.

When Mask = 0x0F, lower 4bit data which is set in the [Data] box is written.
Upper 4bit is hold to current setting.

[Interval]: Interval time

Valid boxes for each process command are shown bellow.

- No_use: None
- Register: [Address], [Data], [Interval]
- Reg(Mask): [Address], [Data], [Mask], [Interval]
- Interval: [Interval]
- Stop: None
- End: None

Control Buttons

The function of Control Button is shown bellow.

[Start]: Executing the sequence

[Help]: Opening a help window

[Save]: Saving sequence settings as a file. The file name is "*.aks".

[Open]: Opening a sequence setting file "*.aks".

[Close]: Closing the dialog box and finish the process.

Stop of the sequence

When "Stop" is selected in the sequence, processing is paused and it starts again when [Start] button is clicked.

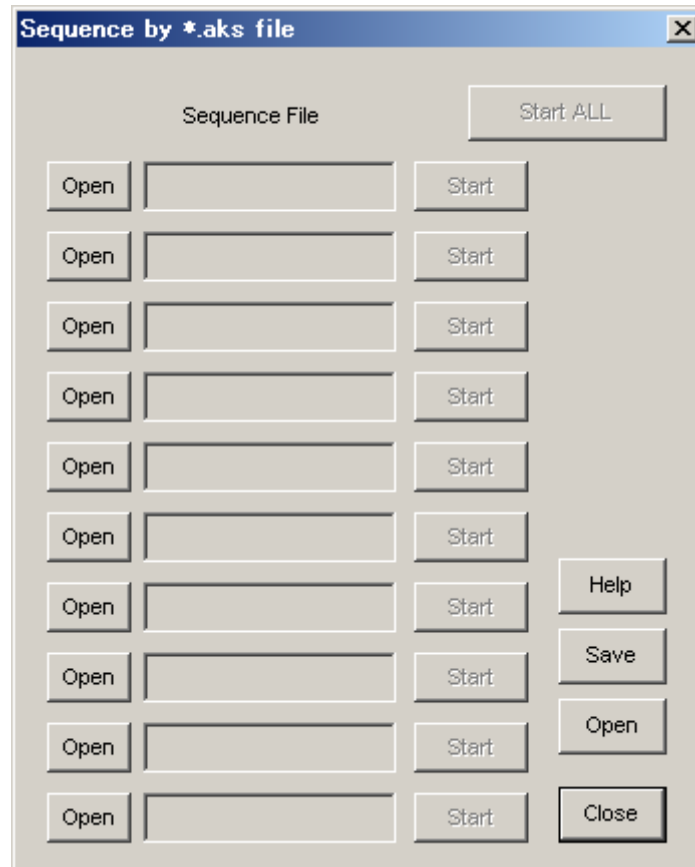
Restarting step number is shown in the "Start Step" box. When finishing the process until the end of sequence, "Start Step" will return to "1".

The sequence can be started from any step by writing the step number to the "Start Step" box.

Write "1" to the "Start Step" box and click [Start] button, when restarting the process from the beginning.

4. [Sequence(File)]: Sequence Setting File Dialog Box

Click [Sequence(File)] button to open sequence setting file dialog box.
Those files saved in the “Sequence setting dialog” can be applied in this dialog.



[Open (left)]: Opening a sequence setting file (*.aks).

[Start]: Executing the sequence setting.

[Start All]: Executing all sequence settings.

Sequences are executed in descending order.

[Help]: Pop up the help window.

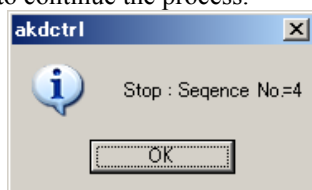
[Save]: Saving sequence setting file assignment. The file name is “*.mas”.

[Open(right)]: Opening a saved sequence setting file assignment “*. mas”.

[Close]: Closing the dialog box and finish the process.

*Operating Suggestions

- (1) Those files saved by [Save] button and opened by [Open] button on the right of the dialog “*.mas” should be stored in the same folder.
- (2) When “Stop” is selected in the sequence the process will be paused and a pop-up message will appear. Click “OK” to continue the process.



MEASUREMENT RESULTS

1) ADC part

[Measurement condition]

- Measurement unit : Audio Precision, System two, Cascade
- MCLK : 512fs at 48kHz, 256fs at 96kHz
- BICK : 64fs
- fs : 48kHz, 96kHz
- BW : 20Hz~20kHz at fs=48kHz, 20Hz~40kHz at 96kHz
- Bit : 24bit
- Power Supply : AVDD=DVDD= TVDD=5V
- Interface : DIT (AK4118)
- Temperature : Room

a) Single-ended Inputs

fs=48kHz

Parameter	Input signal	Measurement filter	LIN1	RIN1	Units
S/(N+D)	1kHz, -0.5dBFS	20kHz LPF	96.9	96.5	dB
DR	1kHz, -60dBFS	20kHz LPF	99.8	99.9	dB
		20kHz LPF+A-weighted	102.7	102.7	dB
S/N	No signal	20kHz LPF	99.9	100.1	dB
		20kHz LPF+A-weighted	102.8	103.1	dB

fs=96kHz

Parameter	Input signal	Measurement filter	LIN1	RIN1	Units
S/(N+D)	1kHz, -0.5dBFS	40kHz LPF	93.1	93.0	dB
DR	1kHz, -60dBFS	40kHz LPF	98.0	98.1	dB
		40kHz LPF+A-weighted	104.7	104.8	dB
S/N	No signal	40kHz LPF	98.1	98.1	dB
		40kHz LPF+A-weighted	105.2	105.2	dB

b) Differential Inputs

fs=48kHz

Parameter	Input signal	Measurement filter	LIN1 ±	RIN1 ±	Units
S/(N+D)	1kHz, -0.5dBFS	20kHz LPF	98.3	97.4	dB
DR	1kHz, -60dBFS	20kHz LPF	100.2	100.3	dB
		20kHz LPF+A-weighted	102.9	103.0	dB
S/N	No signal	20kHz LPF	100.4	100.4	dB
		20kHz LPF+A-weighted	103.3	103.3	dB

fs=96kHz

Parameter	Input signal	Measurement filter	LIN1 ±	RIN1 ±	Units
S/(N+D)	1kHz, -0.5dBFS	40kHz LPF	95.9	95.5	dB
DR	1kHz, -60dBFS	40kHz LPF	98.4	98.5	dB
		40kHz LPF+A-weighted	105.2	105.4	dB
S/N	No signal	40kHz LPF	98.4	98.5	dB
		40kHz LPF+A-weighted	105.6	105.5	dB

2) DAC part

[Measurement condition]

- Measurement unit : Audio Precision, System two, Cascade
- MCLK : 512fs at 48kHz, 256fs at 96kHz, 128fs at 192kHz
- BICK : 64fs
- fs : 48kHz, 96kHz, 192kHz
- BW : 20Hz~20kHz at fs=48kHz, 20Hz~40kHz at 96kHz, 20Hz~40kHz at 192kHz
- Bit : 24bit
- Power Supply : AVDD=DVDD= TVDD=5V
- Interface : DIR (AK4118)
- Temperature : Room

fs=48kHz

Parameter	Input signal	Measurement filter	LOUT1	ROUT1	Units
S/(N+D)	1kHz, 0dBFS	20kHz Brick-wall LPF	101.5	100.4	dB
DR	1kHz, -60dBFS	20kHz Brick-wall LPF	103.3	103.2	dB
		20kHz Brick-wall LPF A-weighted	105.7	105.7	dB
S/N	No signal	20kHz Brick-wall LPF	103.3	103.1	dB
		20kHz Brick-wall LPF A-weighted	105.8	105.7	dB

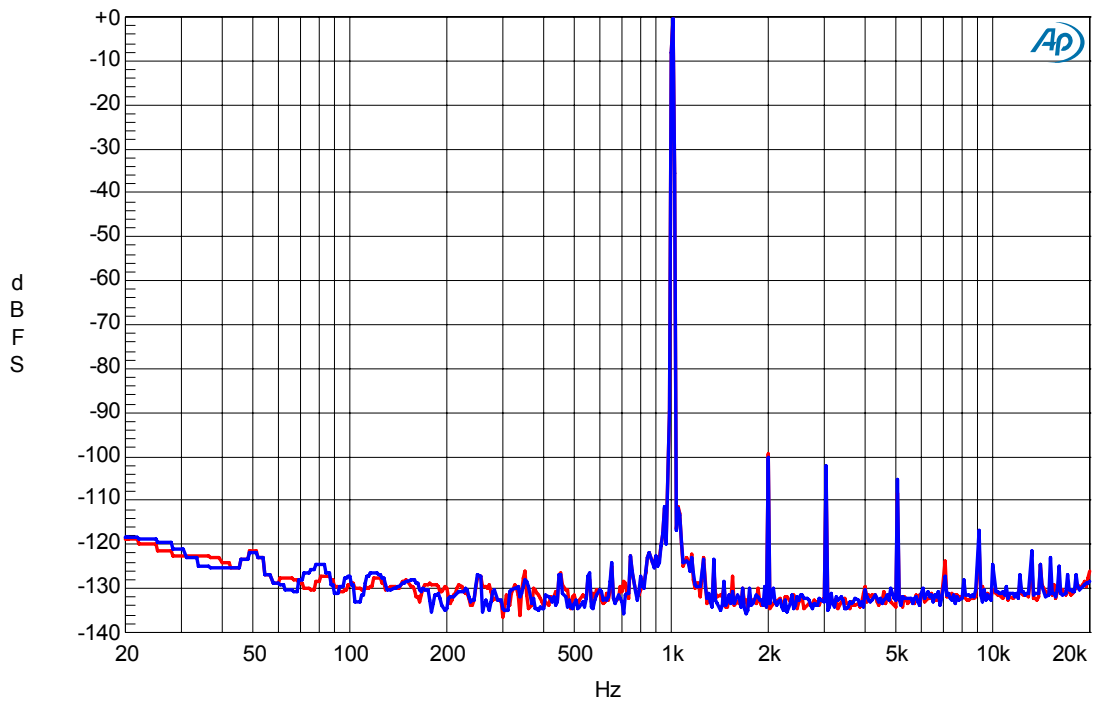
fs=96kHz

Parameter	Input signal	Measurement filter	LOUT1	ROUT1	Units
S/(N+D)	1kHz, 0dBFS	40kHz Brick-wall LPF	99.3	98.1	dB
DR	1kHz, -60dBFS	40kHz Brick-wall LPF	100.6	100.5	dB
		40kHz Brick-wall LPF A-weighted	105.6	105.5	dB
S/N	No signal	40kHz Brick-wall LPF	100.6	100.5	dB
		40kHz Brick-wall LPF A-weighted	105.6	105.5	dB

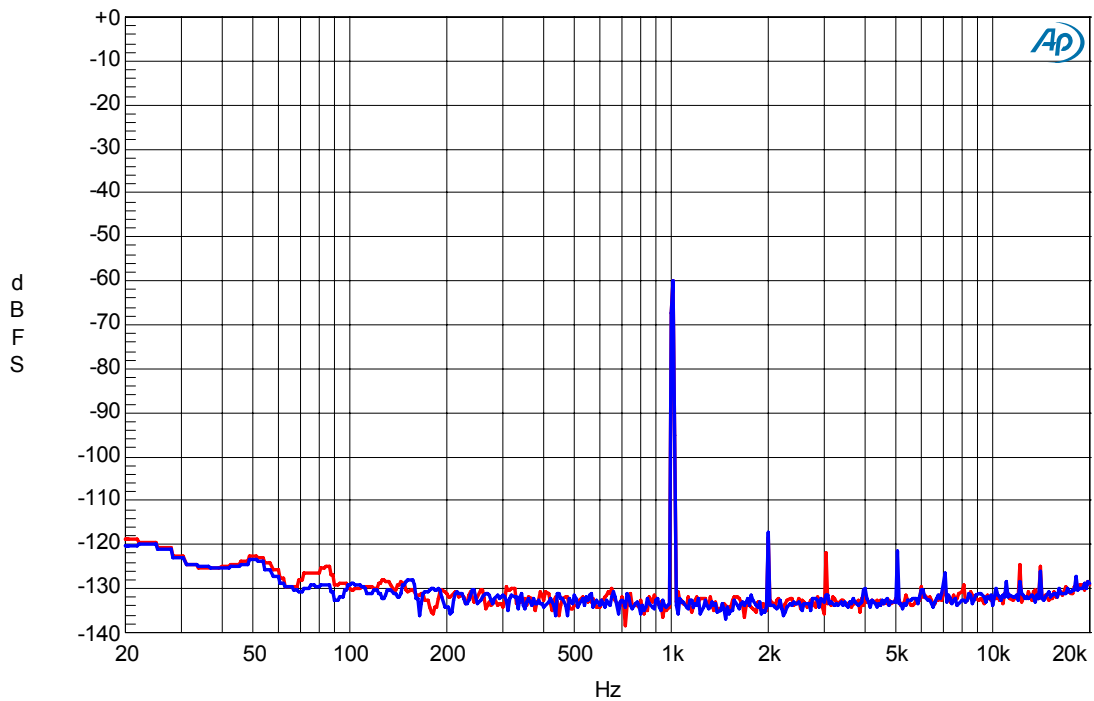
fs=192kHz

Parameter	Input signal	Measurement filter	LOUT1	ROUT1	Units
S/(N+D)	1kHz, 0dBFS	40kHz Brick-wall LPF	98.3	97.6	dB
DR	1kHz, -60dBFS	40kHz Brick-wall LPF	100.5	100.6	dB
		40kHz Brick-wall LPF A-weighted	105.6	105.5	dB
S/N	No signal	40kHz Brick-wall LPF	100.7	100.5	dB
		40kHz Brick-wall LPF A-weighted	105.6	105.5	dB

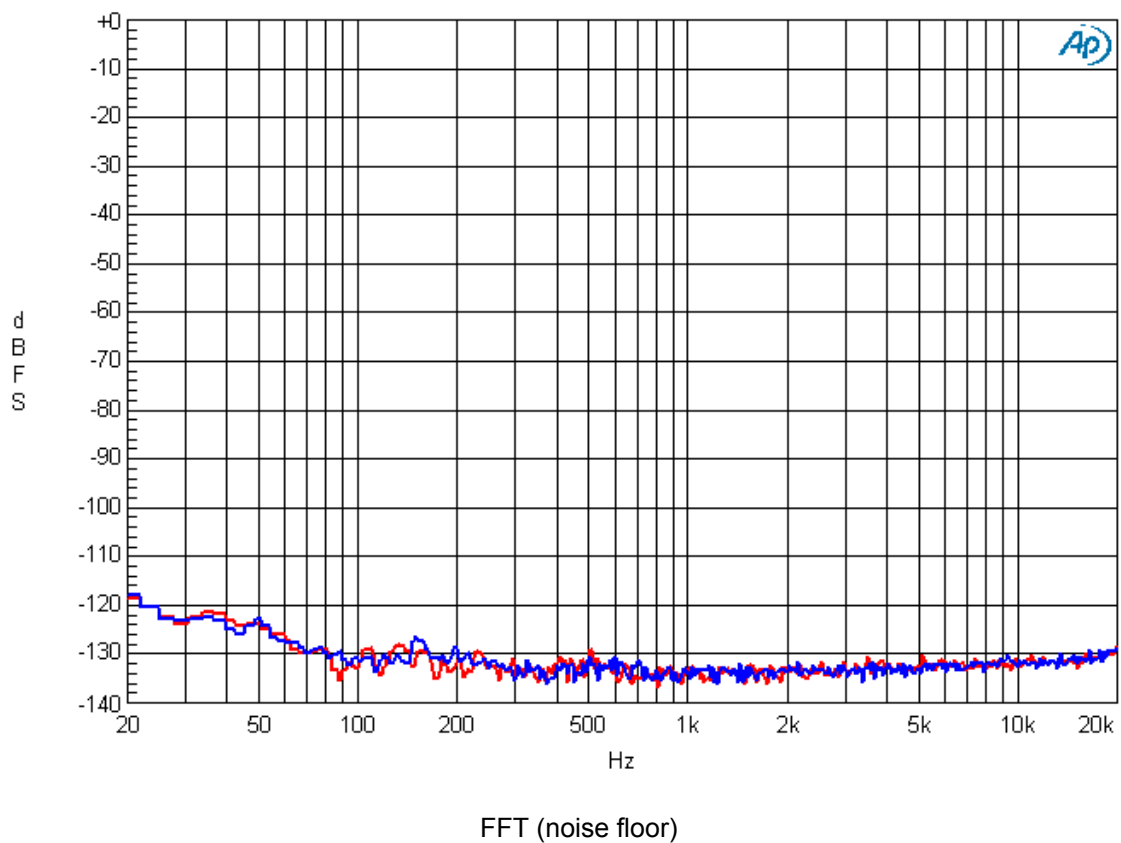
1.1.1 ADC (fs=48kHz, Single-ended Inputs)

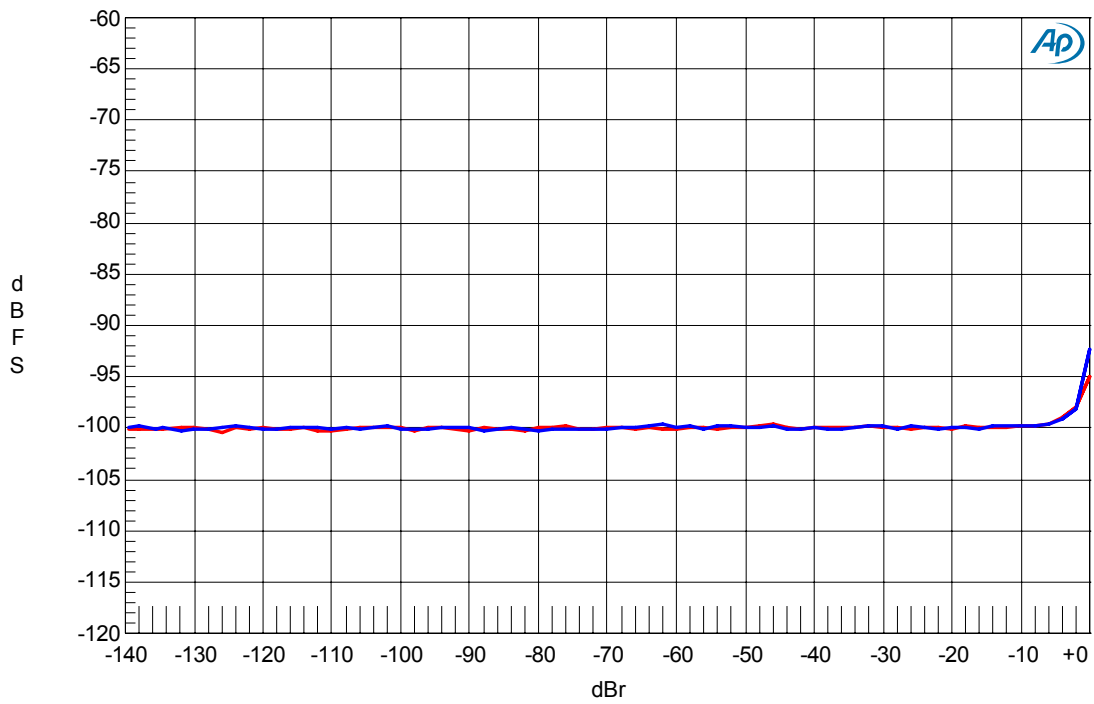


FFT (Input=-0.5dBr, fin=1kHz)

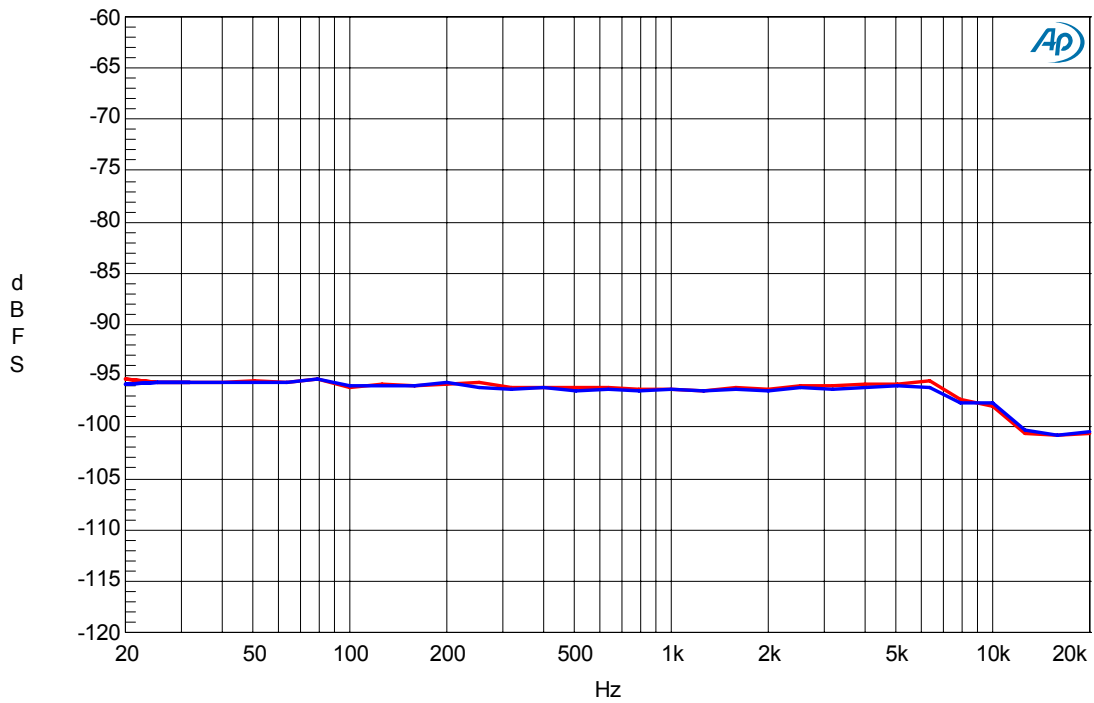


FFT (Input=-60dBr, fin=1kHz)

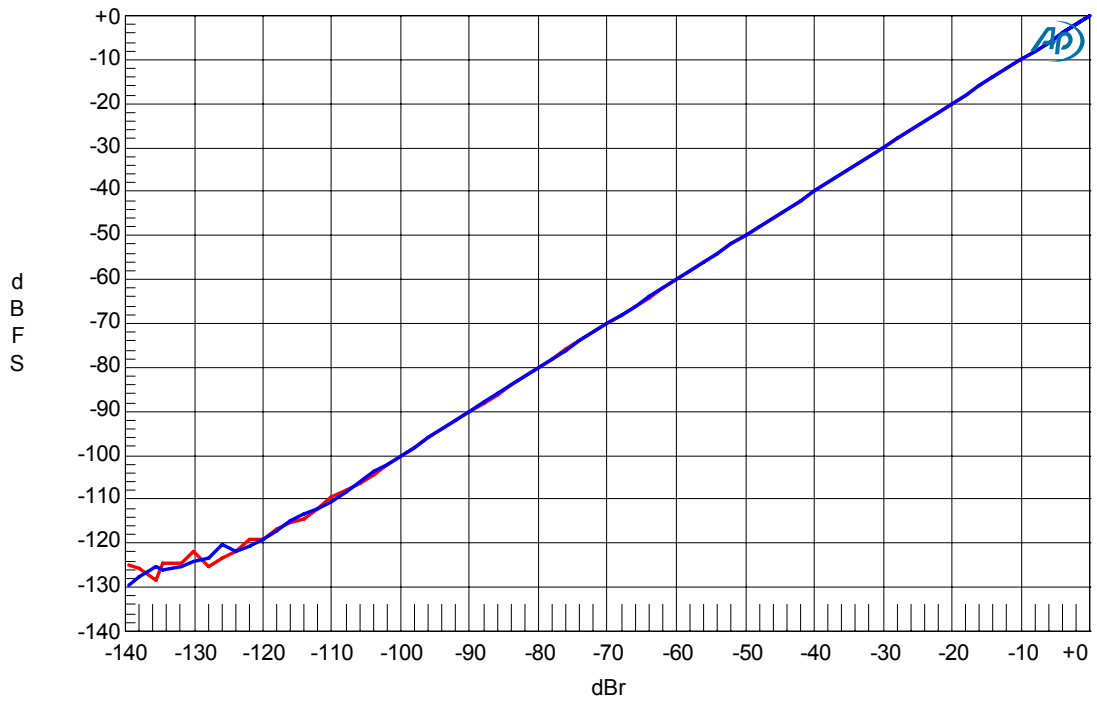




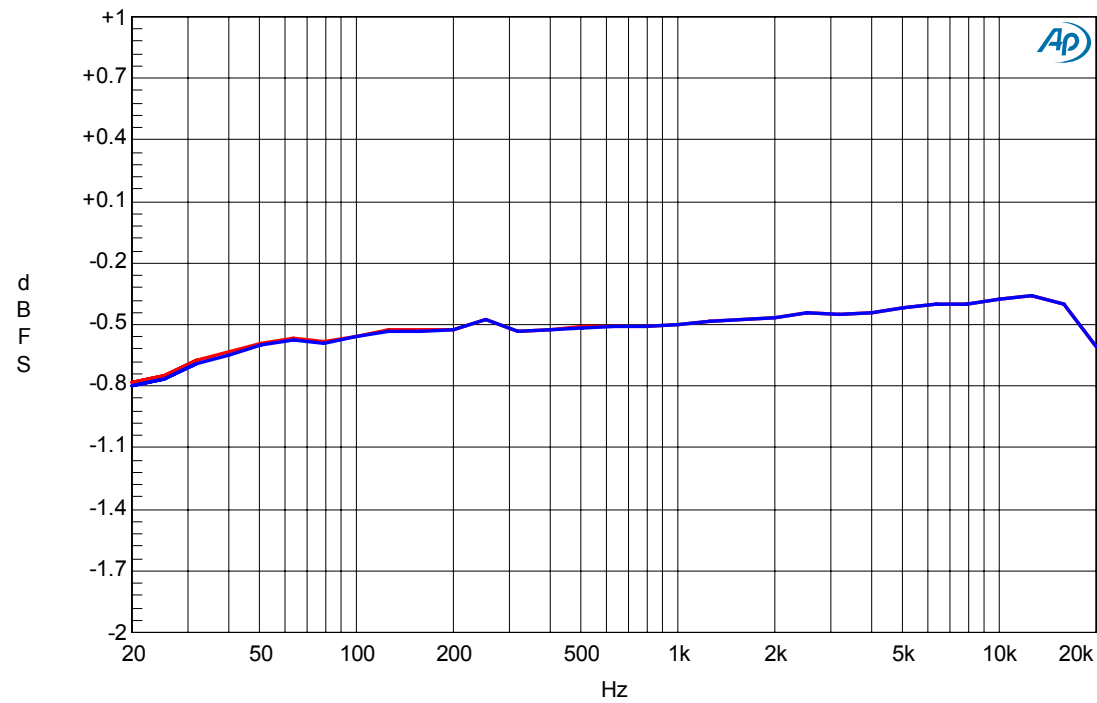
THD + N vs. Input Level (fin=1kHz)



THD + N vs. Input Frequency (Input=-0.5dBr)

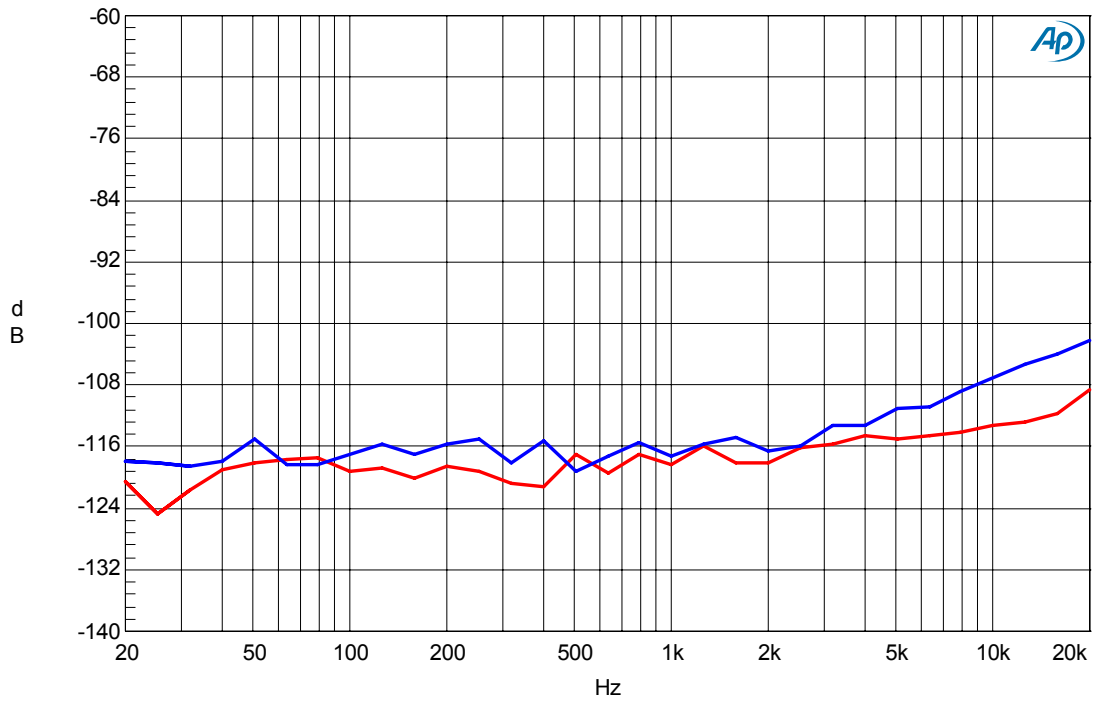


Linearity (fin=1kHz)



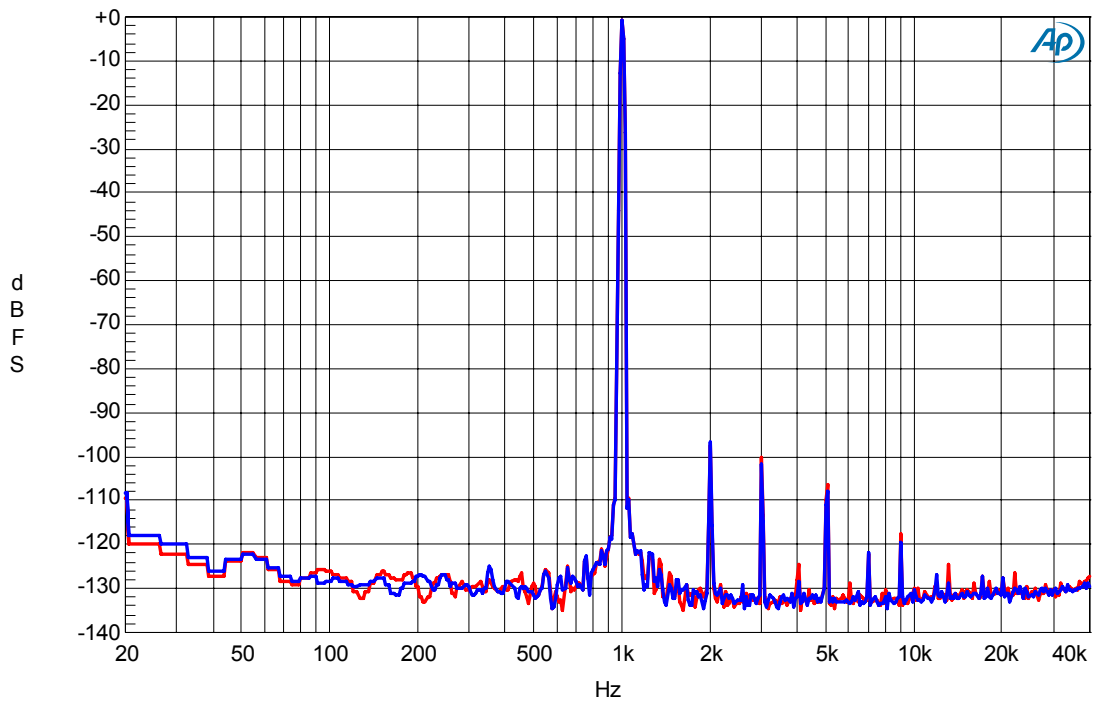
Frequency Response (Input Level=-0.5dBr)

v

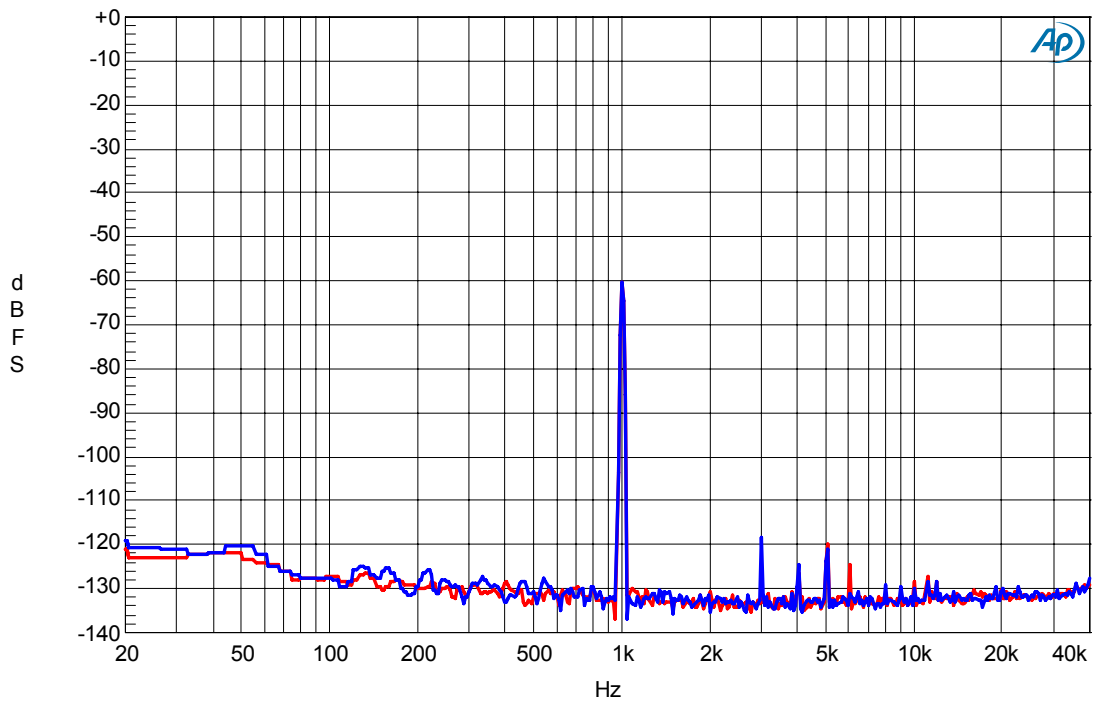


Crosstalk (Input Level=-0.5dBr)

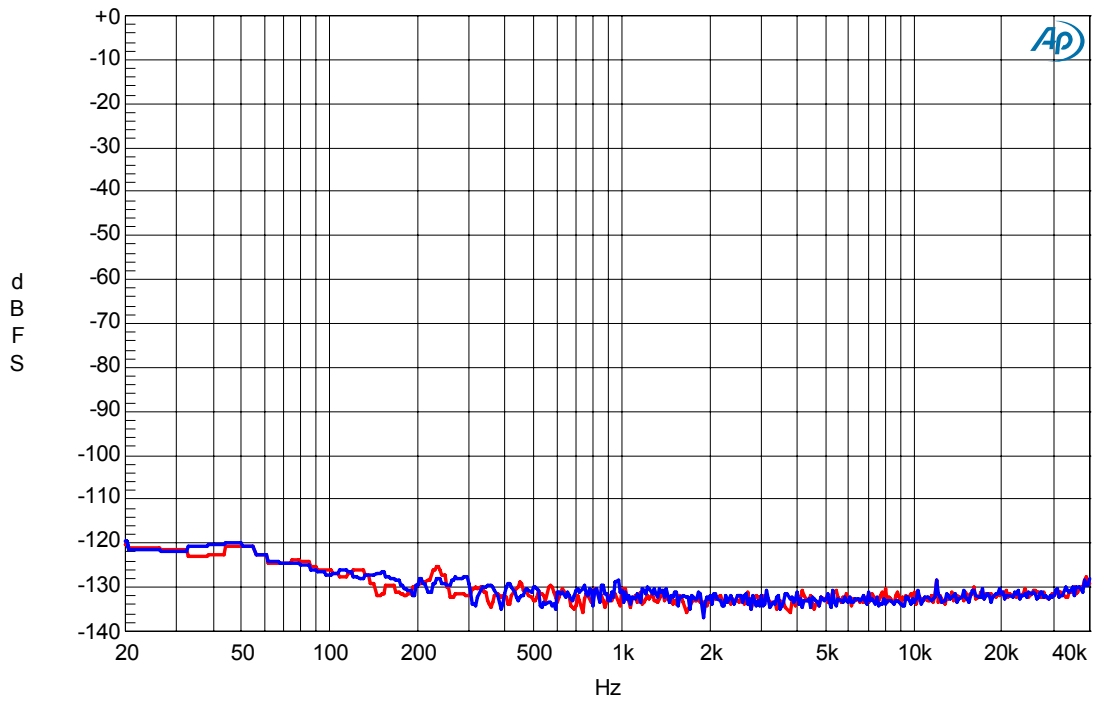
1.1.2 ADC (fs=96kHz, Single-ended Inputs)



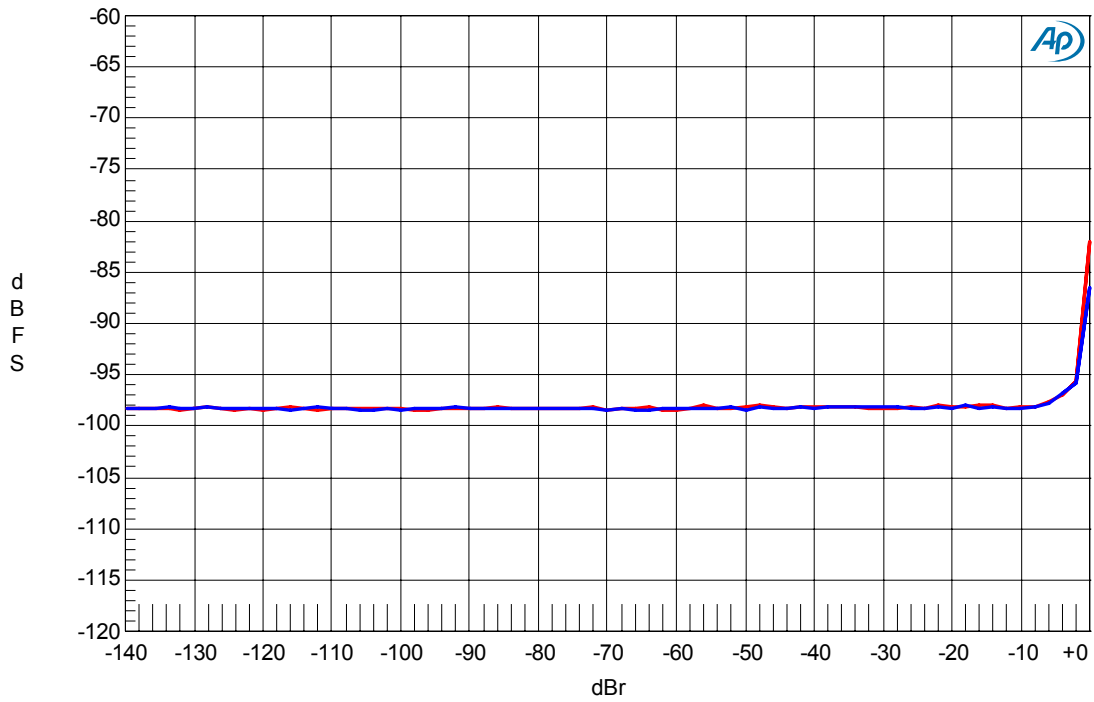
FFT (Input=-0.5dBr, fin=1kHz)



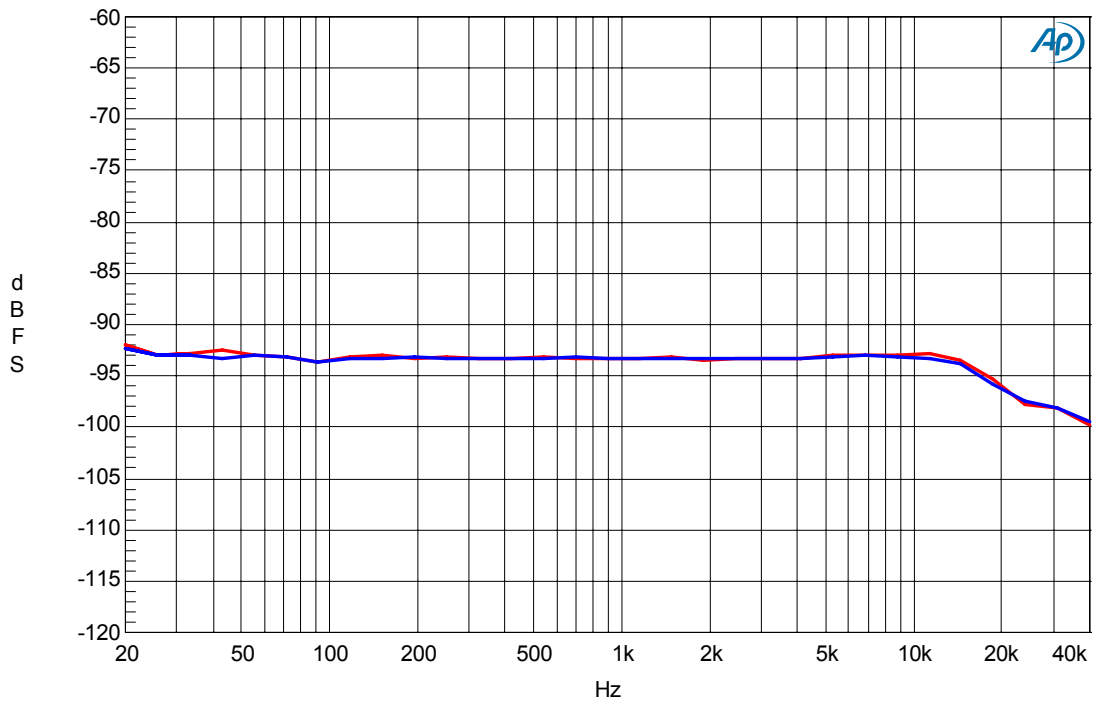
FFT (Input=-60dBr, fin=1kHz)



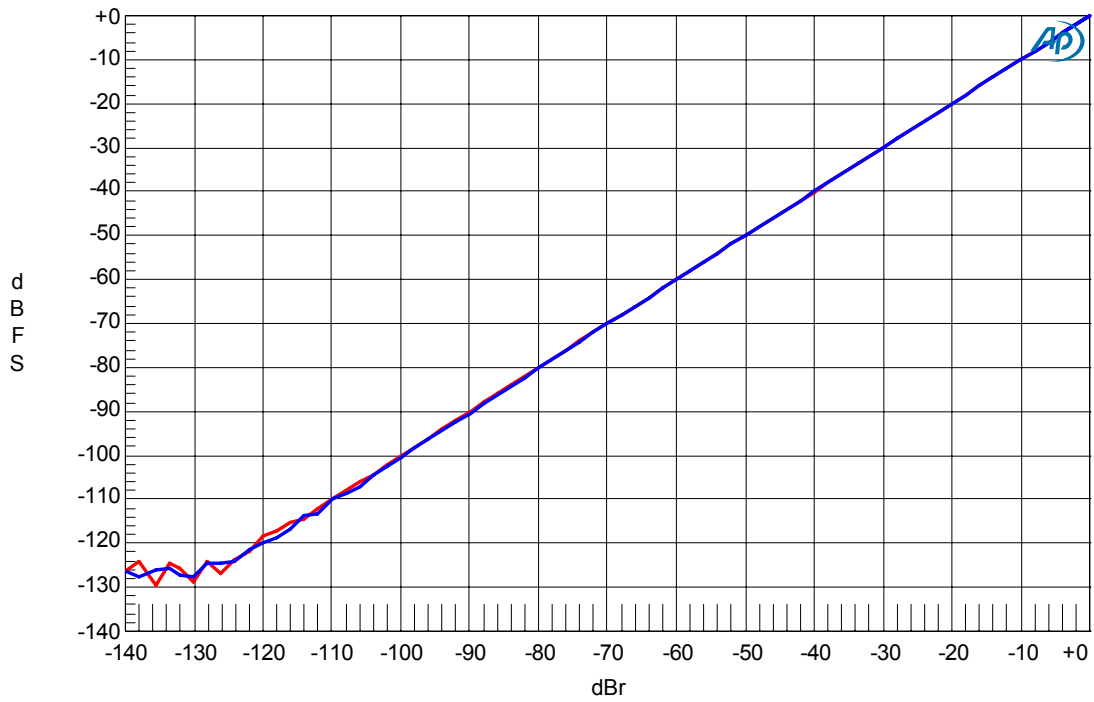
FFT (Noise floor)



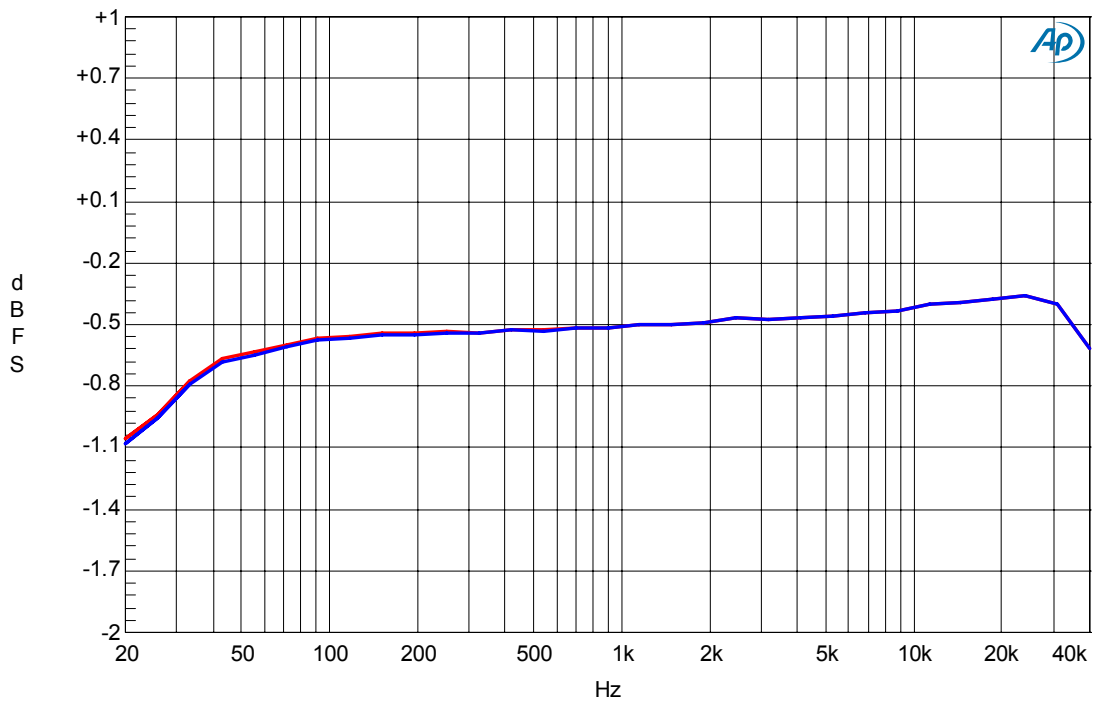
THD + N vs. Input Level (fin=1kHz)



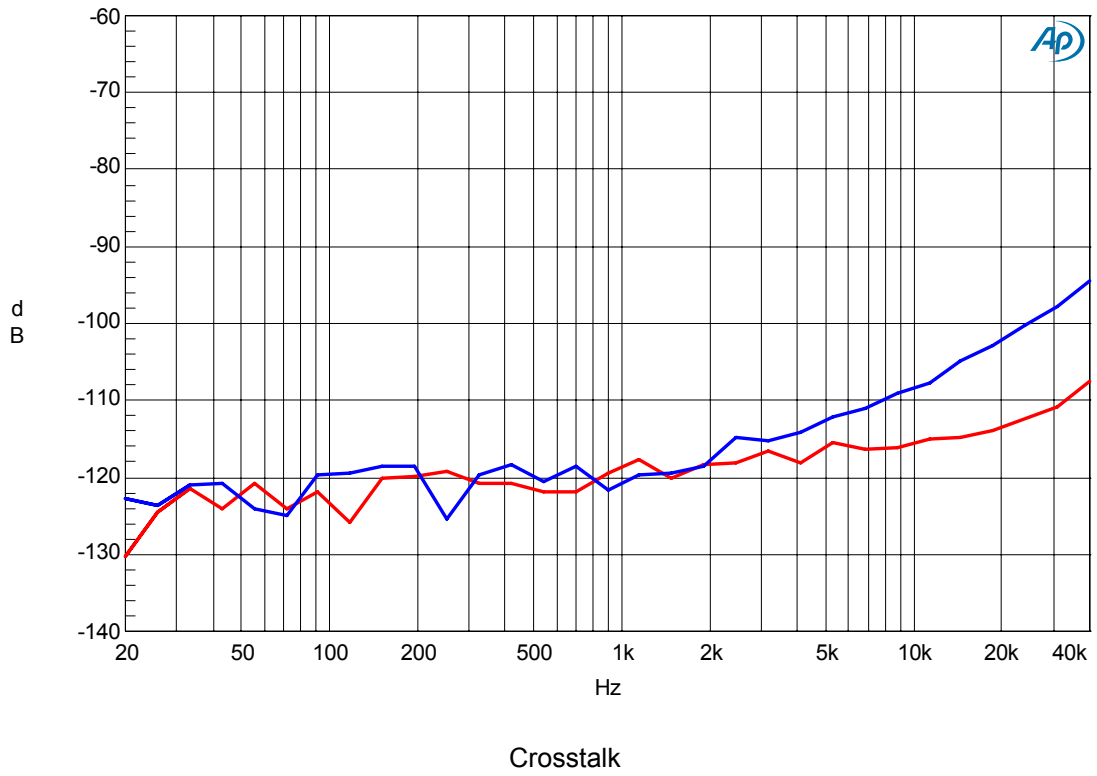
THD + N vs. Input Frequency (Input Level=-0.5dBr)



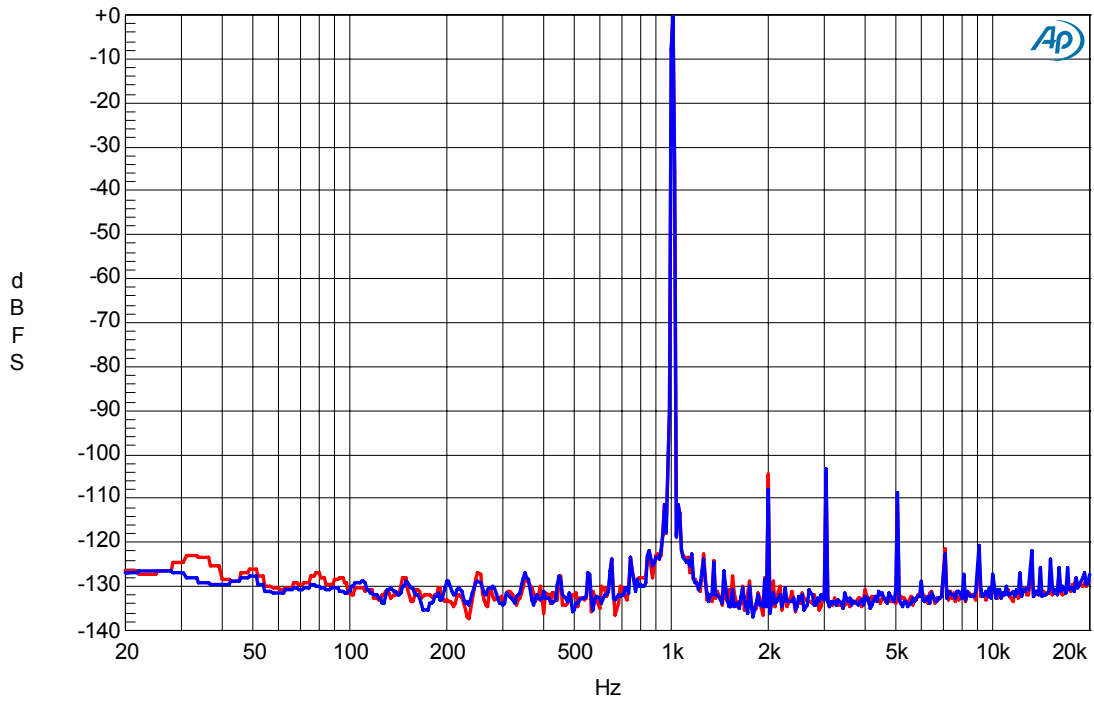
Linearity (fin=1kHz)



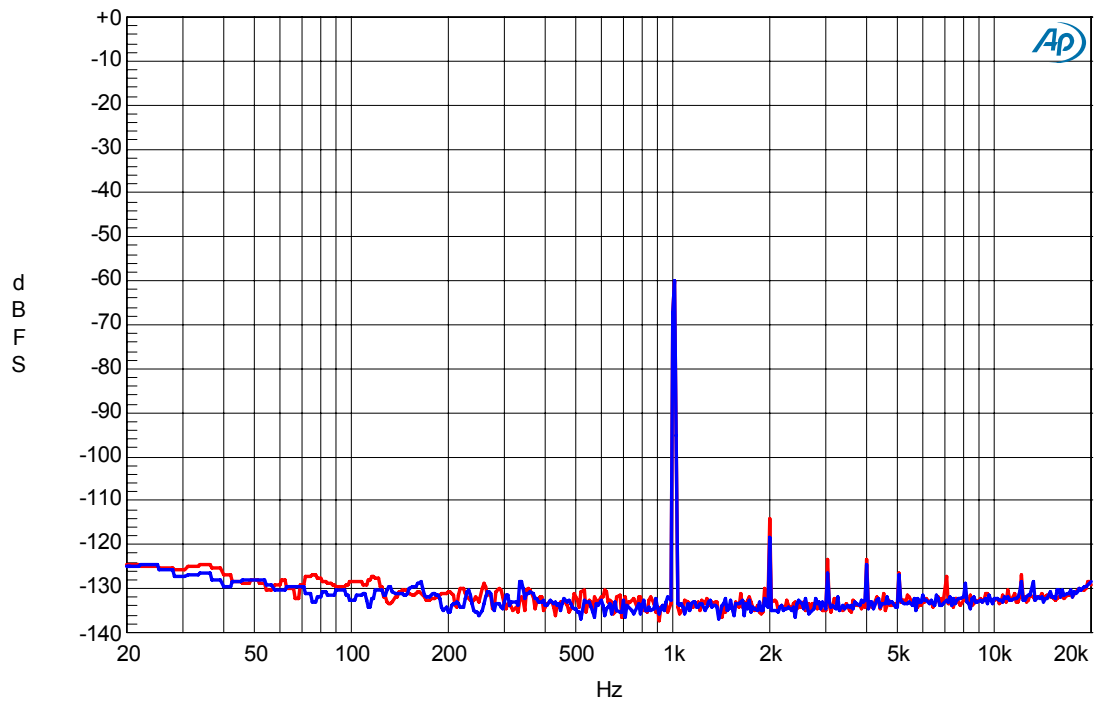
Frequency Response (Input Level=-0.5dBr)



1.2.1 ADC (fs=48kHz, Differential Inputs)

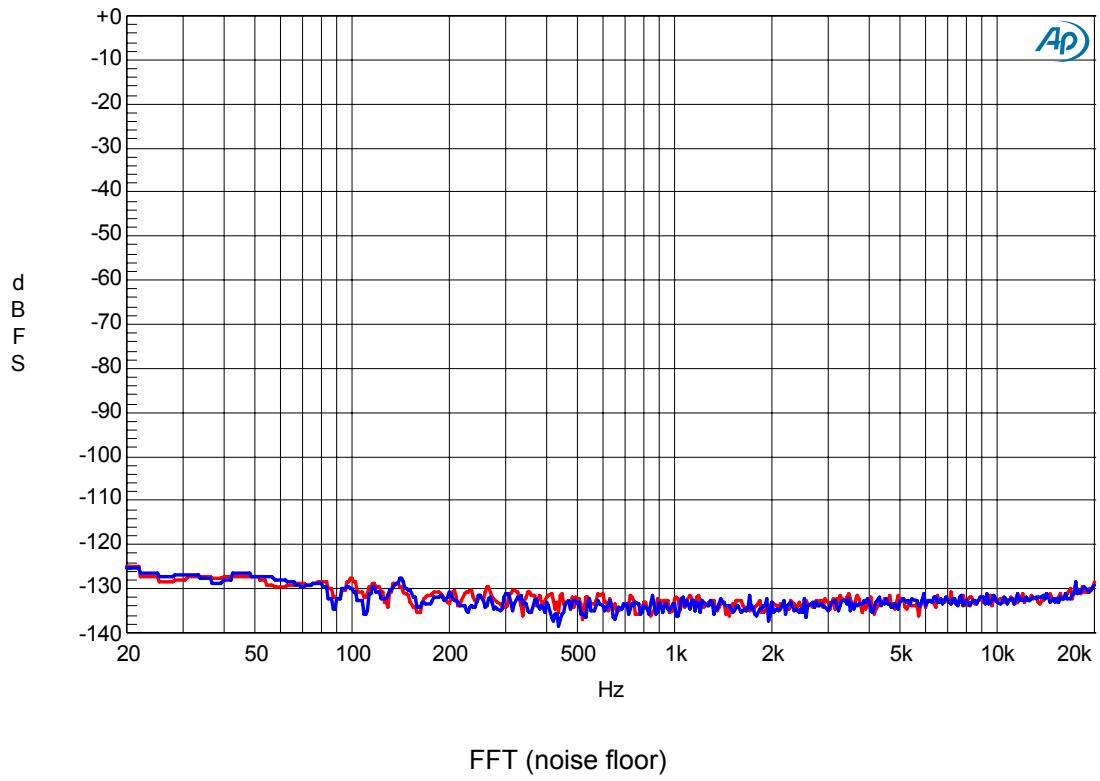


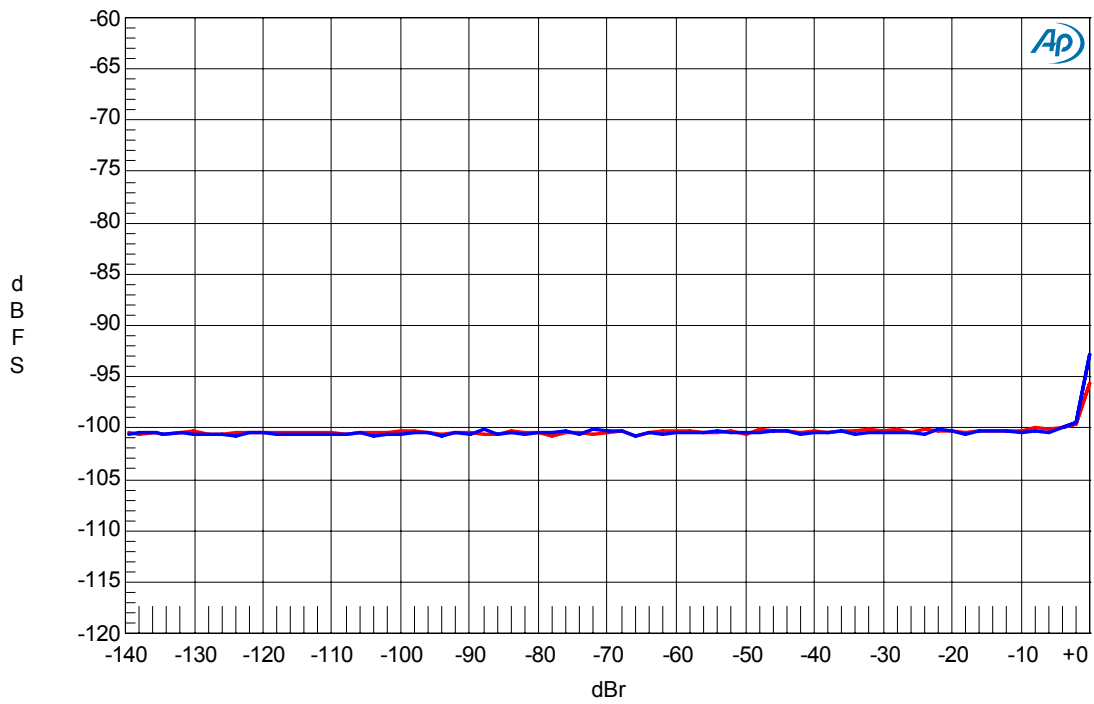
FFT (Input=-0.5dBr, fin=1kHz)



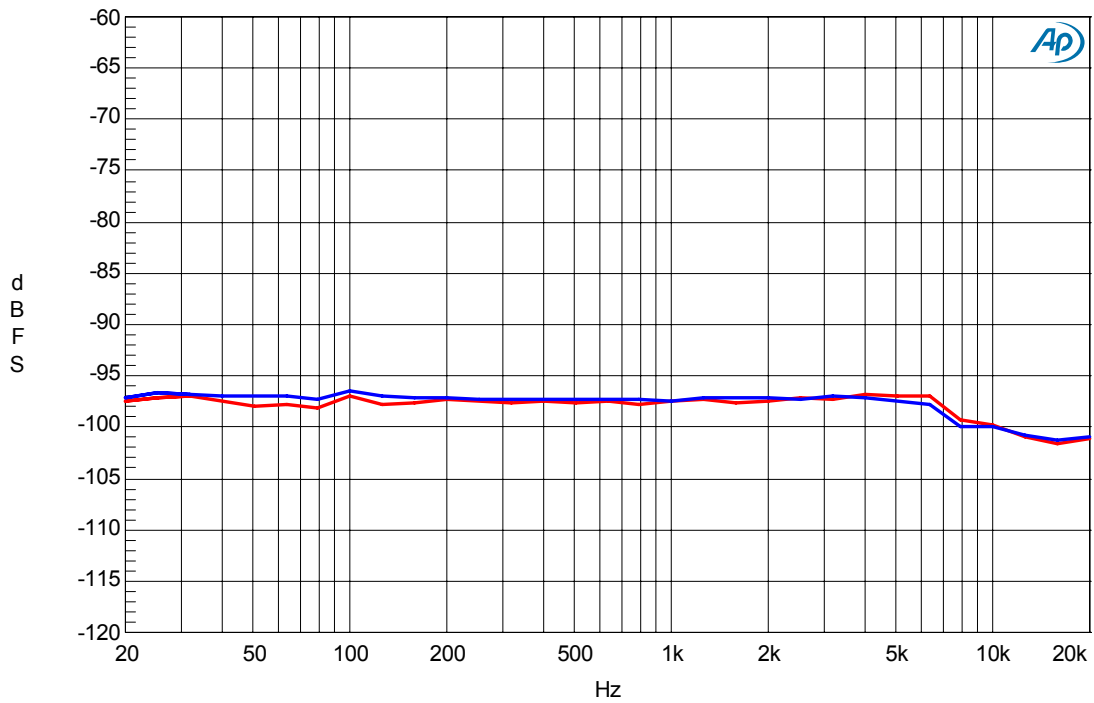
(Input=-60dBr, fin=1kHz)

FFT

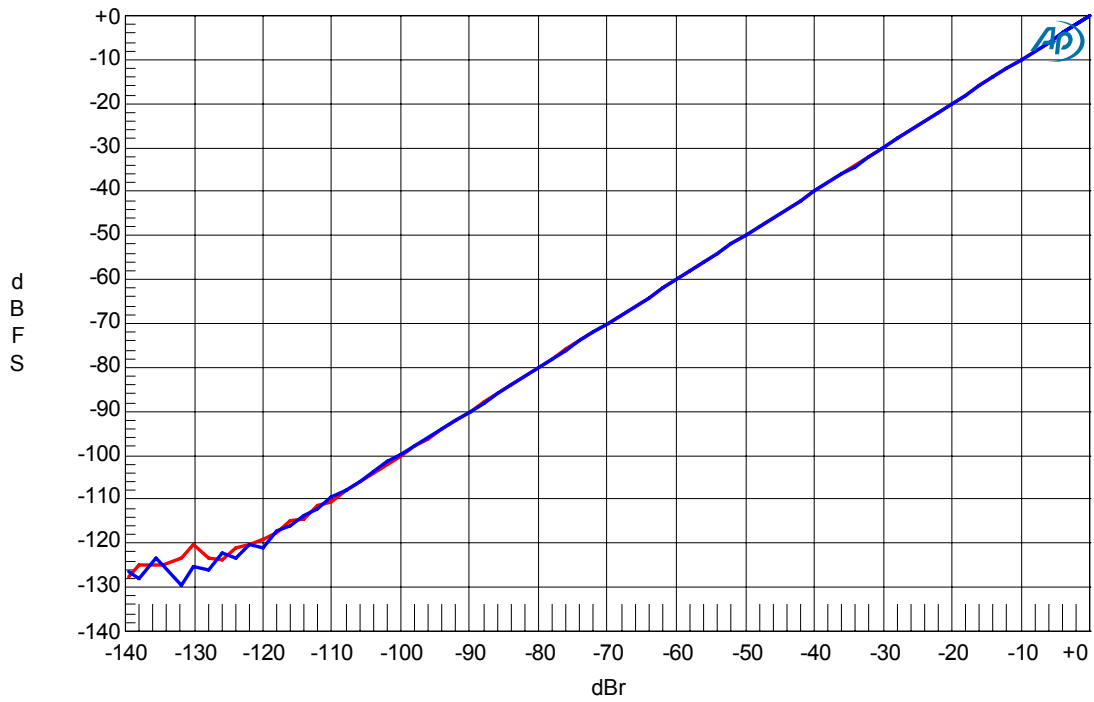




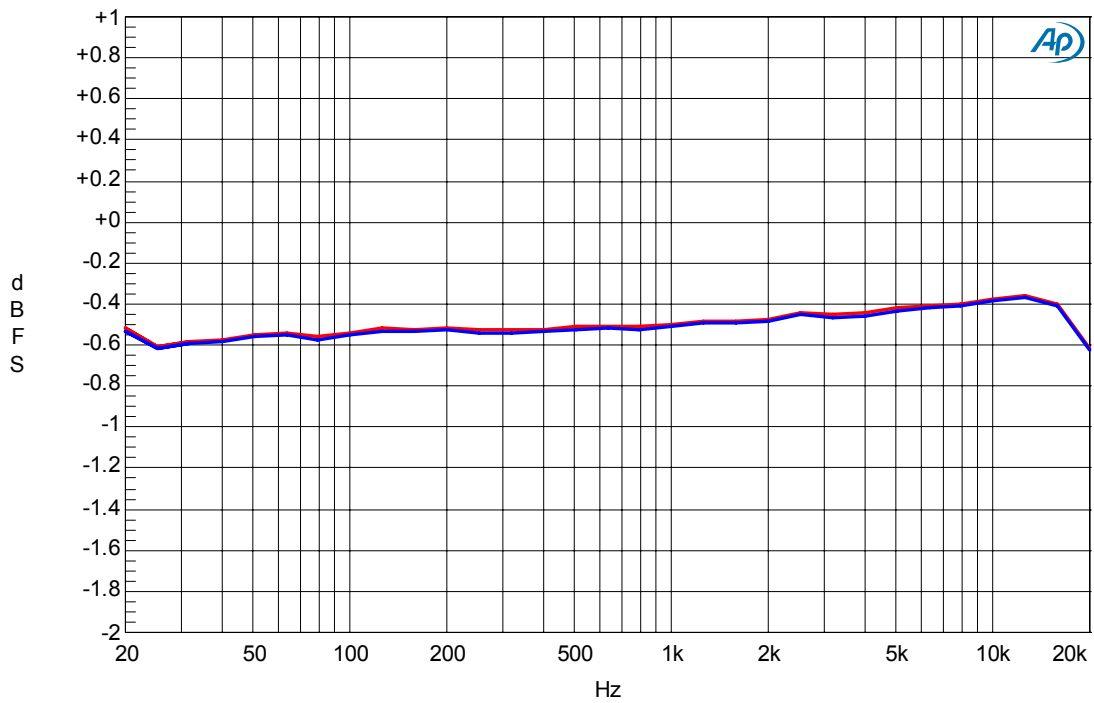
THD + N vs. Input Level (fin=1kHz)



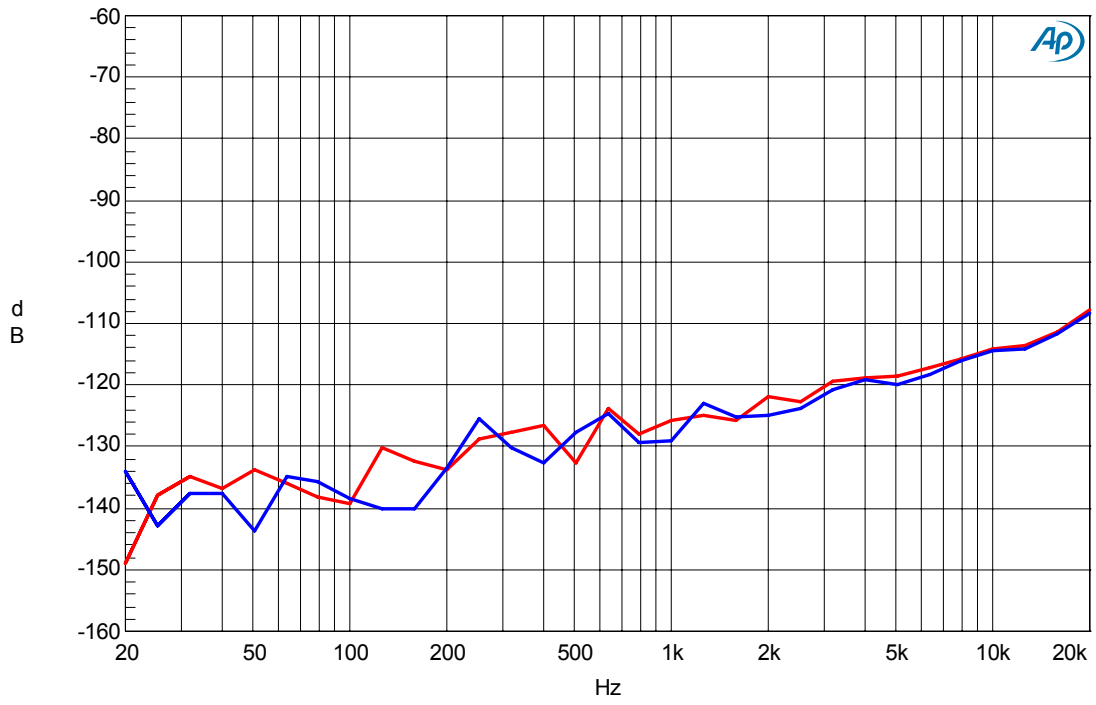
THD + N vs. Input Frequency (Input=-0.5dBr)



Linearity (fin=1kHz)

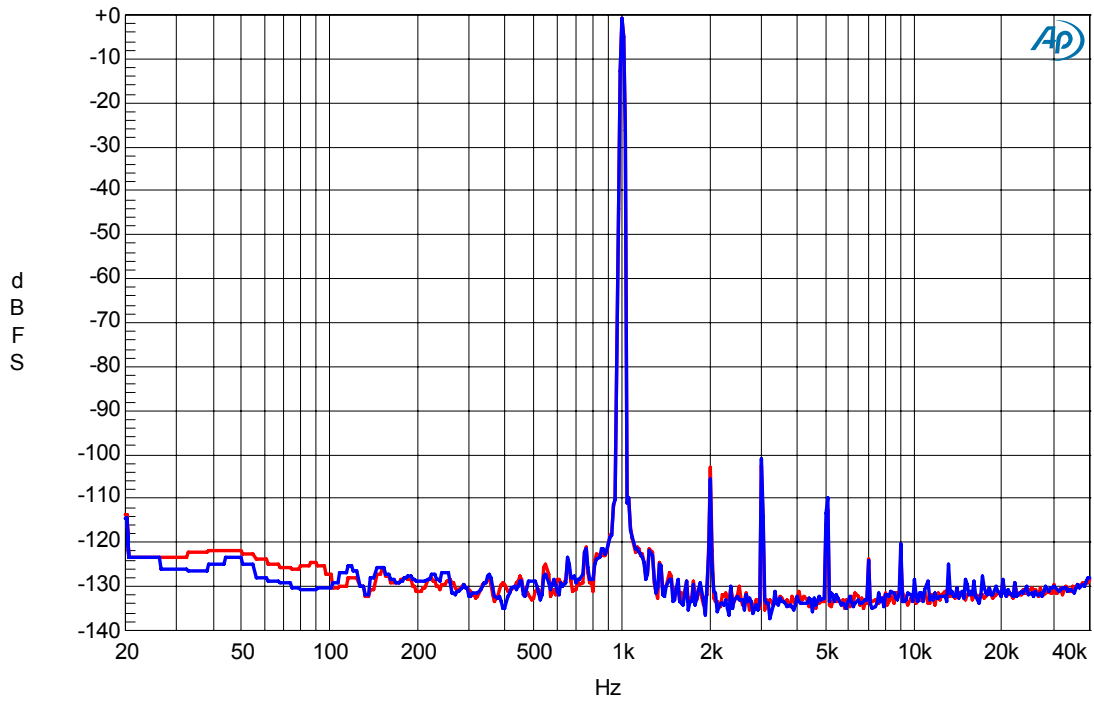


Frequency Response (Input Level=-0.5dBr)

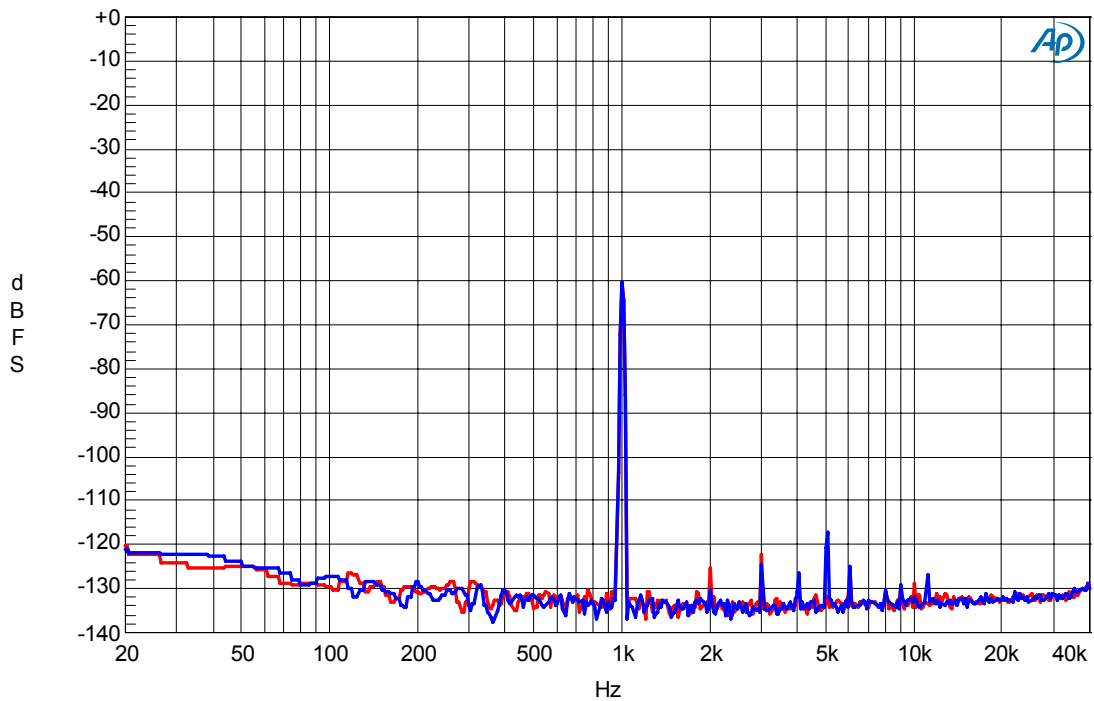


Crosstalk (Input Level=-0.5dBr)

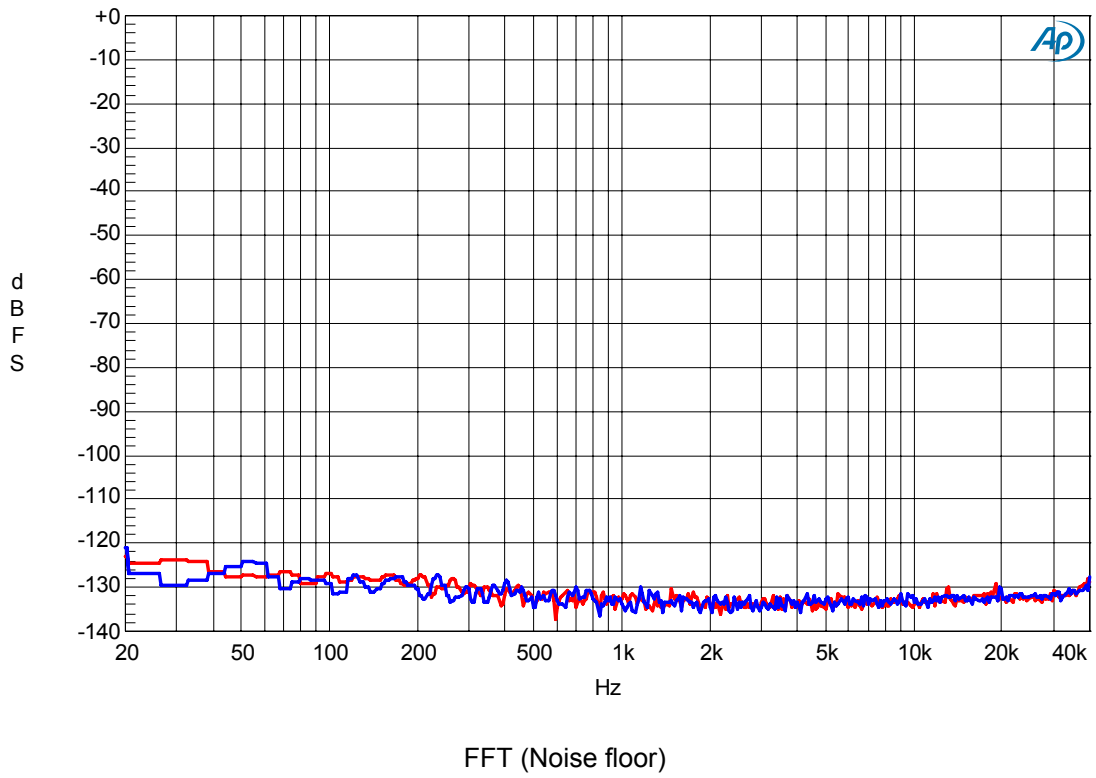
1.2.2 ADC (fs=96kHz, Differential Inputs)

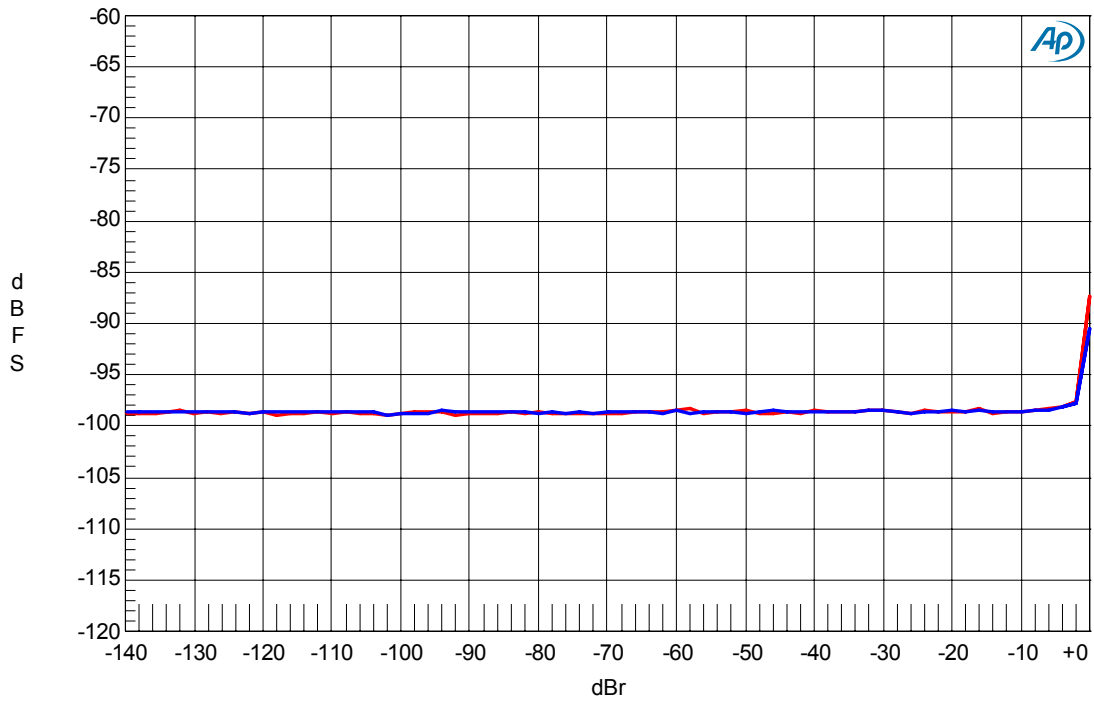


FFT (Input=-0.5dBr, fin=1kHz)

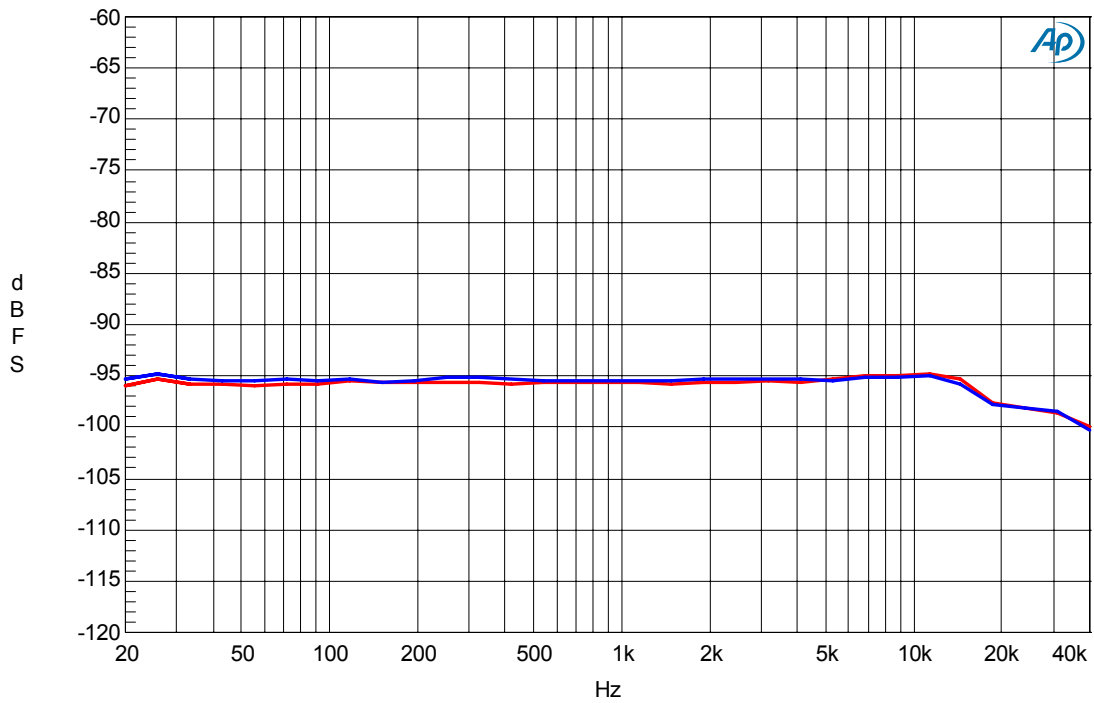


FFT (Input=-60dBr, fin=1kHz)

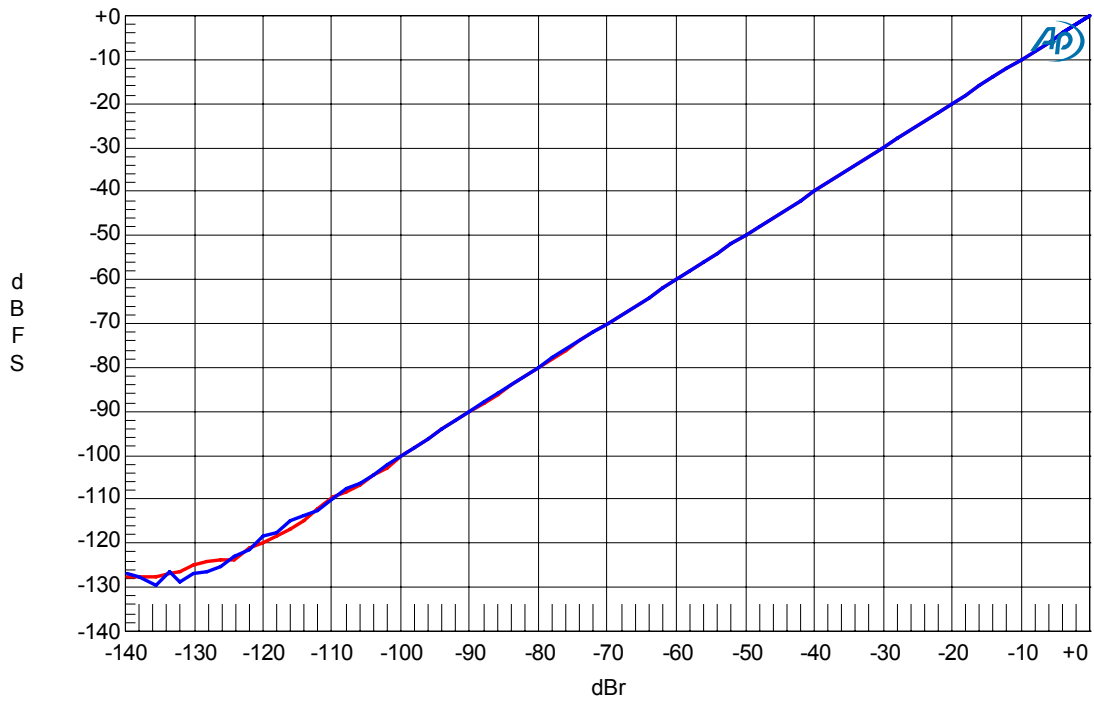




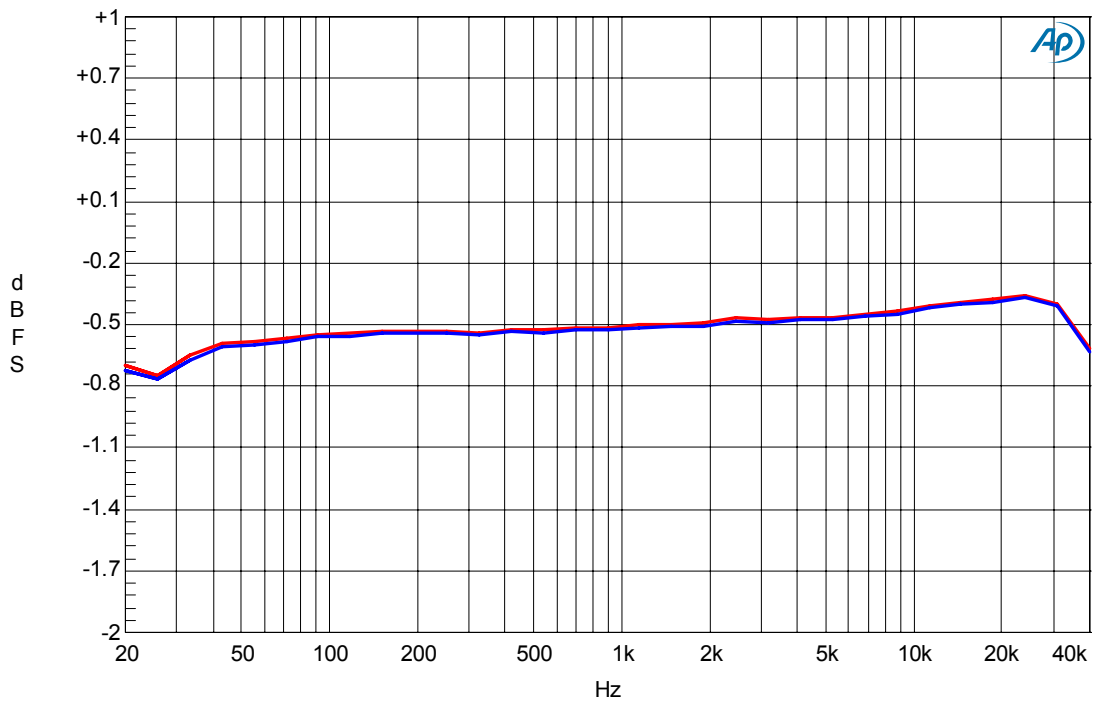
THD + N vs. Input Level (fin=1kHz)



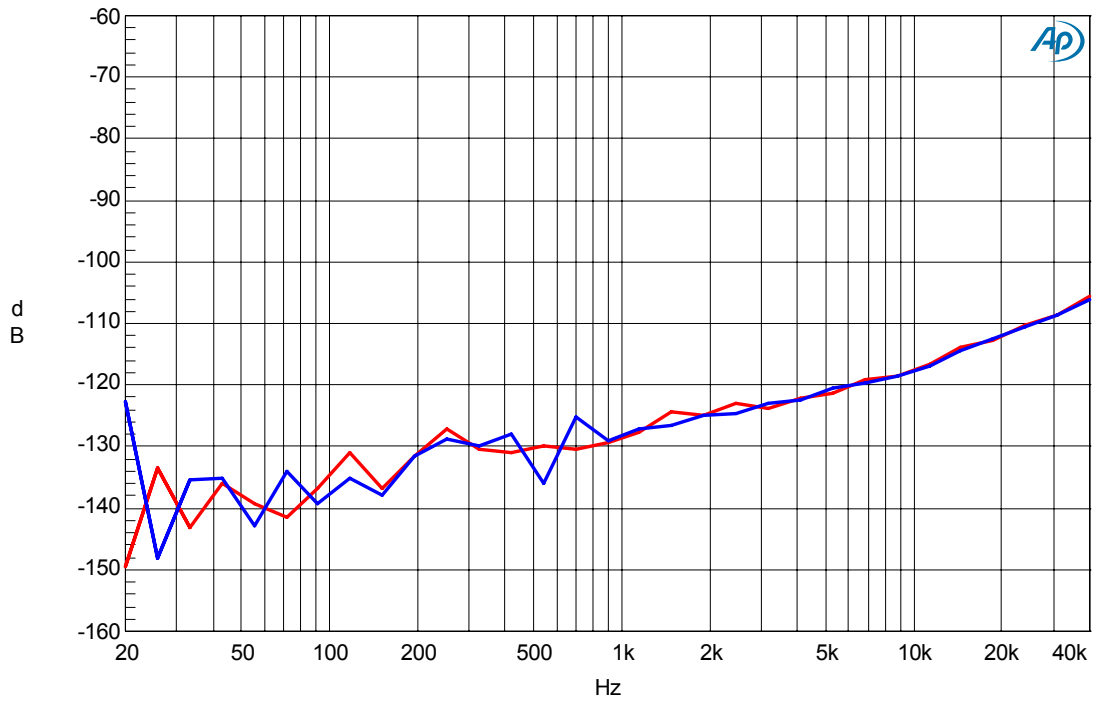
THD + N vs. Input Frequency (Input Level=-0.5dBr)



Linearity (fin=1kHz)

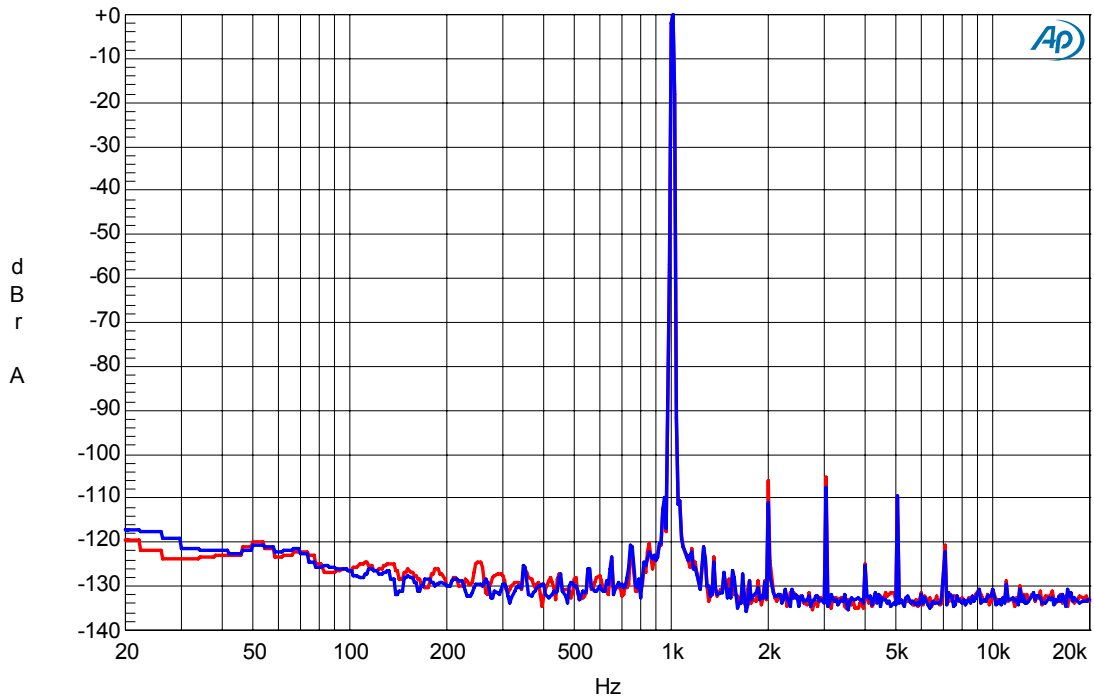


Frequency Response (Input Level=-0.5dBr)

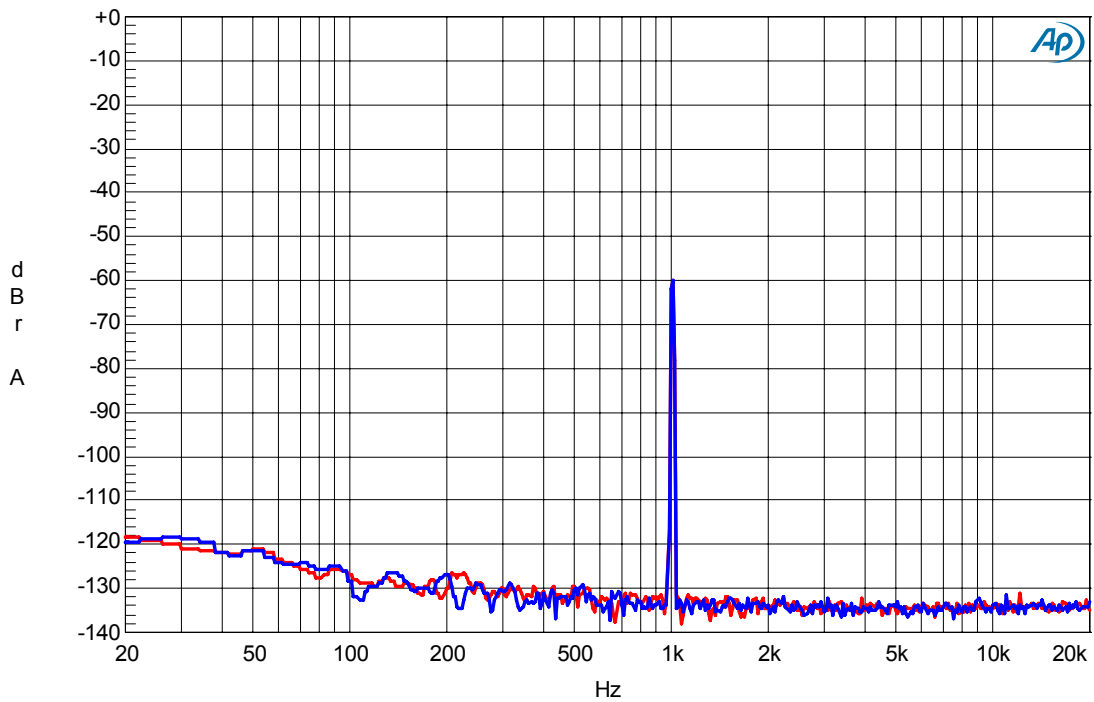


Crosstalk (Input Level=-0.5dBr)

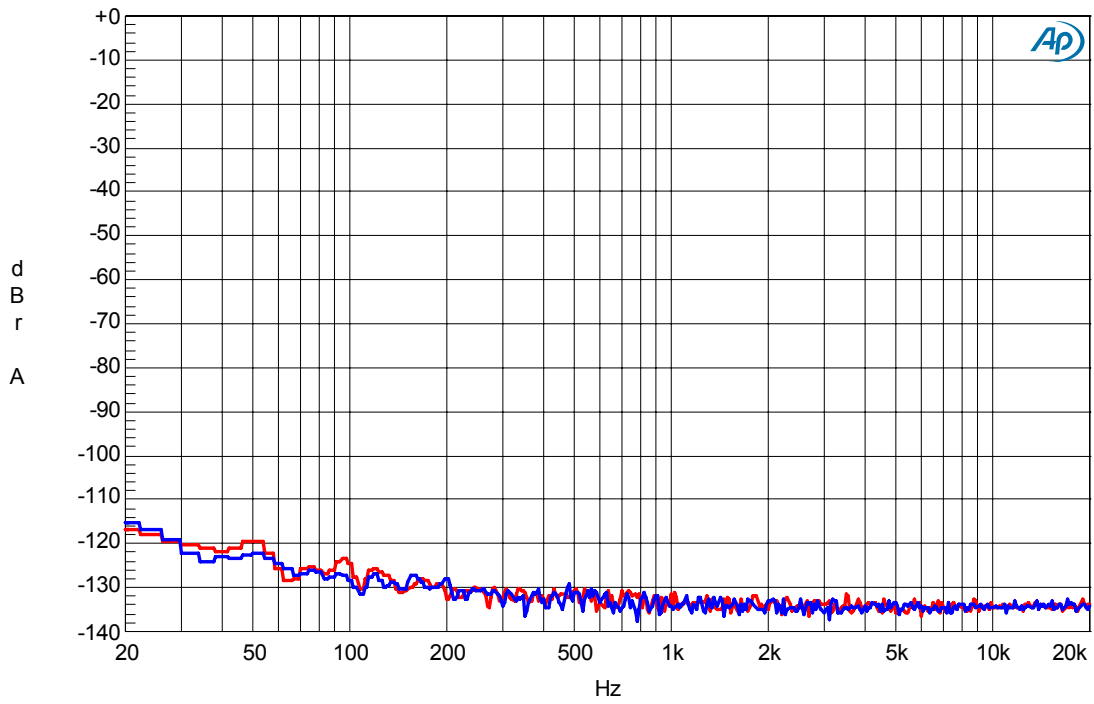
2.1 DAC (fs=48kHz)



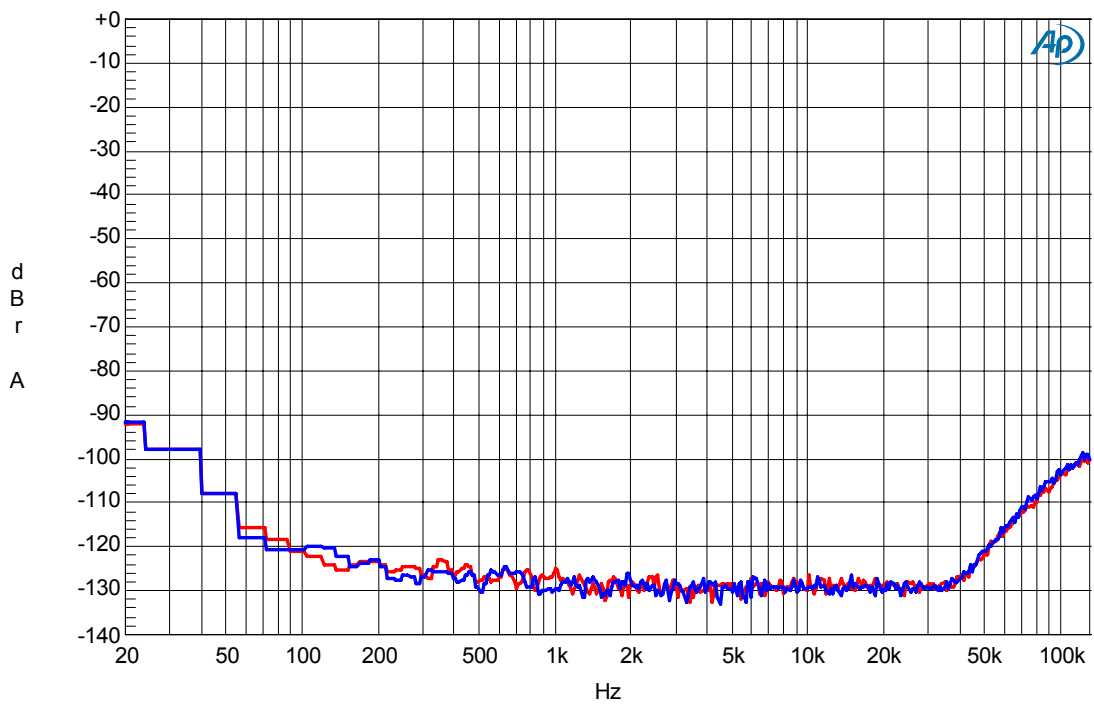
FFT (Input=0dBFS, fin=1kHz)



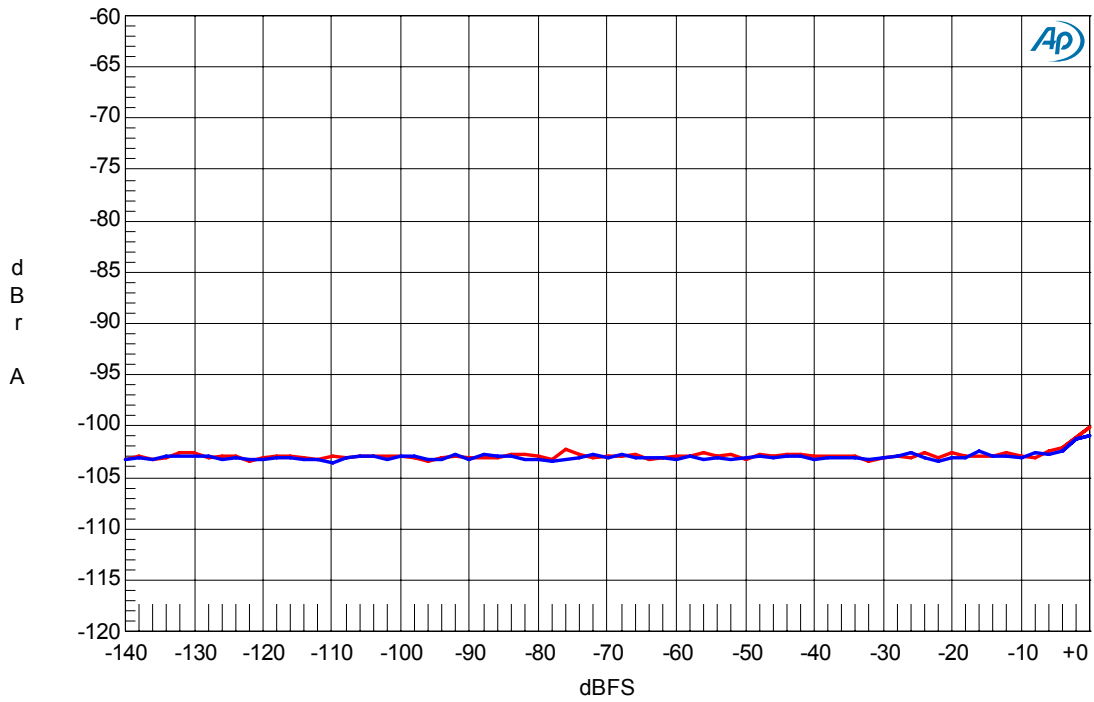
FFT (Input=-60dBFS, fin=1kHz)



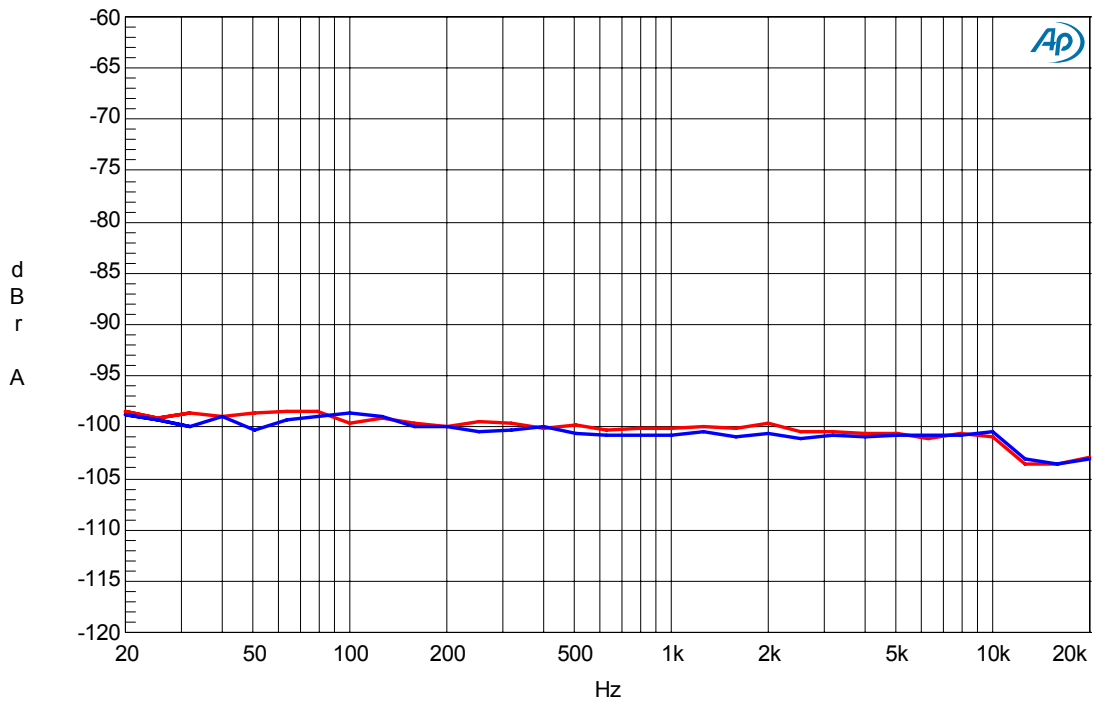
FFT (Noise floor)



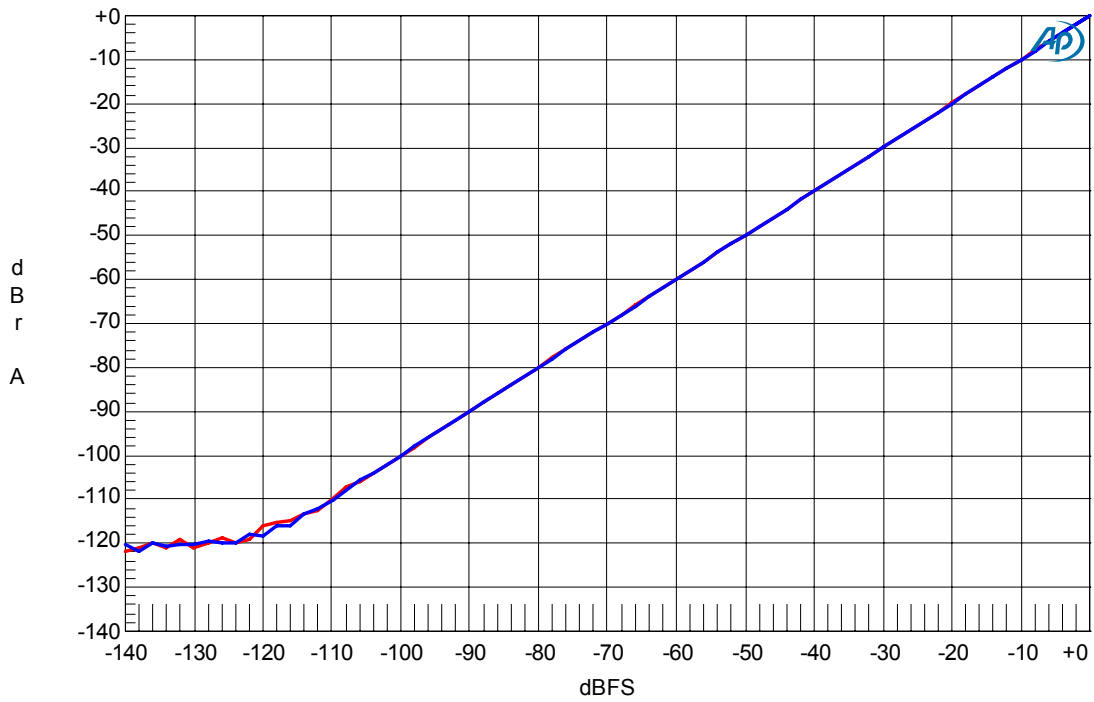
FFT (Out-of-band noise)



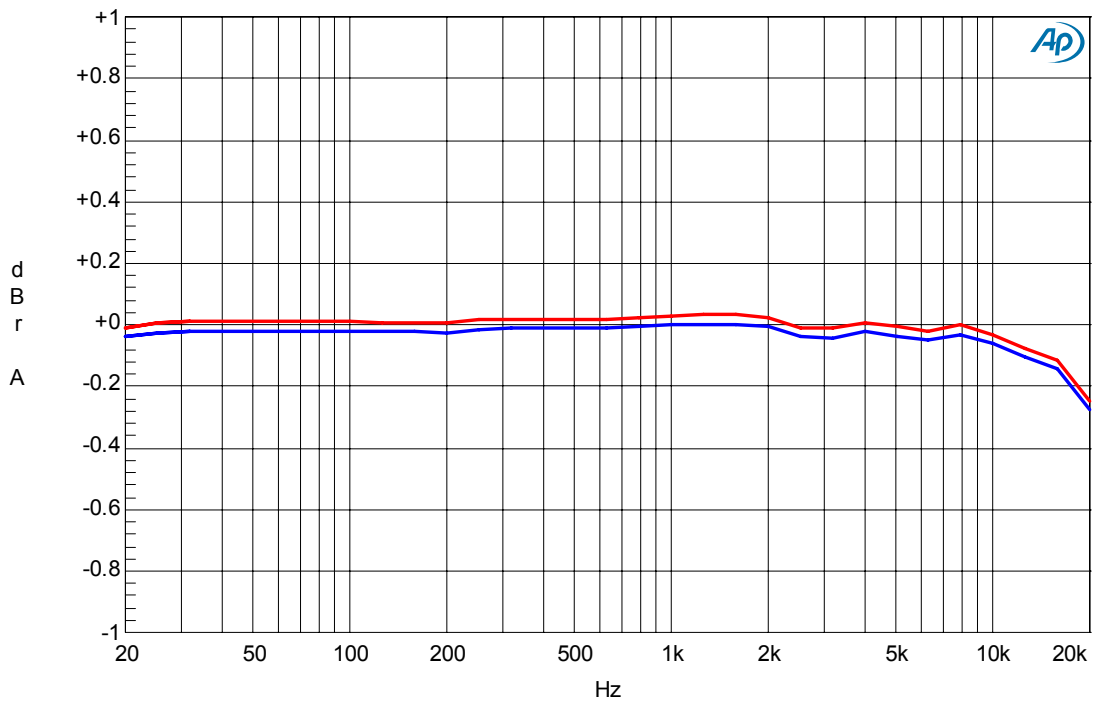
THD + N vs. Input Level (fin=1kHz)



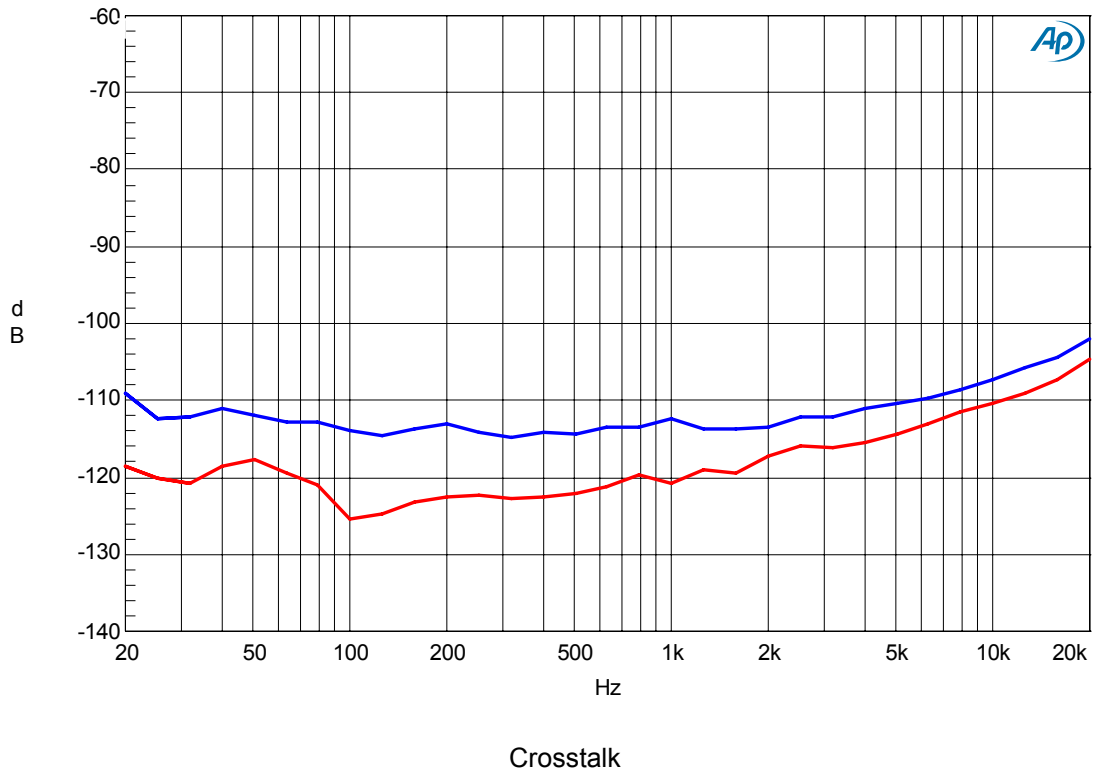
THD + N vs. Input Frequency (Input=0dBFS)



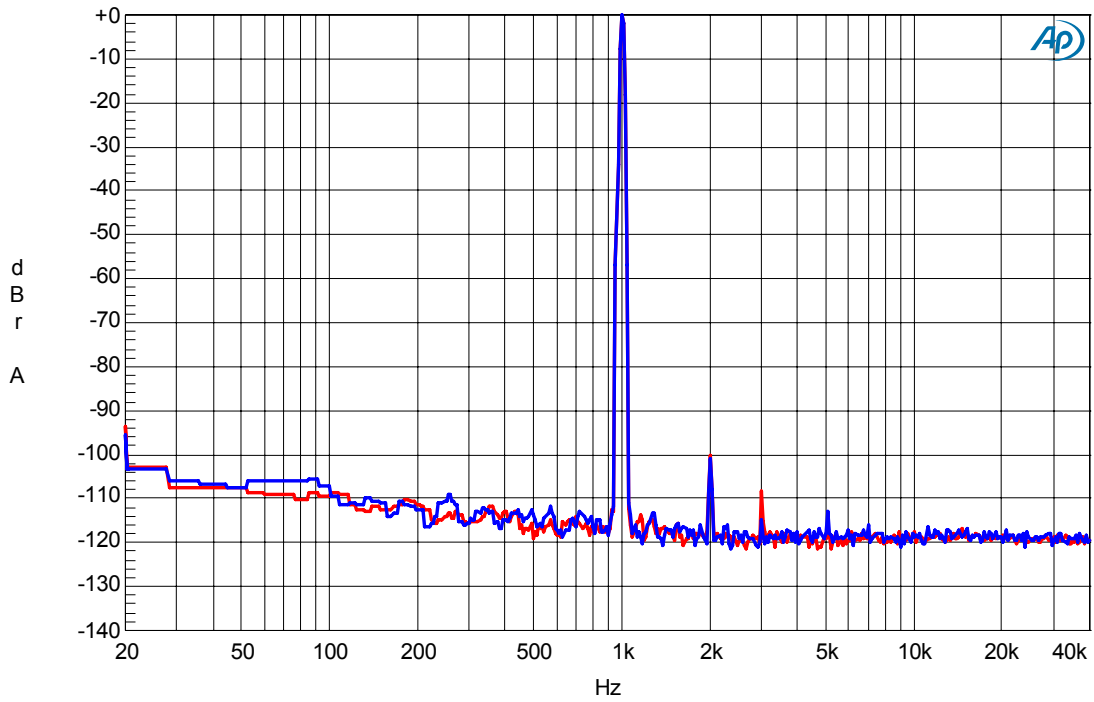
Linearity (fin=1kHz)



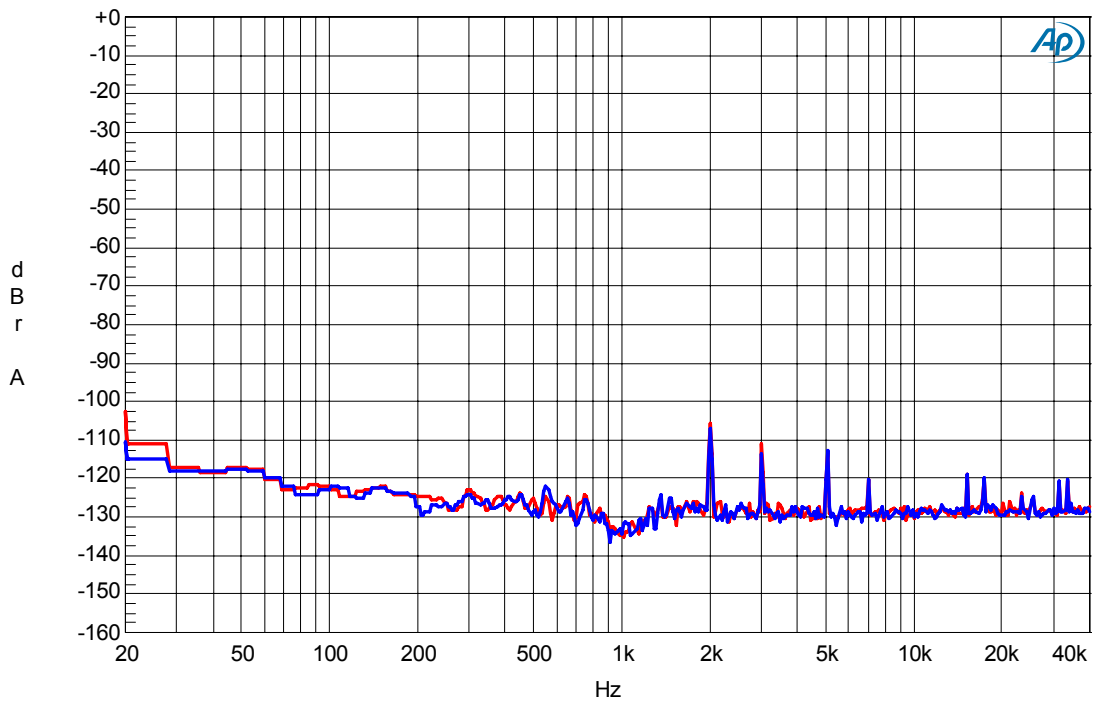
Frequency Response (Including external RC filter)



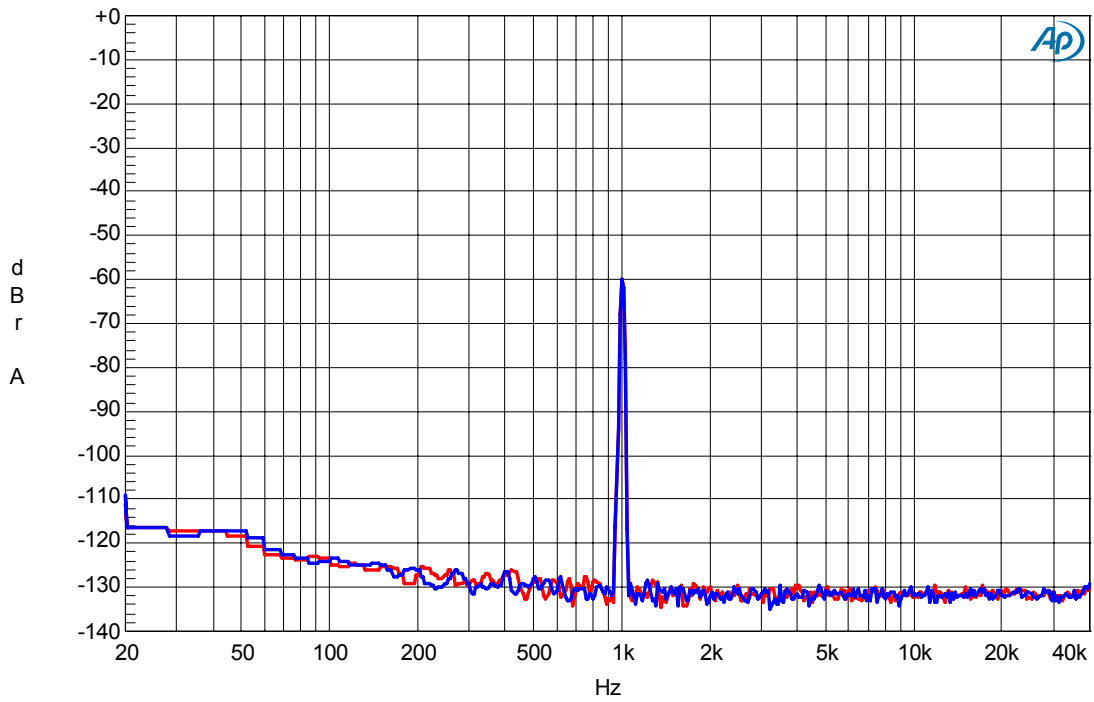
2.2 DAC (fs=96kHz)



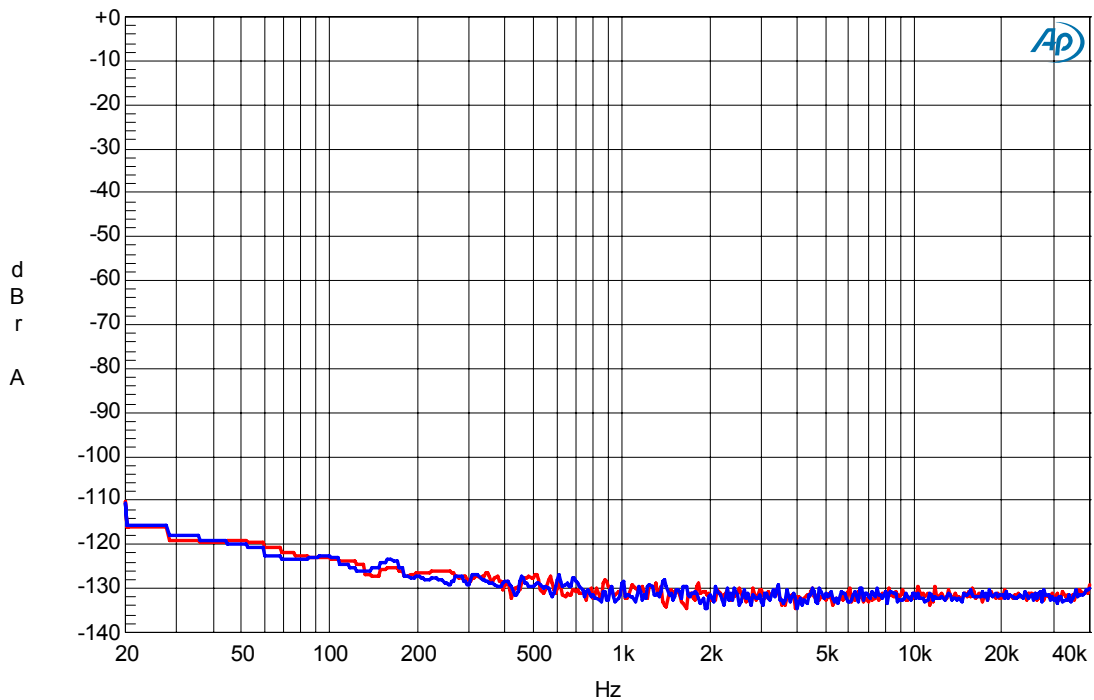
FFT (Input=0dBFS, fin=1kHz)



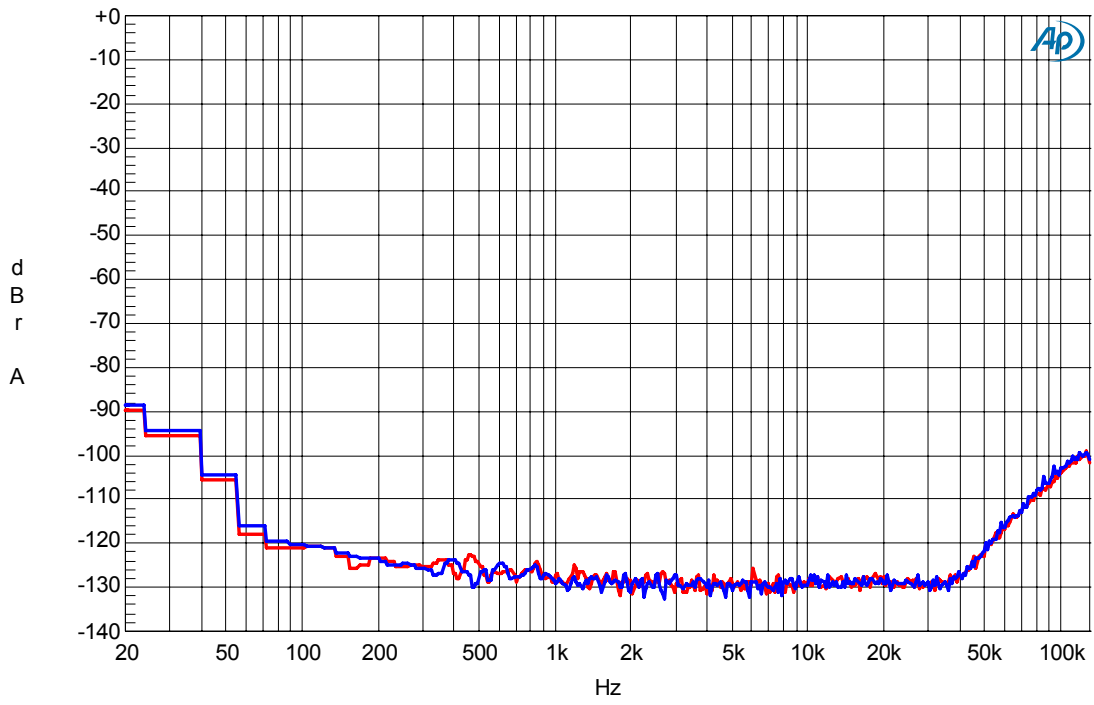
FFT (Input=0dBFS, fin=1kHz, Notch on)



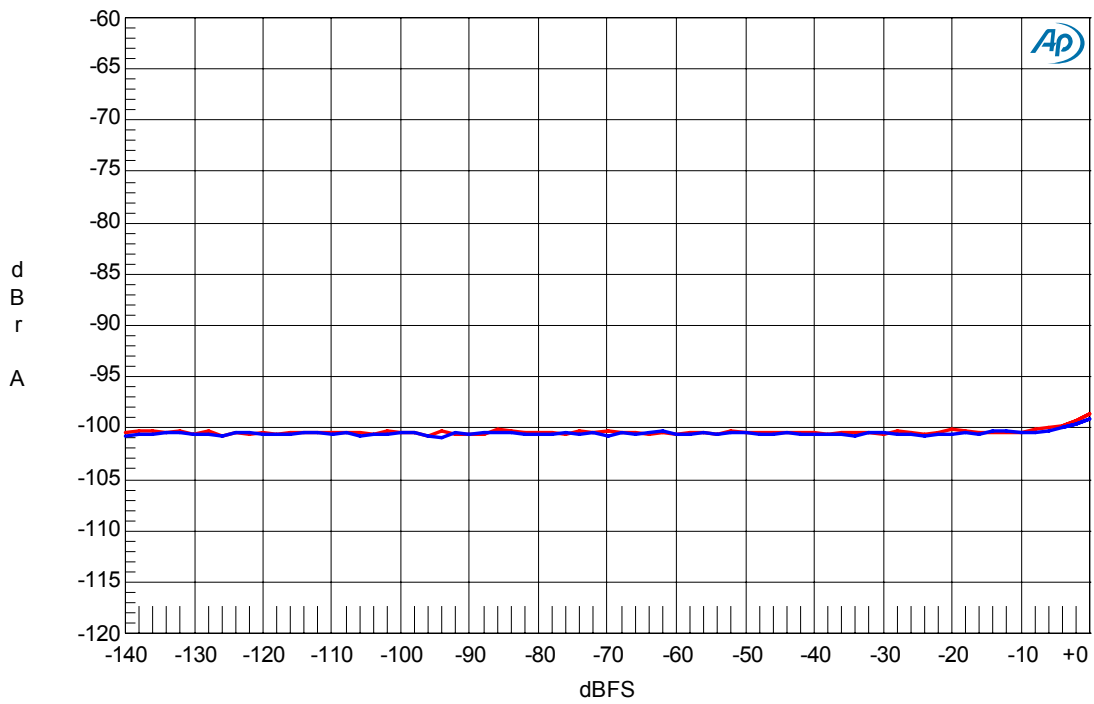
FFT (Input=-60dBFS,fin=1kHz)



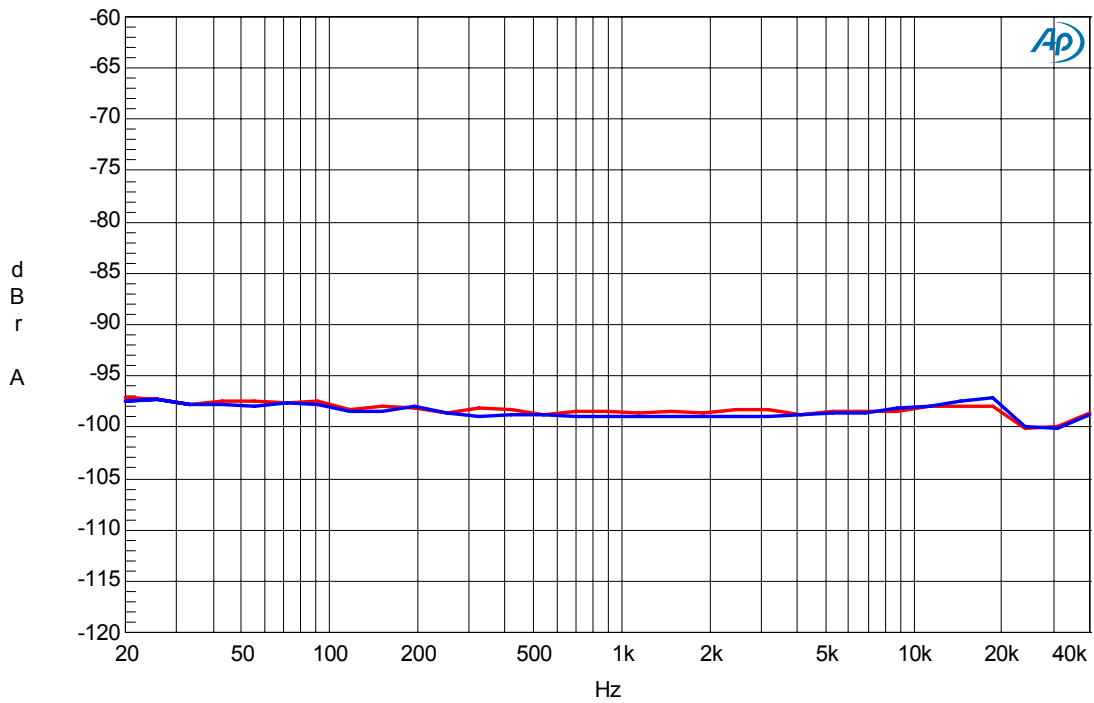
FFT (Noise floor)



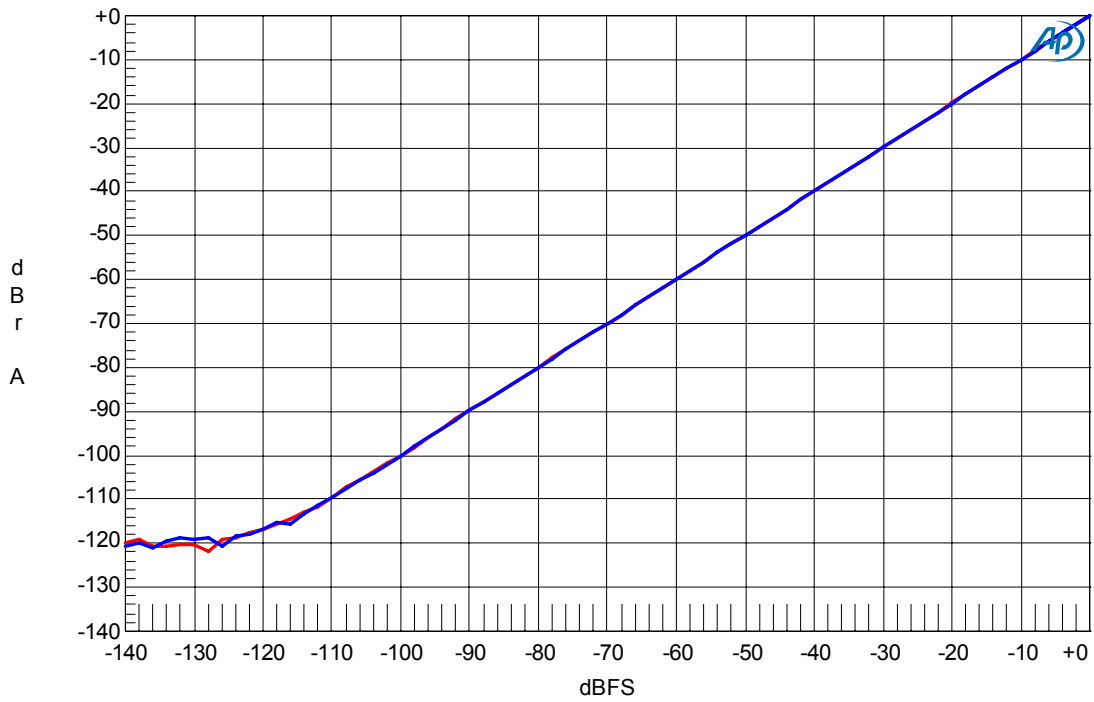
FFT (Out-of-band noise)



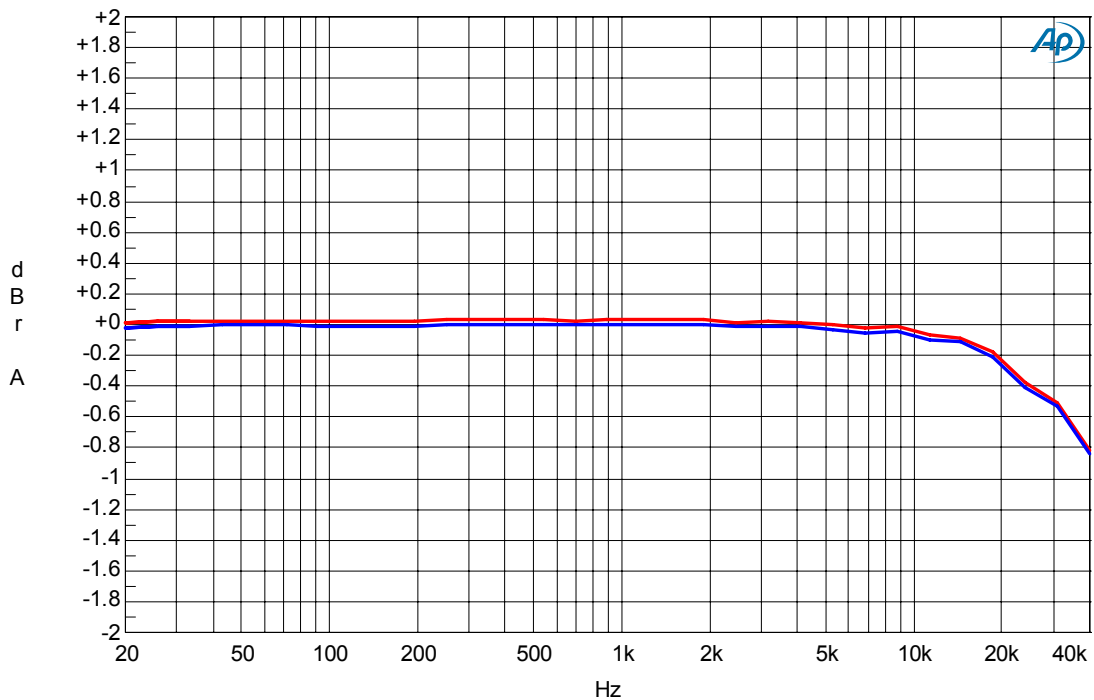
THD + N vs. Input Level (fin=1kHz)



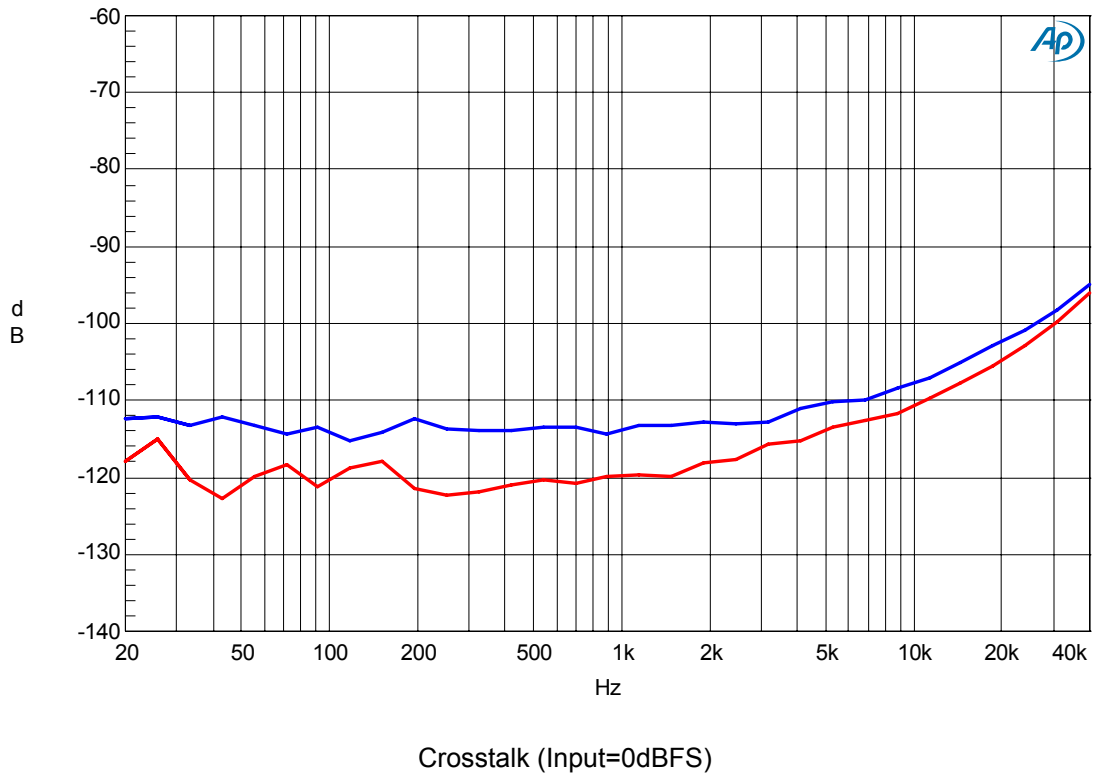
THD + N vs. Input Frequency (Input=0dBFS)



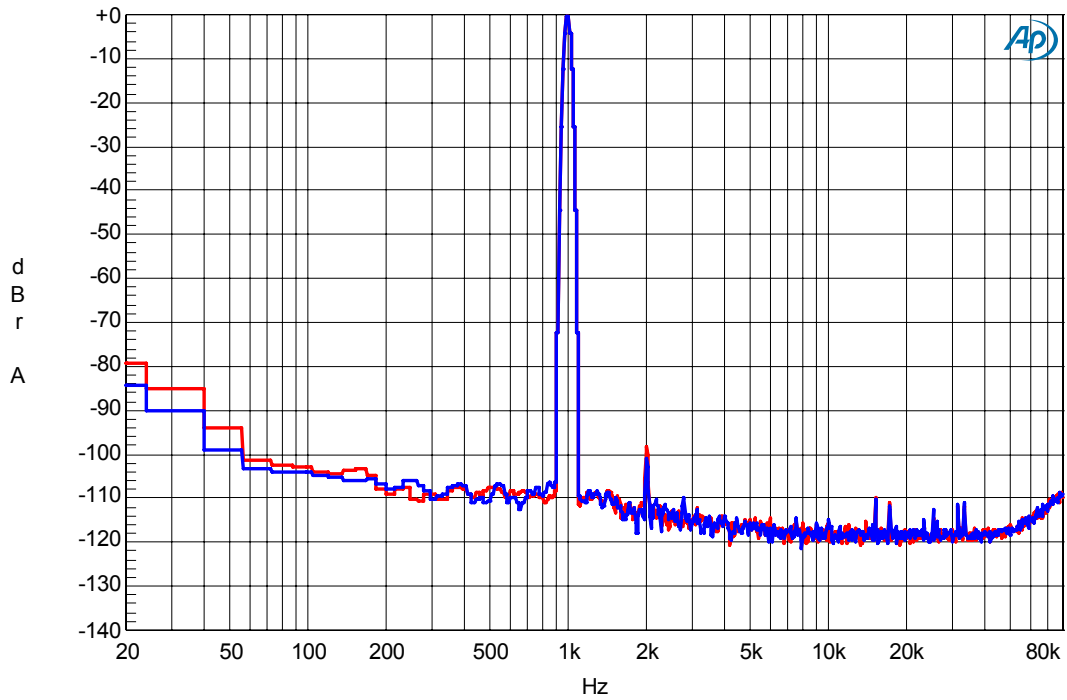
Linearity (fin=1kHz)



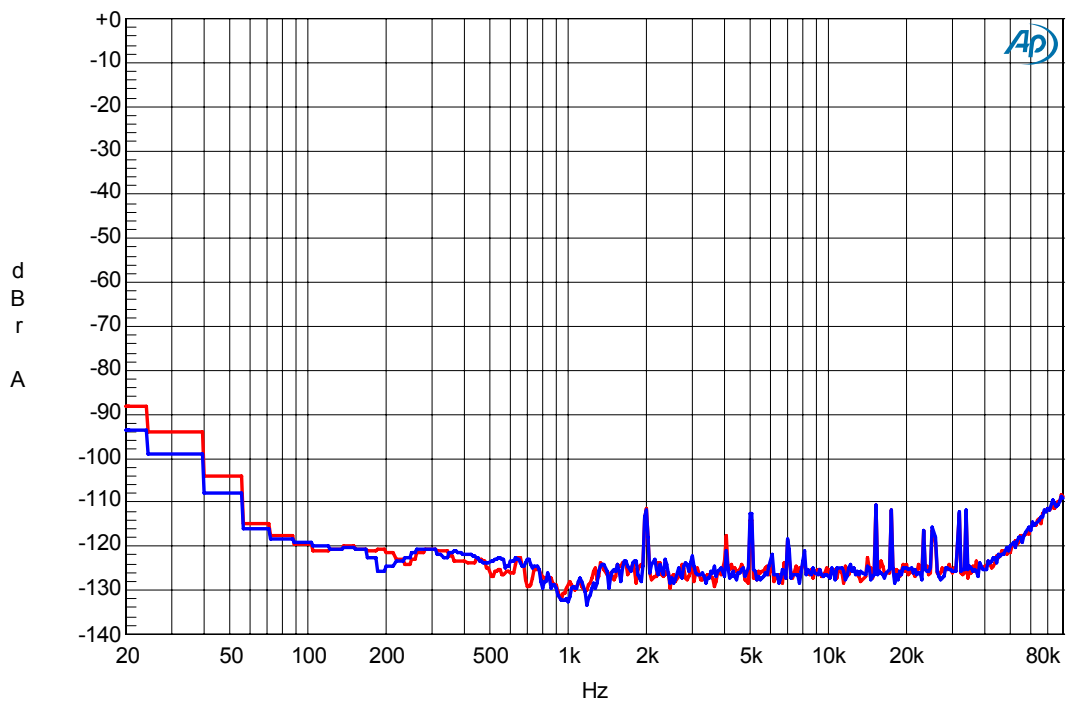
Frequency Response (Including external RC filter)



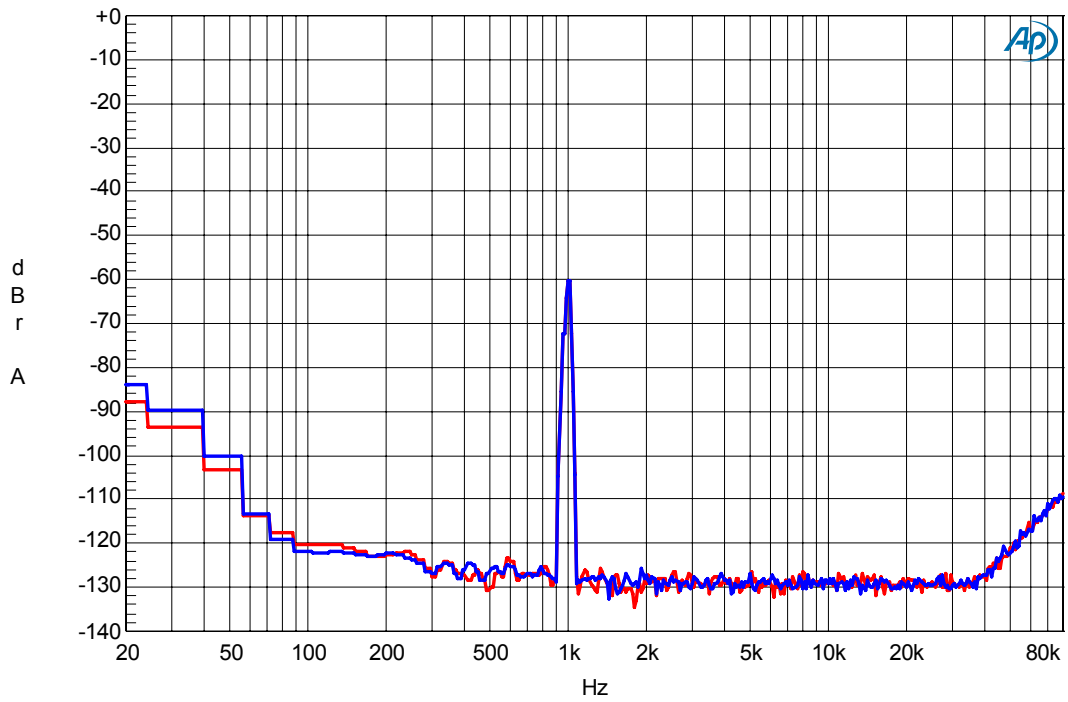
2.3 DAC (fs=192kHz)



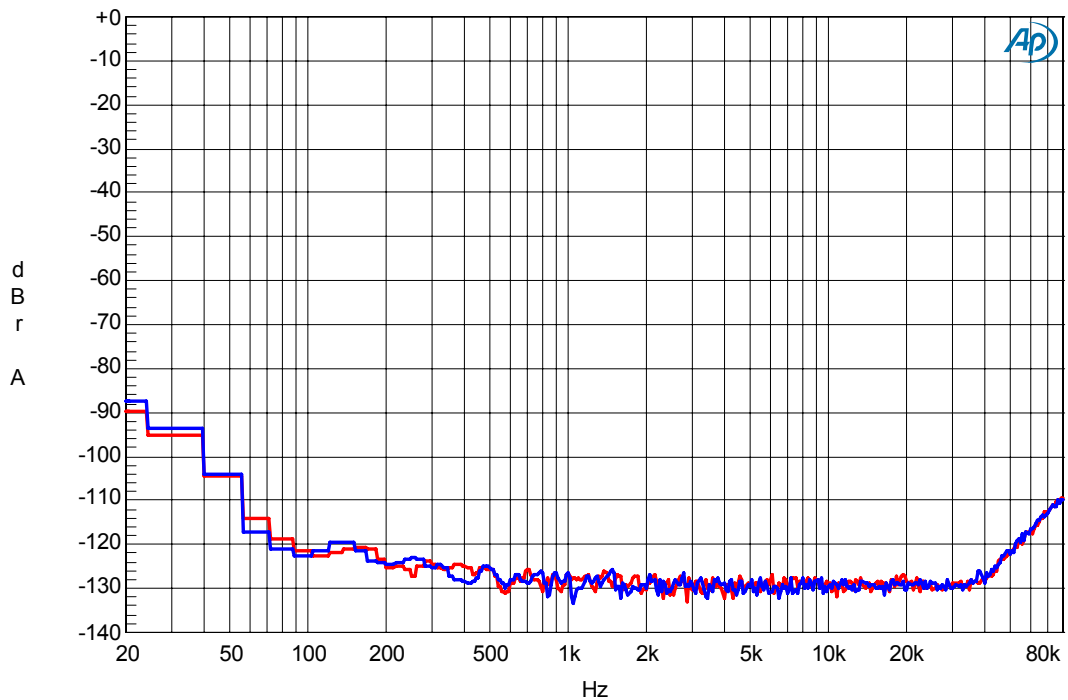
FFT (Input=0dBFS, fin=1kHz)



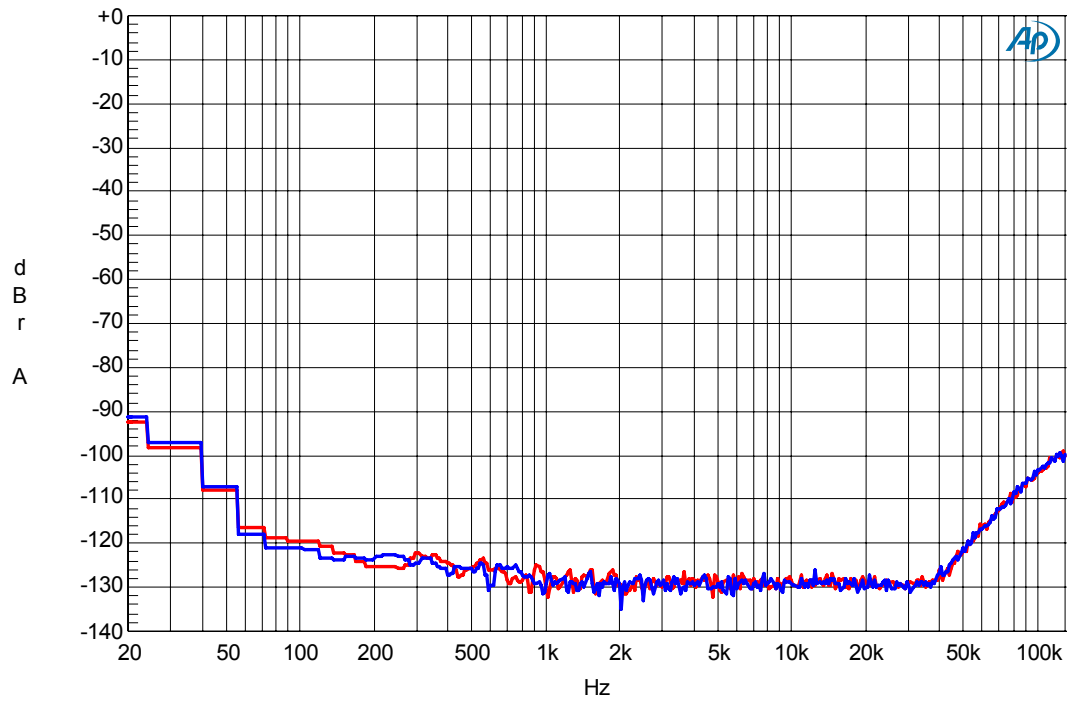
FFT (Input=0dBFS, fin=1kHz, Notch on)



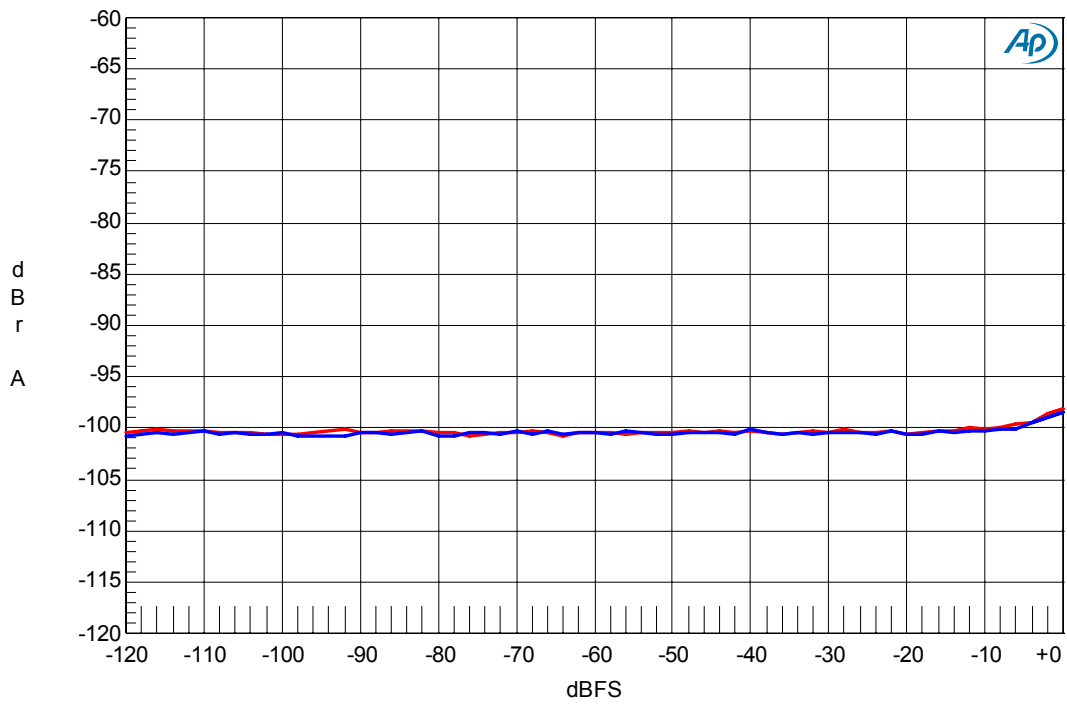
FFT (Input=-60dBFS,fin=1kHz)



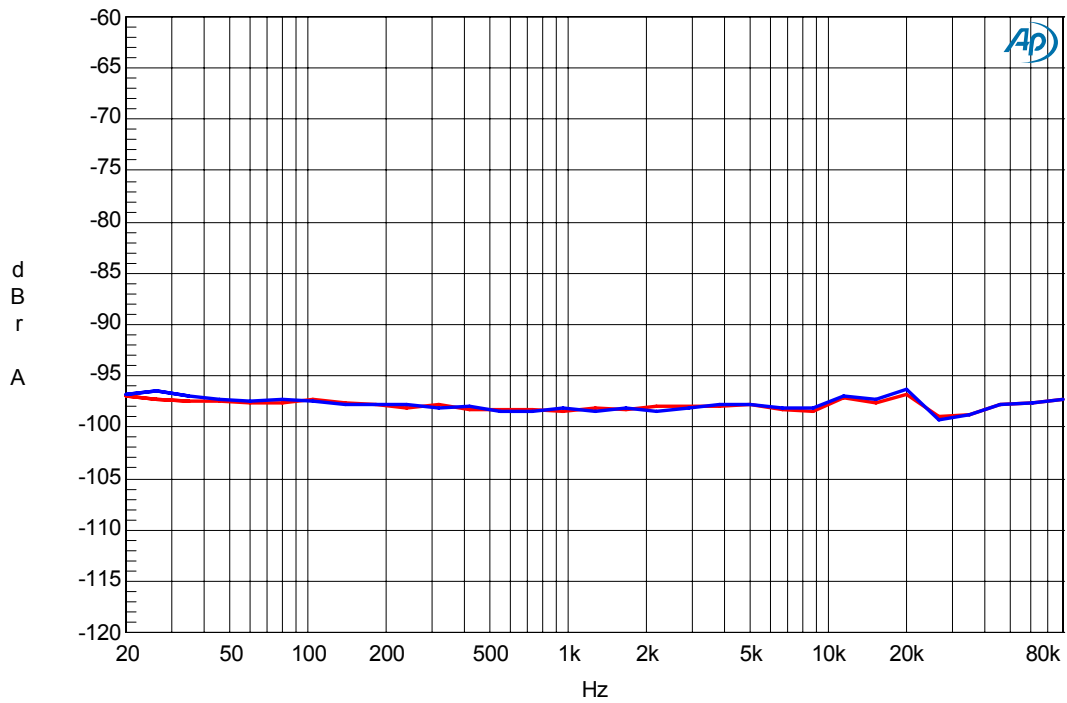
FFT (Noise floor)



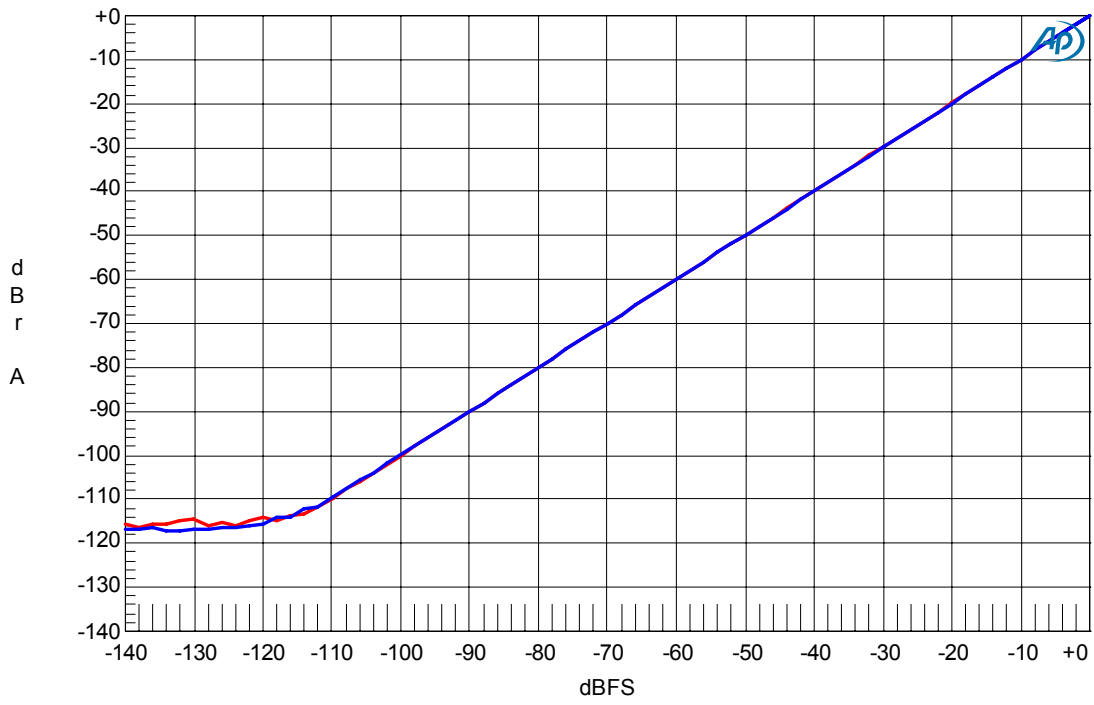
FFT (Out-of-band noise)



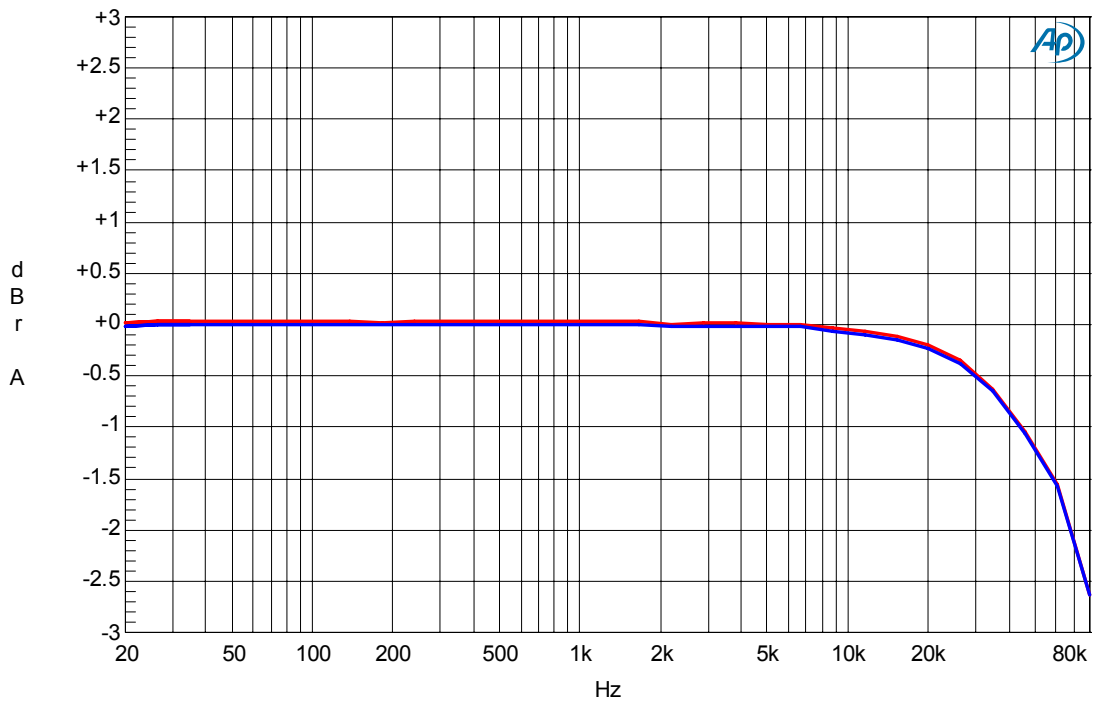
THD + N vs. Input Level (fin=1kHz)



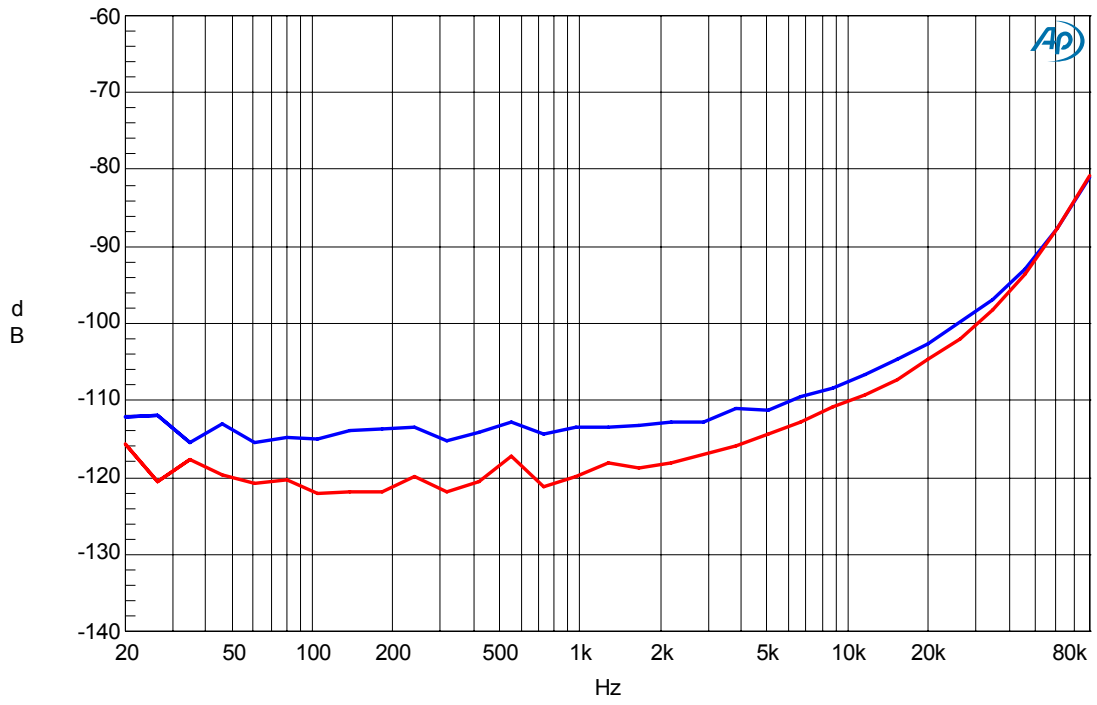
THD + N vs. Input Frequency (Input=0dBFS)



Linearity (fin=1kHz)



Frequency Response (Including external RC filter)



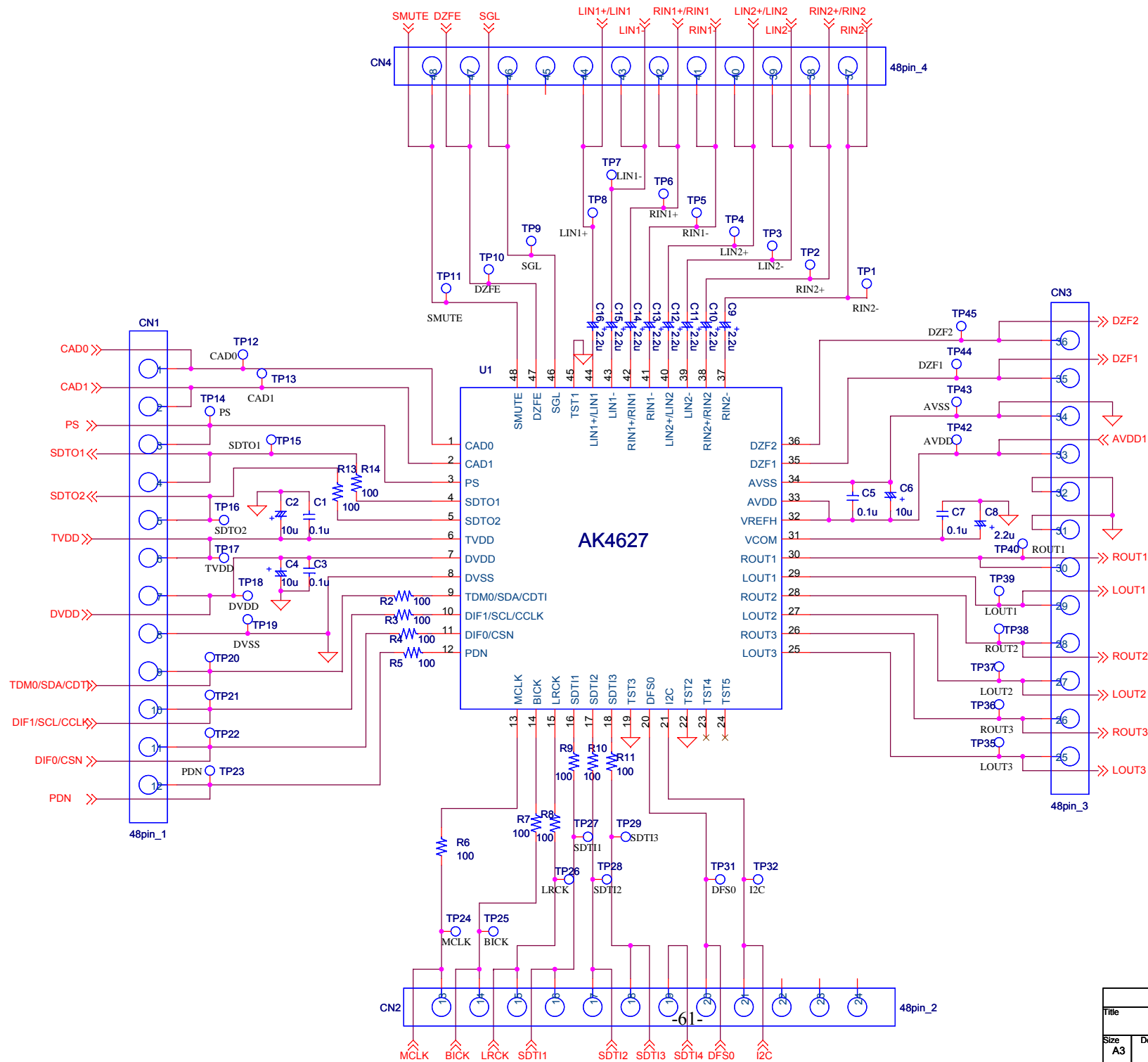
Crosstalk (Input=0dBFS)

Revision History

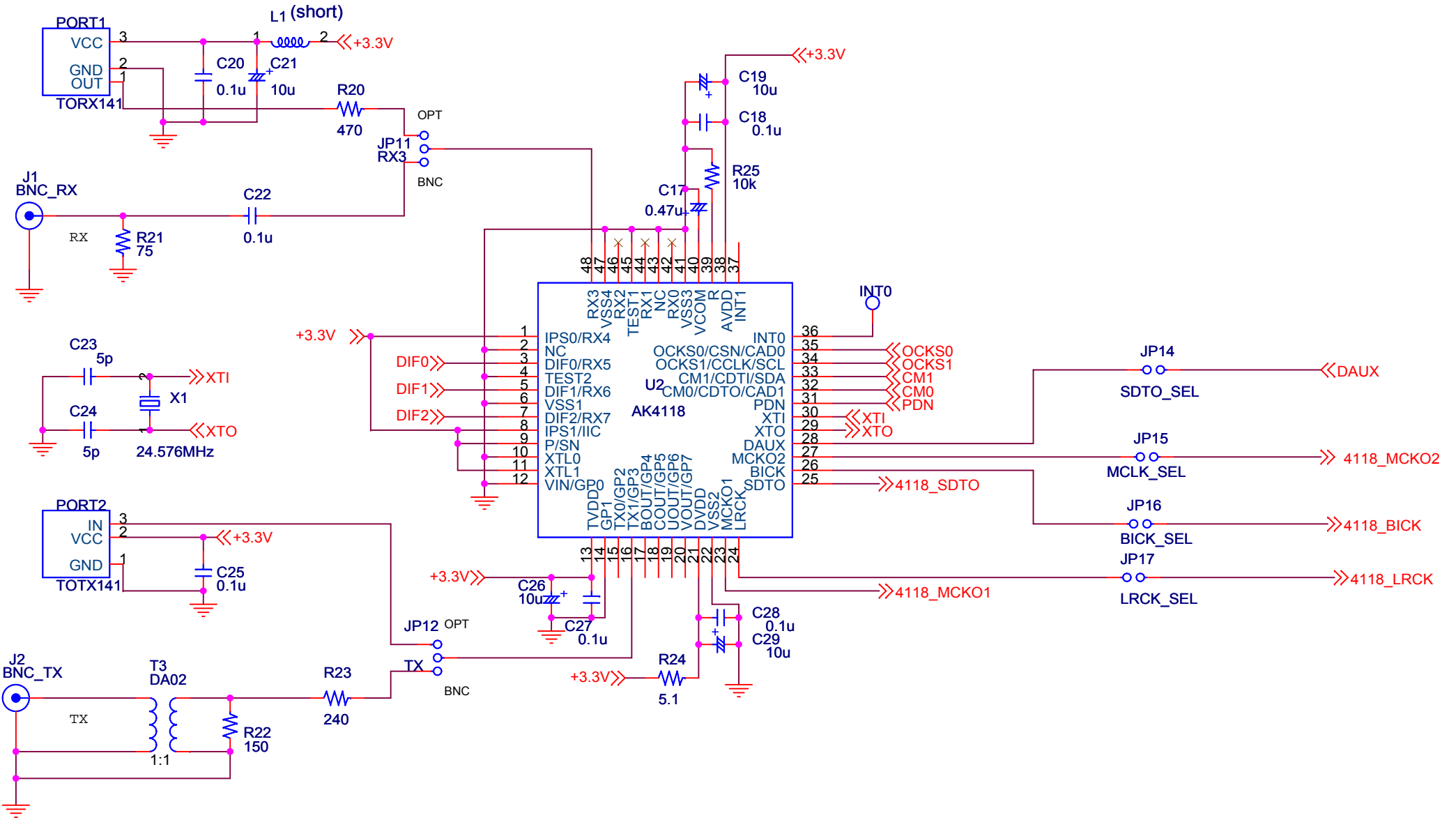
Date (YY/MM/DD)	Manual Revision	Board Revision	Reason	Contents
2010/08/09	KM102000	0	First Edition	

IMPORTANT NOTICE

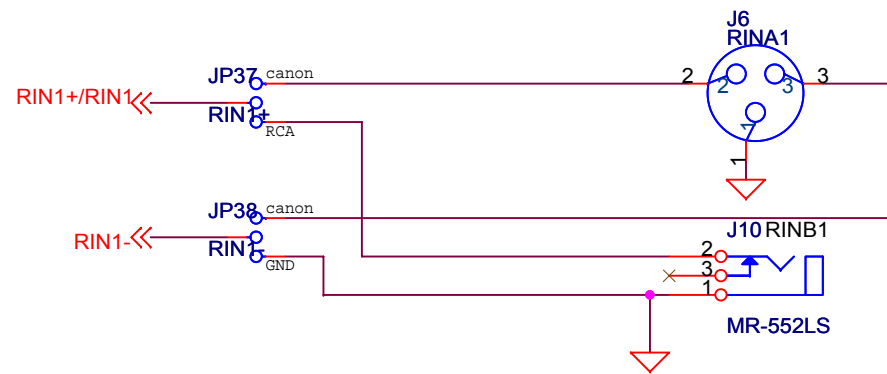
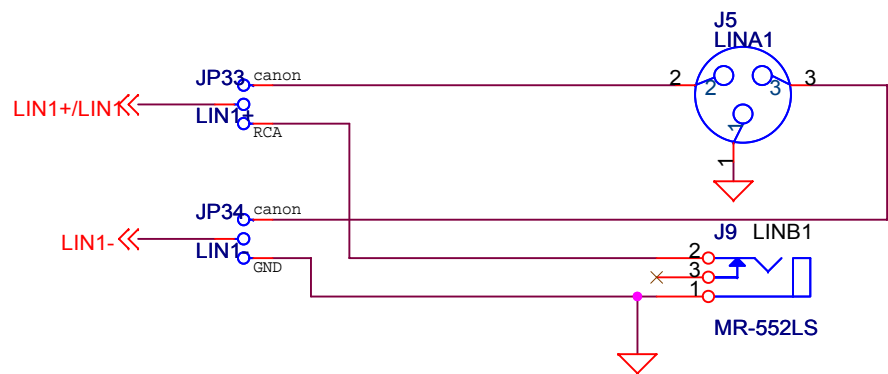
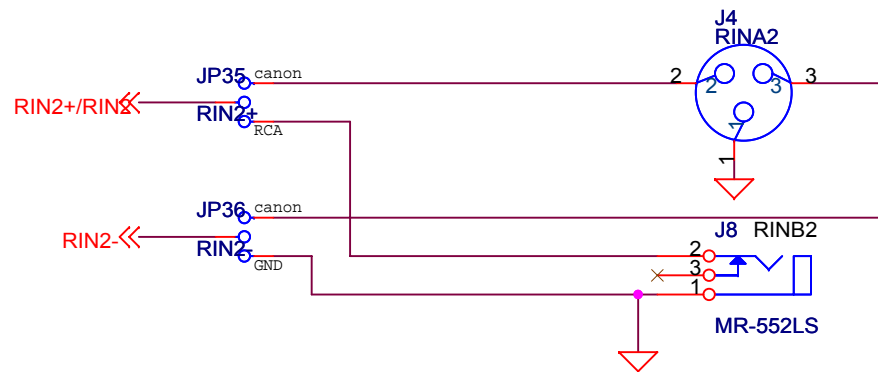
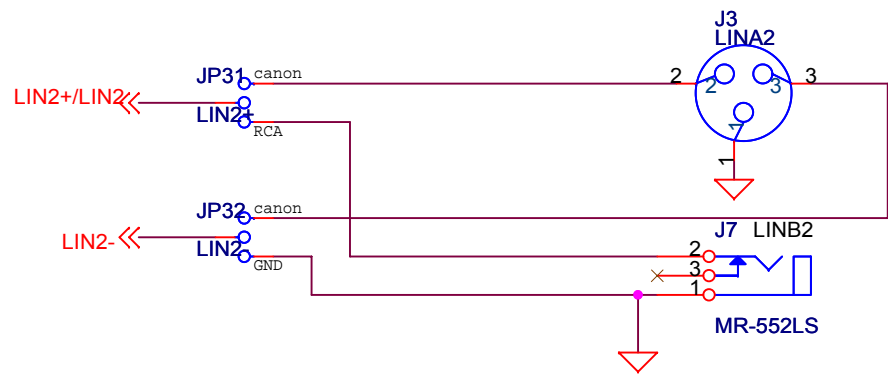
- These products and their specifications are subject to change without notice.
When you consider any use or application of these products, please make inquiries the sales office of Asahi Kasei Microdevices Corporation (AKM) or authorized distributors as to current status of the products.
- Descriptions of external circuits, application circuits, software and other related information contained in this document are provided only to illustrate the operation and application examples of the semiconductor products. You are fully responsible for the incorporation of these external circuits, application circuits, software and other related information in the design of your equipments. AKM assumes no responsibility for any losses incurred by you or third parties arising from the use of these information herein. AKM assumes no liability for infringement of any patent, intellectual property, or other rights in the application or use of such information contained herein.
- Any export of these products, or devices or systems containing them, may require an export license or other official approval under the law and regulations of the country of export pertaining to customs and tariffs, currency exchange, or strategic materials.
- AKM products are neither intended nor authorized for use as critical components_{Note1)} in any safety, life support, or other hazard related device or system_{Note2)}, and AKM assumes no responsibility for such use, except for the use approved with the express written consent by Representative Director of AKM. As used here:
 - Note1) A critical component is one whose failure to function or perform may reasonably be expected to result, whether directly or indirectly, in the loss of the safety or effectiveness of the device or system containing it, and which must therefore meet very high standards of performance and reliability.
 - Note2) A hazard related device or system is one designed or intended for life support or maintenance of safety or for applications in medicine, aerospace, nuclear energy, or other fields, in which its failure to function or perform may reasonably be expected to result in loss of life or in significant injury or damage to person or property.
- It is the responsibility of the buyer or distributor of AKM products, who distributes, disposes of, or otherwise places the product with a third party, to notify such third party in advance of the above content and conditions, and the buyer or distributor agrees to assume any and all responsibility and liability for and hold AKM harmless from any and all claims arising from the use of said product in the absence of such notification.



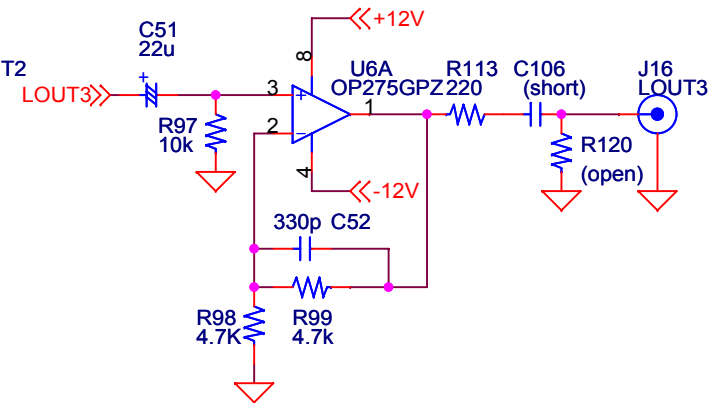
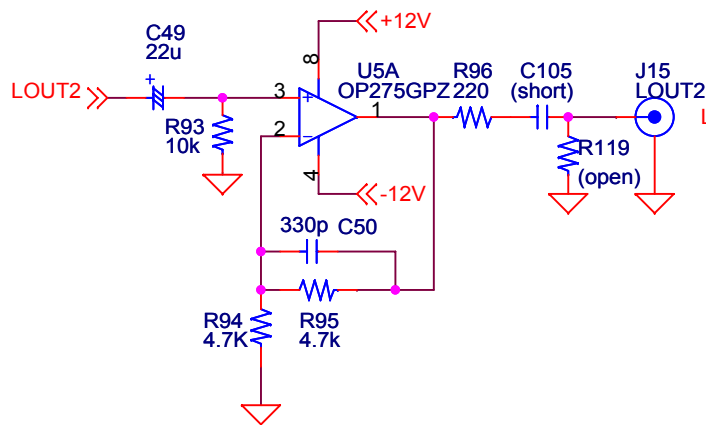
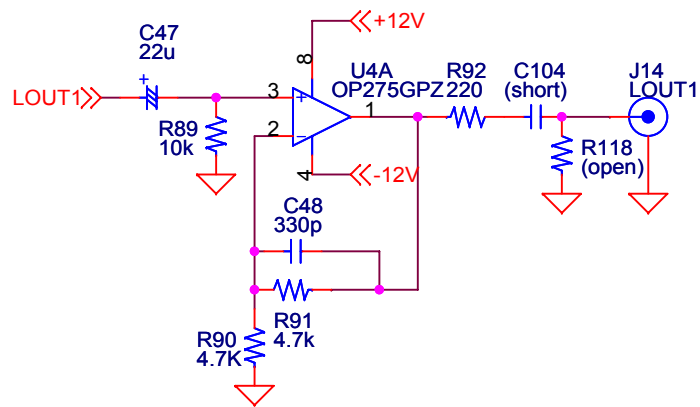
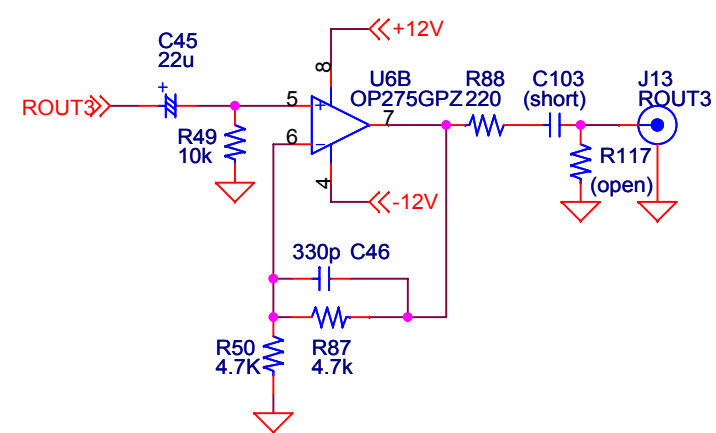
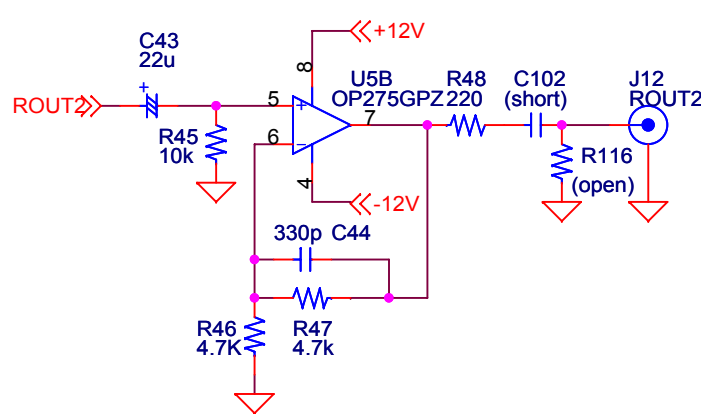
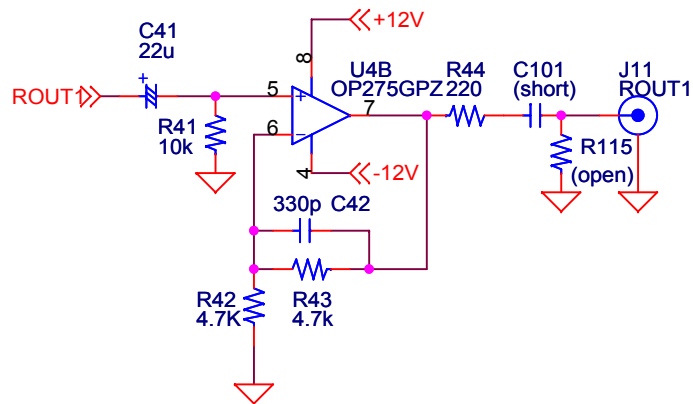
Title			AKD4627-A-MAIN
Size	Document Number	AK4627	
A3			Rev 0
Date:	Wednesday, August 04, 2010	Sheet 1	of 6



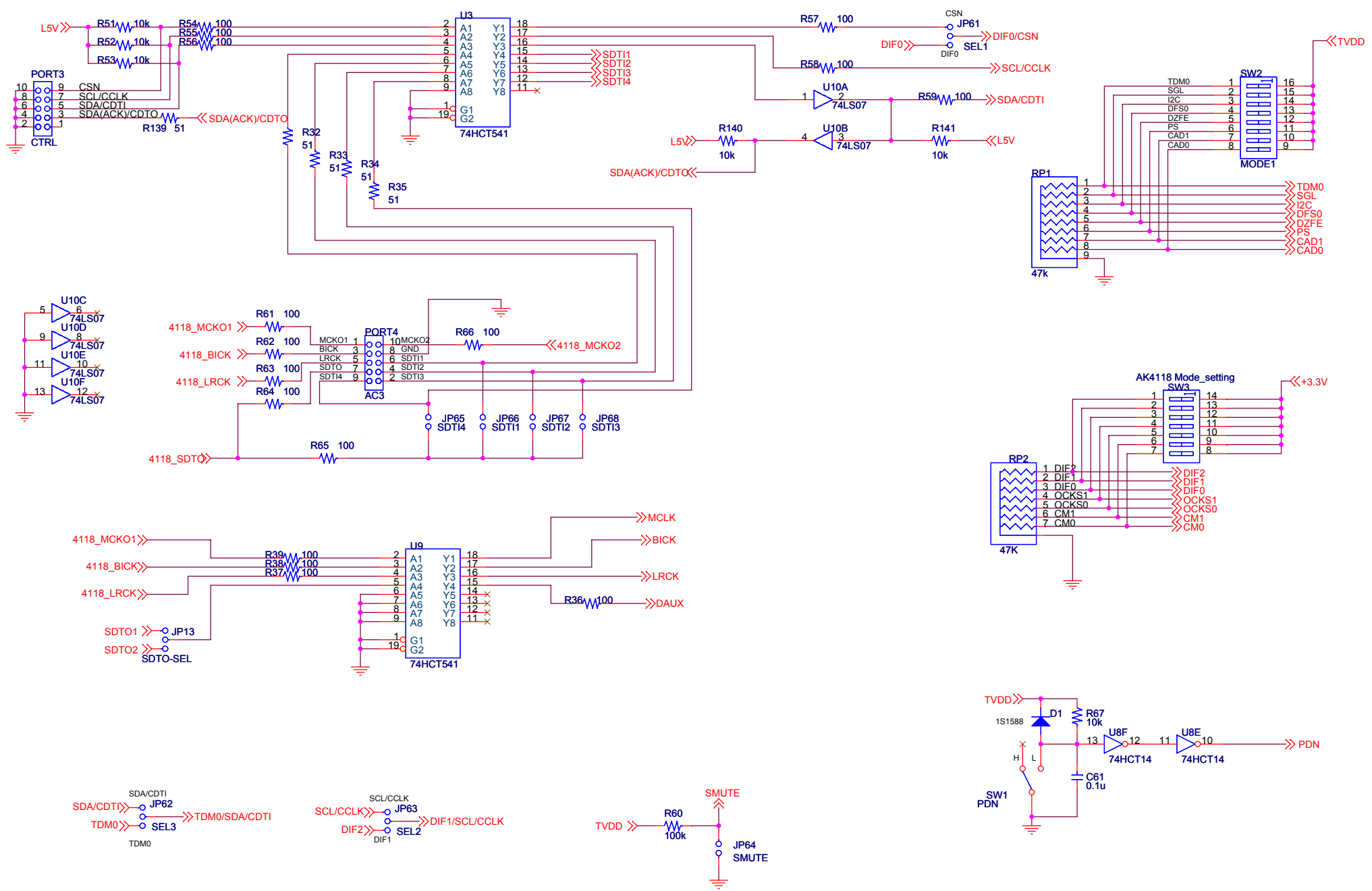
Title			AKD4627-A-Main		
Size	Document Number	AK4118			Rev
A4					0
Date:	Wednesday, August 04, 2010	Sheet	1	of	6



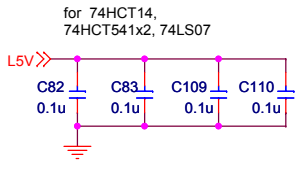
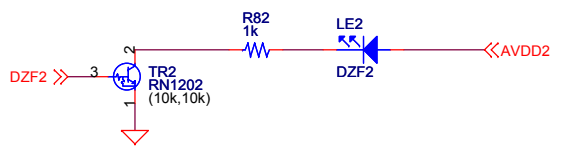
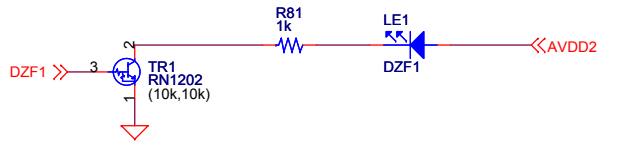
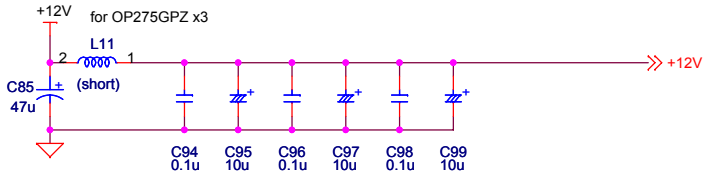
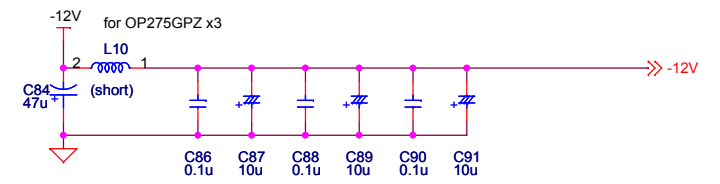
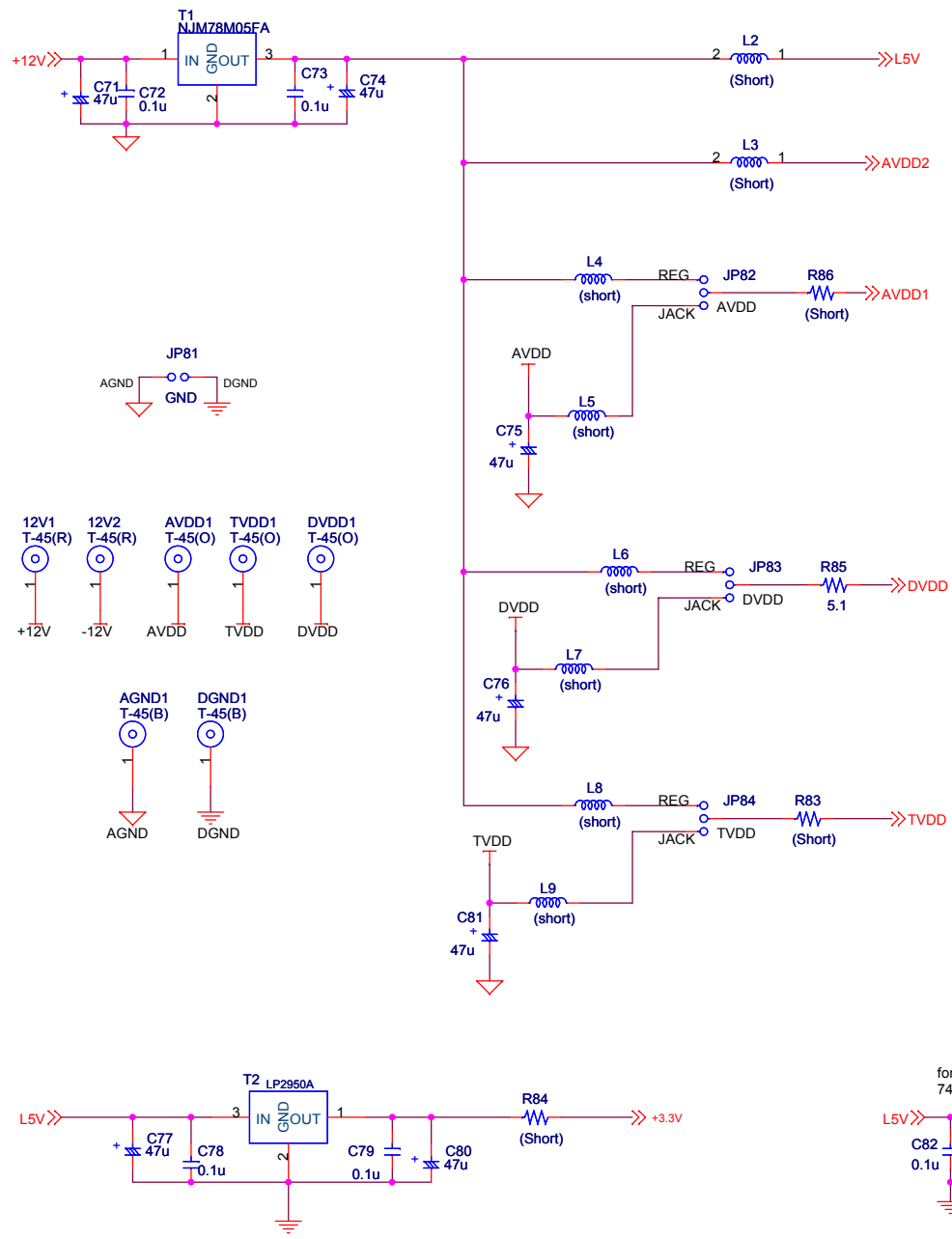
Title		
<Title> AKD4627-A-MAIN		
Size	Document Number	Rev
A4	<Doc> Analog Input	0
Date: Wednesday, August 04, 2010		Sheet 3 of 6



Title		
<Title>		AKD4627-A-MAIN
Size	Document Number	Rev
A4	<Doc>	0
Date: Wednesday, August 04, 2010		
Sheet	4	of 6



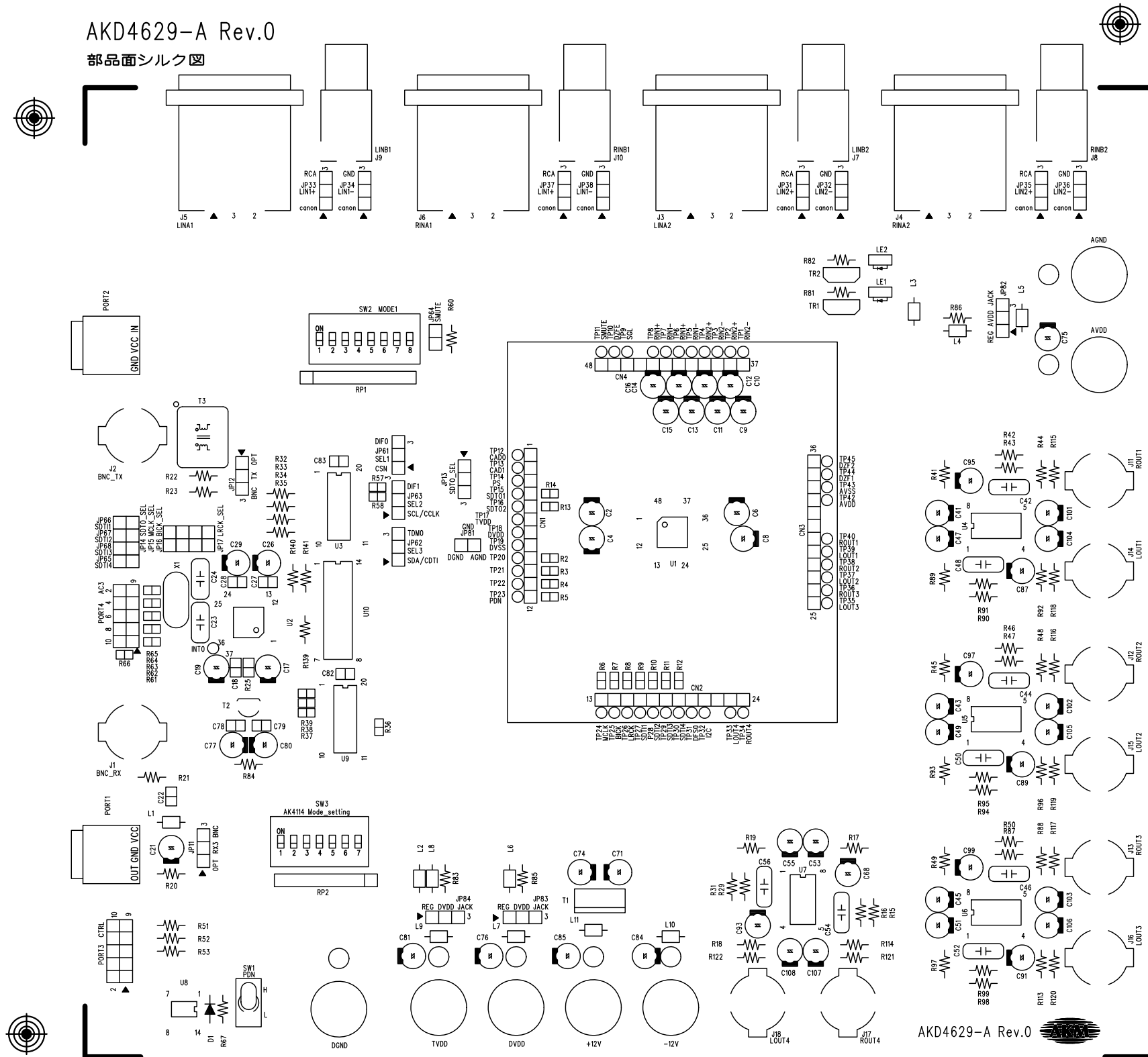
Title	<Title> AKD4627-A-MAIN		Rev
Size	Document Number	Digital I/F	0
A3	<Doc>		
Date:	Wednesday, August 04, 2010	Sheet 5 of 6	



Title	<Title> AKD4627-A-MAIN	
Size	Document Number	Rev
A3	<Doc> Power Supply	0
Date:	Wednesday, August 04, 2010 Sheet 6 of 6	

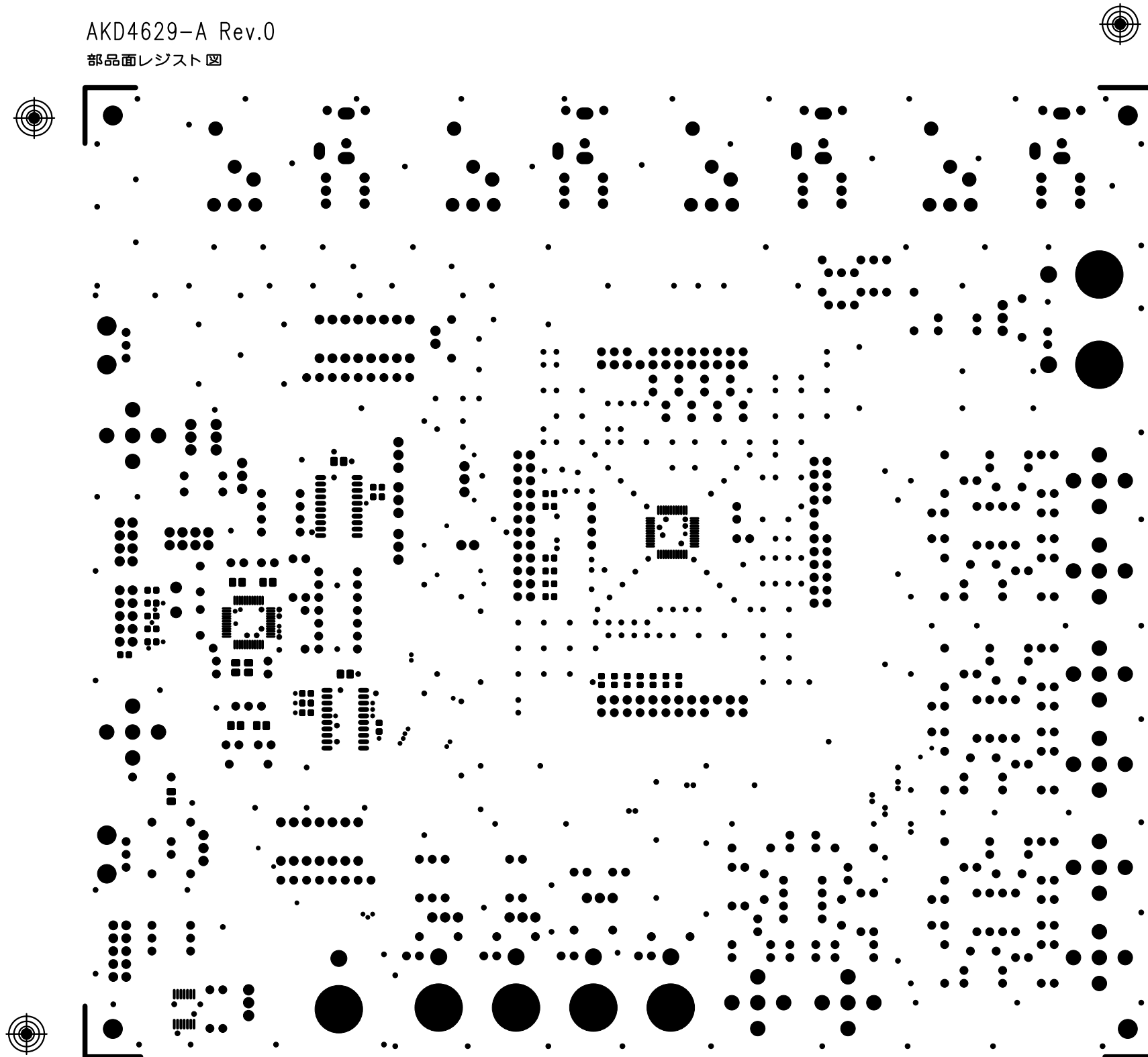
AKD4629-A Rev.0

部品面シルク図



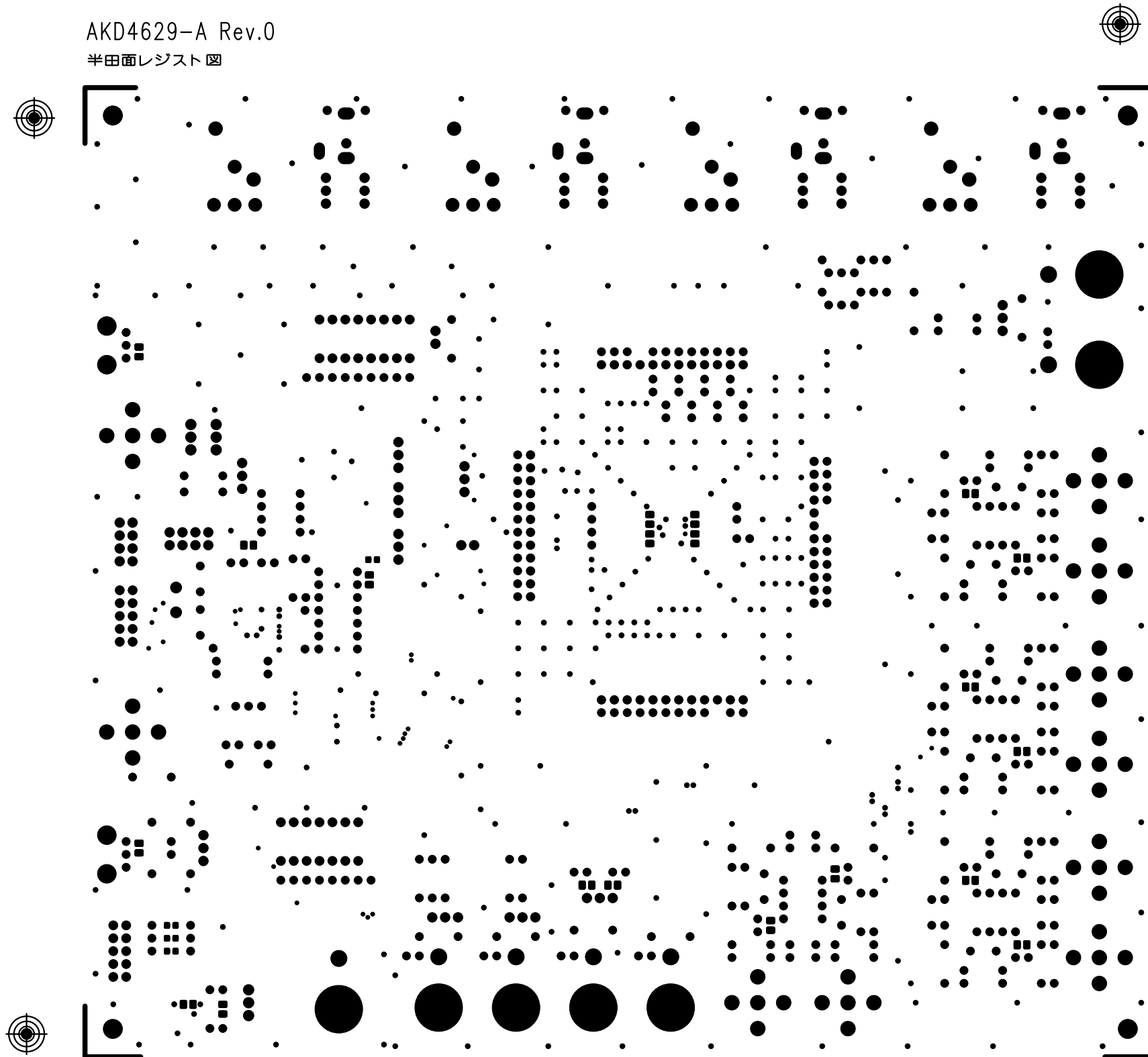
AKD4629-A Rev.0

部品面レジスト図



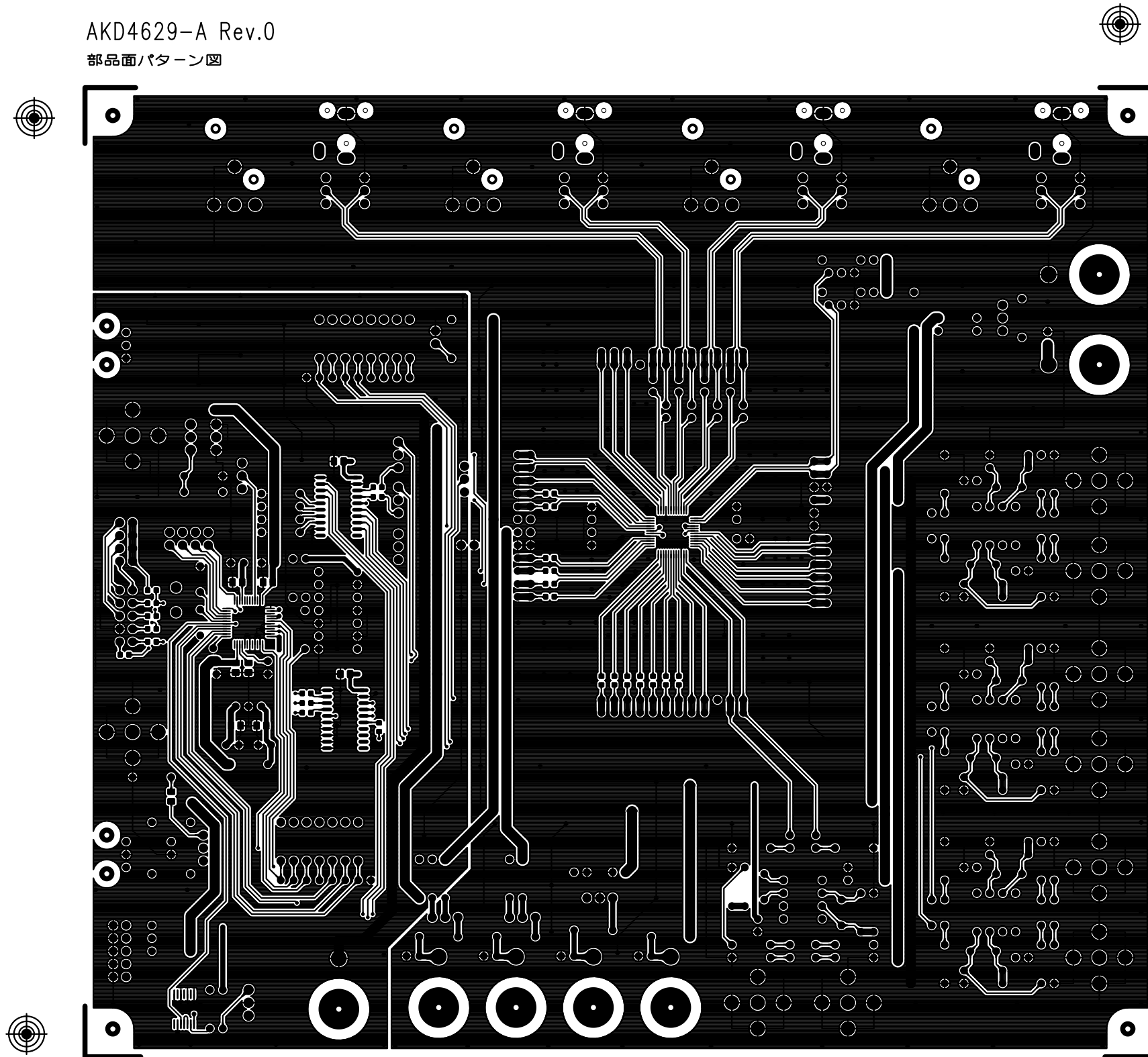
AKD4629-A Rev.0

半田面レジスト図



AKD4629-A Rev.0

部品面パターン図



AKD4629-A Rev.0

半田面パターン図

